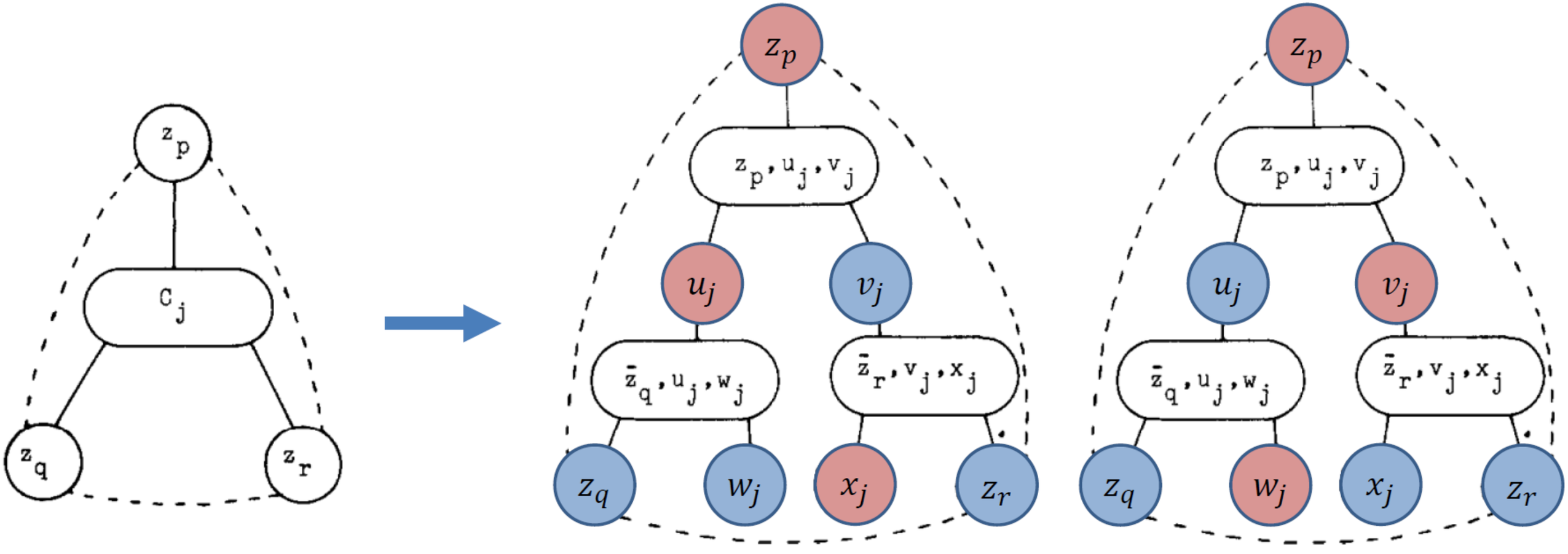
z_p
C_j
z_q
z_r
z_p
z_p, u_j, v_j
u_j
v_j
$\bar{z}_q, u_j, w_j$
$\bar{z}_r, v_j, x_j$
z_q
w_j
x_j
z_r
z_p
z_p, u_j, v_j
u_j
v_j
$\bar{z}_q, u_j, w_j$
$\bar{z}_r, v_j, x_j$
z_q
w_j
x_j
z_r