

6.896  
2/18/04  
L5.1

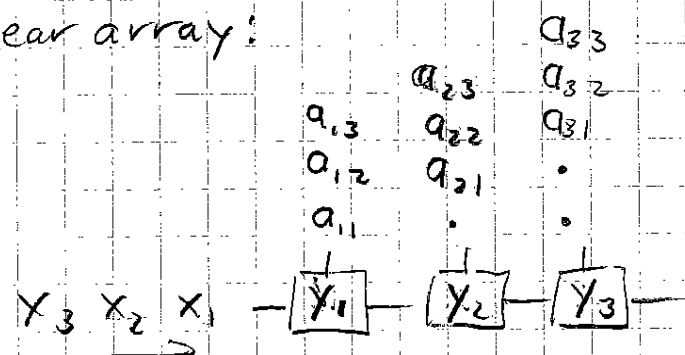
# Matrix computations

- dense matrices
- mesh networks (1D & 2D)
- word model

## Matrix-vector mult.

$N \times N$  matrix  $A = (a_{ij})$   
 $N$ -vector  $x = (x_j)$   
 Compute  $N$ -vector  $y = (y_i)$ , where  $y_i = \sum_{j=1}^N a_{ij} x_j$

Linear array:

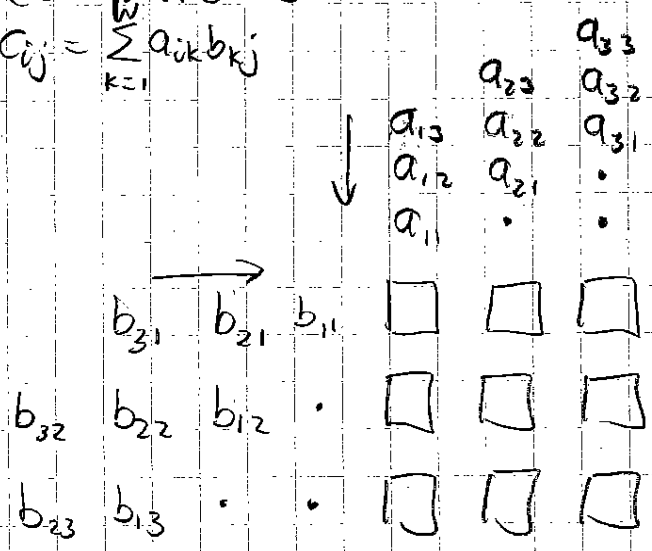


$\Theta(N)$  time ( $3N$  steps)  
 $\Theta(N)$  HW

## Matrix mult.

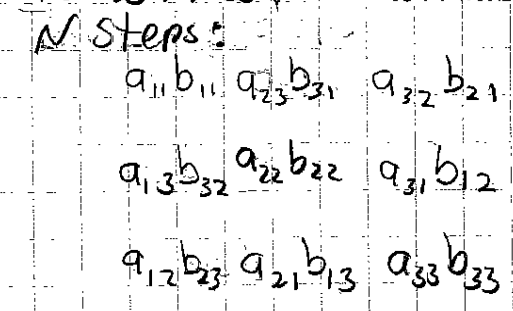
$N \times N$  matrices.  
 Compute  $C = AB$

$$C_{ij} = \sum_{k=1}^N a_{ik} b_{kj}$$



$\Theta(N)$  time ( $3N$  steps)  
 $\Theta(N^2)$  HW

Torus: mesh + "end around"



Simulating torus on mesh:



Each step of torus simulated by 2 mesh steps.

Gaussian elimination

$Ax = b$ , solve for  $x$  (A symmetric, positive definite or irreducible diag dominant  $\Rightarrow$  pivot on diagonal)

$$\begin{pmatrix} 2 & -3 & 1 \\ 1 & -1 & -2 \\ 3 & 1 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 7 \\ -2 \\ 0 \end{pmatrix}$$

Tabular method:

$$\begin{array}{ccc|c} 2 & -3 & 1 & 7 \\ 1 & -1 & -2 & -2 \\ 3 & 1 & -1 & 0 \end{array} \Rightarrow \begin{array}{ccc|c} \textcircled{1} & -3/2 & 1/2 & 7/2 \\ 1 & -1 & -2 & -2 \\ 3 & 1 & -1 & 0 \end{array} \Rightarrow \begin{array}{ccc|c} 1 & -3/2 & 1/2 & 7/2 \\ 0 & 1/2 & -5/2 & -11/2 \\ 0 & 1/2 & -5/2 & -21/2 \end{array}$$

