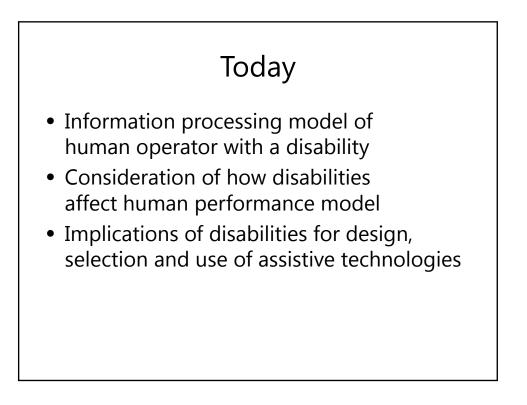
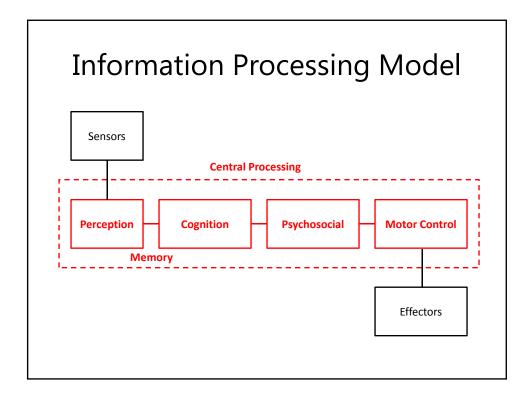
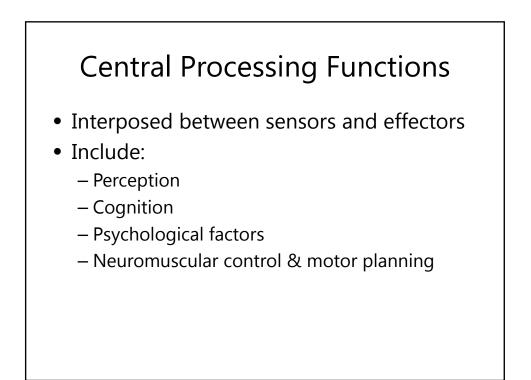
6.811 / PPAT: Principles and Practice of Assistive Technology

Today: Information Processing Model of the Human User (II) [C&H Ch. 3]

> Wednesday, 18 September 2013 Prof. Seth Teller

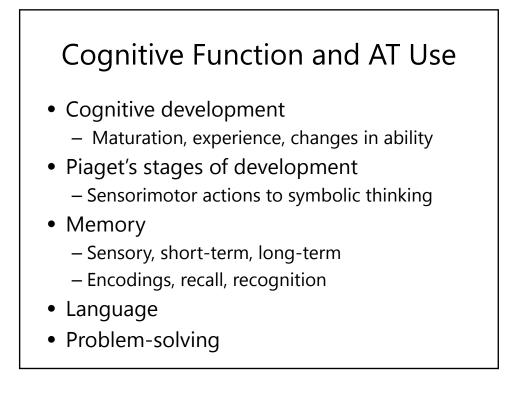






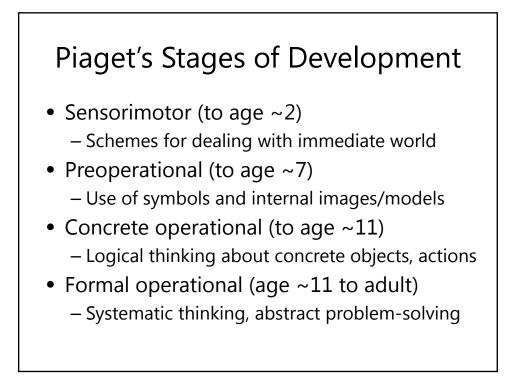
Perceptual Function and AT Use

- Addition of meaning to raw sensory data
- Thresholding
 - Output production above a minimal input level
- Figure-ground discrimination
 - Separating one portion of signal from another
- Localization
 - Placement of visual/auditory source in space
- Estimation of physical parameters
 - Length, distance, time (reaching, selection, control etc.)