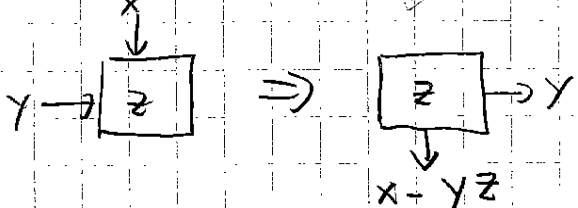
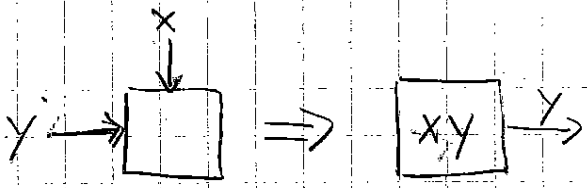
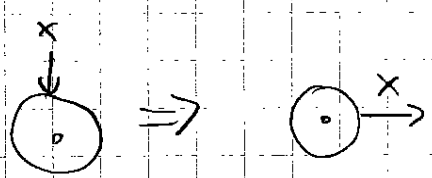
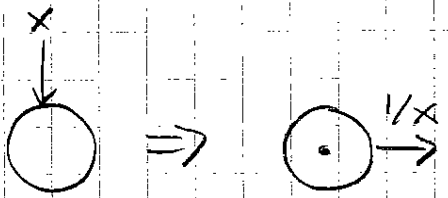
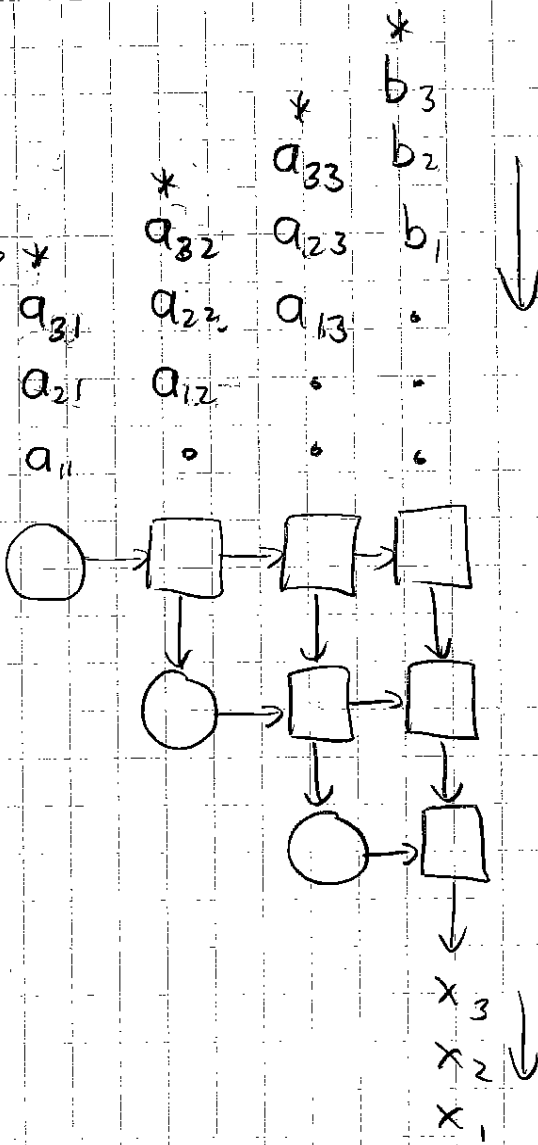
$$\Rightarrow \begin{array}{ccc|c} 1 & -3/2 & 1/2 & 7/2 \\ 0 & \textcircled{1} & -5 & -11 \\ 0 & 1/2 & -5/2 & -21/2 \end{array} \Rightarrow \begin{array}{ccc|c} 1 & 0 & -7 & -13 \\ 0 & 1 & -5 & -11 \\ 0 & 0 & 25 & 50 \end{array} \Rightarrow \begin{array}{ccc|c} 1 & 0 & -7 & -13 \\ 0 & 1 & -5 & -11 \\ 0 & 0 & \textcircled{1} & 2 \end{array}$$

$$\Rightarrow \begin{array}{ccc|c} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 2 \end{array} \quad x = \begin{pmatrix} -1 \\ -1 \\ 2 \end{pmatrix}$$

$$\boxed{a_{ij}^{(k)} = a_{ij}^{(k-1)} - \frac{a_{ik}^{(k-1)} a_{kj}^{(k-1)}}{a_{kk}^{(k-1)}}$$