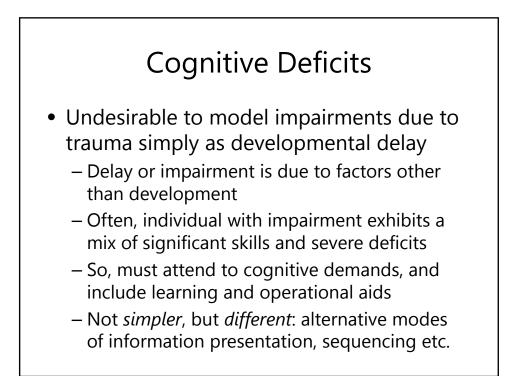
Cognitive Development

- Development is a function of both:
 - Biological maturation (growth)
 - Interaction with environment (learning)
- AT designers and providers must consider both current status, development change
- Capabilities for manipulation or other purposive motor actions, symbolic thinking, logical problem-solving



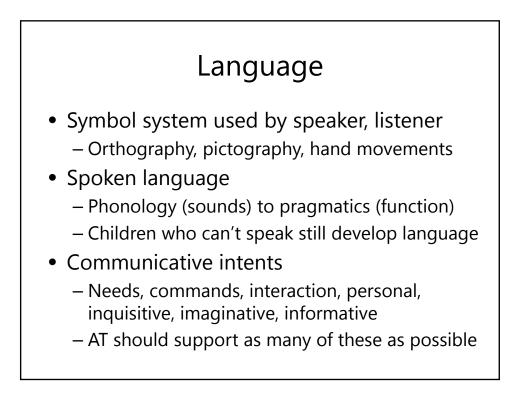
Key Concepts for ATP

- Observational learning (as young as 9 mos.)
 Imitation of observed (but unpracticed) acts
- Co-occurrences
 - Inferences about causality, contingent results
- Animism
 - Attribution of life, consciousness to objects
- Active vs. passive learning
 - E.g., driver vs. passenger of wheelchair
- Implications?



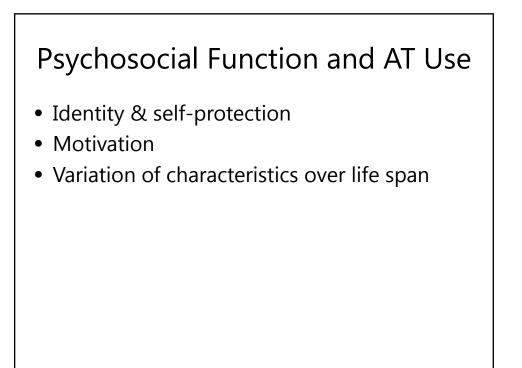
Memory

- Sensory memory
 - Storage of data after cessation of stimulus
 - Afterimages (~250 msec.), auditory echoes (~5 sec.)
- Short-term (or working) memory
 - Temporary storage (20-30 sec.) of task information
 - Maximizing STM use: grouping, patterns
- Long-term memory (information of lasting value)
 - Turning on/using AT device; goals, destinations
 - Somatosensory memory, e.g. feel of joystick
- Recall vs. recognition



Problem Solving, Decision Making

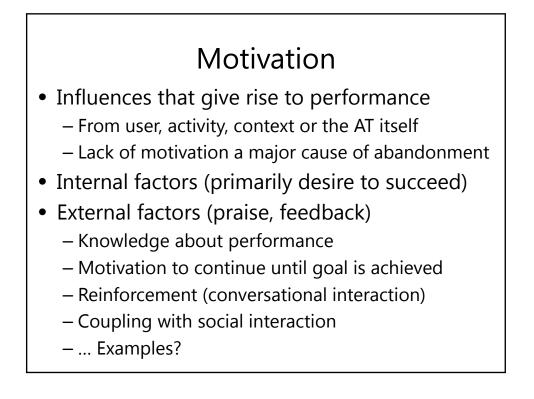
- Problem solving
 - Discovery of a solution in a new situation
- Decision making
 - Weighing and selection among alternatives
- Both PS and DM depend on memory
 Of past actions and contingent outcomes
- As novice AT user becomes expert user, dominant strategy shifts from PS to DM
- Training can facilitate both sets of skills



Identity and Self-Protection

- Identity

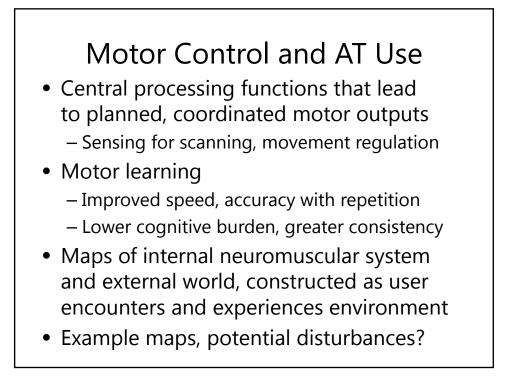
 Self-concept, locus of control, well-being
- Self-protection
 - Regulation of behavior, avoidance of harm
- Dependence on AT can cause anxiety
 - If device use causes emotional discomfort... may result in avoidance or abandonment
 - Those w/ congenital (vs. acquired) disability may be more likely to view AT as opening up opportunities (not as reminder of lost independence)



AT Use Over the Life Span

- Childhood to early teenage years
 - Eager to explore, interested in experimenting
- Young to middle-aged adult

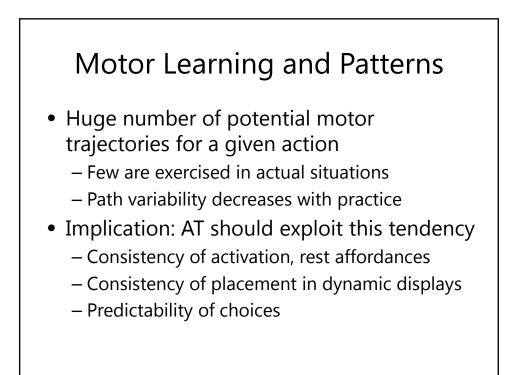
 Engaged in job pursuits, want to succeed
- Middle-aged adults
 - May find technology awkward, threatening
 - Prefer to learn and practice in private
- Older adults
 - Little exposure to technology; may be fearful





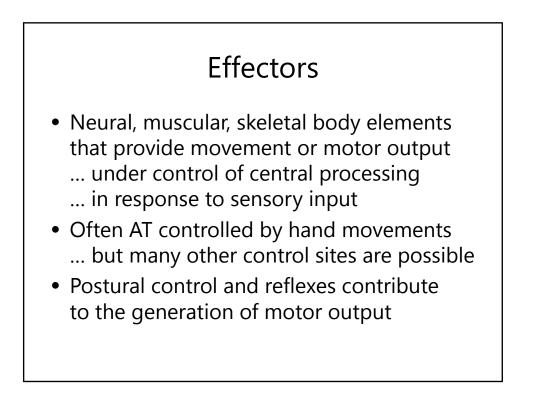
- Requires several sensorimotor tasks
 - Scanning (device affordances, locations, objects)
 - Desired element must be chosen
 - Element must be activated or manipulated
- Speed generally subject to Fitt's Law (1954)
 - Time required to move to a target decreases for closer or larger targets, and increases for more distant or smaller targets
 - Holds for wide variety of body parts, controls
- Accuracy decreases with increasing speed

 May not hold for expert users



Relationship to Stimuli

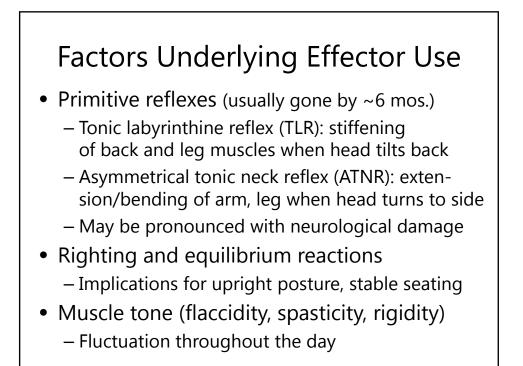
- Motor performance is improved when correspondence between stimulus (e.g. AT system item or prompt) and user response is high
 - E.g., appearance of icons in file system GUI
- This is simply good interface design
- For AT systems, spatial mapping of stimulus to response is often best
 - Fastest response times, fewest errors



Effector Function and AT Use

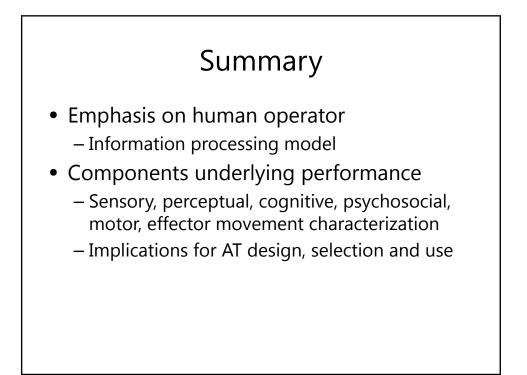
- Motor outputs for stabilization, control

 Large muscles of trunk and pelvis
- Control effectors for manipulation
 - Hand or fingers, shoulders, arm, head, eyes, eyelids, eyebrows, mouth, tongue, leg, foot
 - Respiration (flow of air, sip, puff)
 - Phonation (sound production, whistling, speech)
- Oculomotor control (via PCA, or AT device)
 Approach, grasp, manipulation, release



Characterizing Effector Movement

- Resolution
 - Degree of reliable fine control of objects
- Range
 - Maximal extent of movement possible
- Strength
 - Minimal force required to activate an interface
- Endurance
 - Ability to sustain a force, and repeat over time
 - Performance may decrease until total fatigue



Coming Up

- Today (Wednesday) in lab:
 Voiceover / Screenreaders / Optacon
- Next Monday's lecture:
 - Rob Miller, User-Centered Design
- Next Monday's lab:
 - Contextual inquiry
 - Client matching