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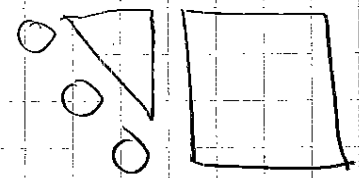
end marker  $\rightarrow$



$\Theta(N)$  time  
 $\Theta(N^2)$  HW

Similar alg with pivoting (Leighton pp. 82-92)

Matrix inverse:



« Inverse bad numerically »

## Transitive closure of a digraph

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Problem: Given a directed graph, for all pairs  $(i, j)$ , determine if  $\exists$  directed path from  $i$  to  $j$ .



### Adjacency matrix

$$A = (a_{ij}) \quad a_{ij} = \begin{cases} 1 & \text{if } i \rightarrow j \text{ is an edge} \\ 0 & \text{otherwise} \end{cases}$$

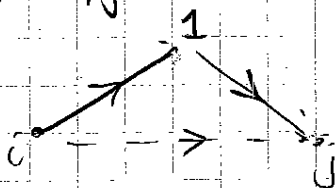
(Assume  $a_{ii} = 1$  for simplicity)

Trans. closure  $A^* = (a_{ij}^*)$ ,  $a_{ij}^* = 1$  iff  $\exists$  path  $i \xrightarrow{*} j$

Step 1:  $\forall i, j$  &  $a_{ii}^{(0)} = 1$  and  $a_{ij}^{(0)} = 1$ , set  $a_{ij}^{(1)} = 1$ .

$$\text{I.e., } a_{ij}^{(1)} \leftarrow a_{ij}^{(0)} \vee a_{ik}^{(0)} a_{kj}^{(0)}$$

Shortcut node 1:



$$A \leftarrow A^{(0)} \rightarrow A^{(1)}$$

$$\text{Step 2} \quad a_{ij}^{(2)} \leftarrow a_{ij}^{(1)} \vee a_{ik}^{(1)} a_{kj}^{(1)}$$

$$A^{(1)} \rightarrow A^{(2)}$$

$$\vdots$$

$$\text{Step } k \quad a_{ij}^{(k)} \leftarrow a_{ij}^{(k-1)} \vee a_{ik}^{(k-1)} a_{kj}^{(k-1)}$$

$$A^{(k-1)} \rightarrow A^{(k)}$$

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LS, JTheorem  $A^{(k)} = A^*$ Proof. (Induction on  $k$ )Claim:  $a_{ij}^{(k)} = 1$  iff  $\exists$  path  $i \rightarrow j$  in orig graph only going through nodes  $1, 2, \dots, k$ . $(\Rightarrow)$  Easy. $(\Leftarrow)$  Case 1.  $i \rightarrow j$  through  $1, \dots, k-1$   $a_{ij}^{(k-1)} = 1$ Case 2.  $i \rightarrow k$  through  $1, \dots, k-1$   $a_{ik}^{(k-1)} = 1$ . $k \rightarrow j$  through  $1, \dots, k-1$   $a_{kj}^{(k-1)} = 1$ .  $\square$  $\Theta(N)$  time on  $N \times N$  mesh.

Idea: Same computation as G.E.:

$$a_{ij}^{(k)} = a_{ij}^{(k-1)} - \frac{a_{ik}^{(k-1)} a_{kj}^{(k-1)}}{a_{kk}^{(k-1)}}$$

Also, shortest paths:

 $a_{ij}$  = weight of edge from  $i$  to  $j$ .  
( $\infty$  if no edge.) $a_{ij}^*$  = weight of min-weight path from  $i$  to  $j$ .  
sum edge weights.

$$a_{ij}^{(k)} = \min(a_{ij}^{(k-1)}, a_{ik}^{(k-1)} + a_{kj}^{(k-1)})$$

Homework: min spanning tree.Use thm: An edge  $i \rightarrow j$  with weight  $a_{ij}$  belongs to MST iff  $\nexists$  path from  $i$  to  $j$  with every edge having weight  $< a_{ij}$ .