

Folding any shape: [Demaine, Demaine, Mitchell 2000]

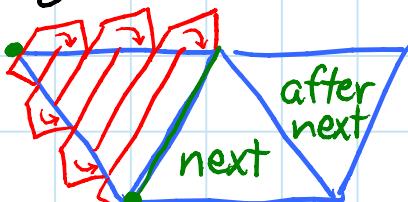
(a.k.a. silhouette [Bern & Hayes 1998] / gift wrapping [Akiyama/Gardner])

Every connected union of polygons in 3D, each with a specified visible color (on each side), can be folded from a sufficiently large piece of bicolor paper of any shape (e.g., square).



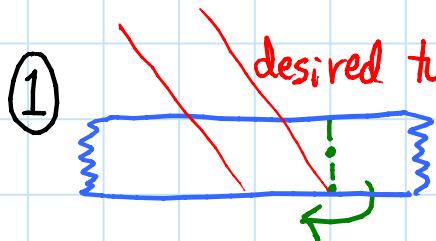
Proof: fold paper down to long narrow strip (!)

- triangulate the polygons
- choose a path visiting each triangle at least once
- cover each triangle along the path by zig-zag parallel to next edge, starting at opposite corner:

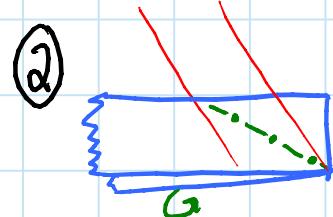


choose parity of zig-zag to arrive at correct corner for next triangle

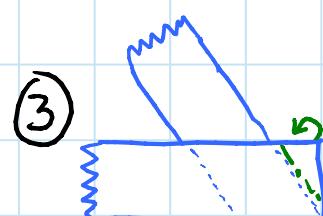
- furn gadget implements zig-zags & vertex turns:



perpendicular mountain



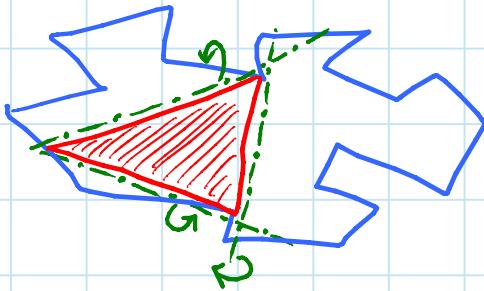
fold bottom layer



hide excess
(many folds)

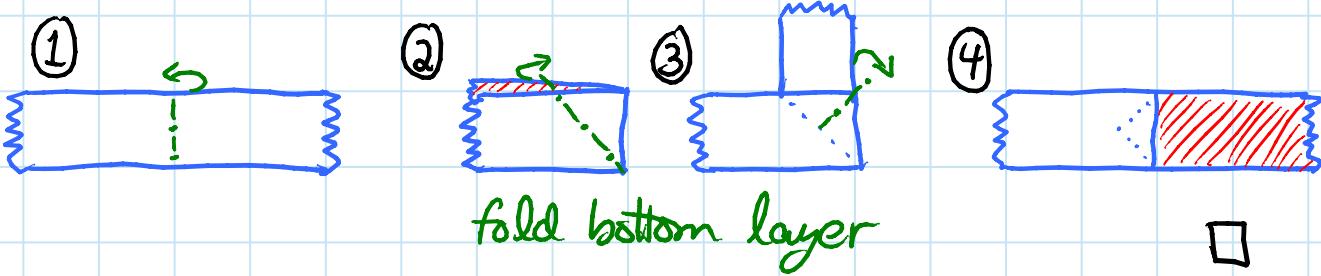
Proof of folding any shape: (cont'd)

- hide excess paper underneath each triangle:
(more generally, can hide under any convex polygon)



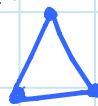
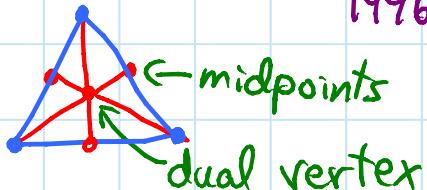
repeatedly mountain fold
along lines extending
desired edges

- color-reversal gadget along transition
between triangles of opposite colors:

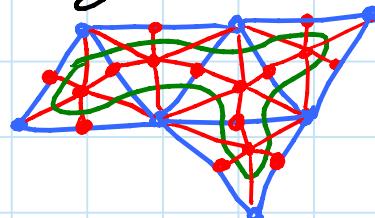


Pseudo-efficiency: if allowed to start with any rectangle of paper, then can achieve
 $\text{area}(\text{paper}) = \text{area}(\text{surface}) + \varepsilon$ for any $\varepsilon > 0$

Proof: construct Hamiltonian refinement [Arkin et al. 1996]
of triangulation:

- cut each  into 

- walk around spanning tree of original dual:

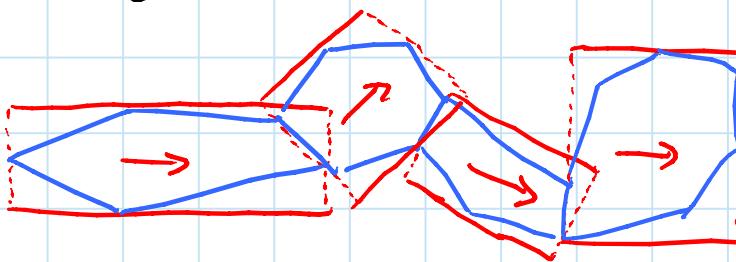


- now visit each triangle exactly once
- wastage from turns $\rightarrow 0$ with strip width. \square

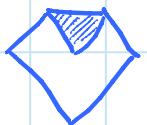
OPEN: pseudopolynomial upper bound? lower bound?

Seam placement: can place seams (visible creases/paper boundary) as desired, provided regions between seams are convex

- idea: vary strip width, use hide gadget



OPEN: what seam placements are possible?



OPEN: can a given polygon of paper fold into a given target polygon? likely NP-hard

OPEN: what is the smallest square that can fold into a given shape? NP-hard?

Cube wrapping: [Catalano-Johnson & Loeb 2001]

- consider 1×1 square

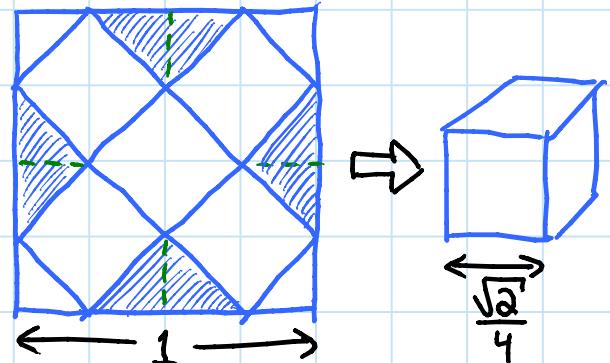
- in $x \times x \times x$ cube,
every point has an
antipodal point $\geq 2x$ away
 \Rightarrow center of square must
be $\geq 2x$ away from corner

(points only get closer by folding)

\Rightarrow opposite corners have distance $\geq 4x$

\Rightarrow side length $\geq 2\sqrt{2}x$

$\Rightarrow x \leq \frac{1}{2\sqrt{2}} = \frac{\sqrt{2}}{4}$ & this is possible



OPEN: optimal square \rightarrow regular tetrahedron?

OPEN: $x \times y$ rectangle \rightarrow largest cube?

- strip method efficient as $x/y \rightarrow \infty$

OPEN: optimal square \rightarrow unit $k \times k$ checkerboard

- conjecture: $k/2$ for even $k \geq 4$

- no real lower bounds

- seamless?

Tree method: [Lang 1994–2003; Lang & Demaine 2004–]

algorithm to find folding of smallest square into "uniaxial" origami base whose projection is a desired metric tree



But:

- optimization is difficult: exponential time, as hard as disk packing, but good heuristics
- non-self-intersection is only conjectured
(we're working on it)

Uniaxial base:

- ① in $z \geq 0$ half-space
- ② intersection with $z=0$ plane
= projection onto that plane
- ③ partition of faces into flaps, each projecting to a line segment (\Rightarrow all faces vertical)
- ④ hinge crease shared by two flaps projects to a point: common endpoint of flap projections
- ⑤ graph of flap projections as edges, connected when flaps share a hinge crease, is a tree (shadow tree). Hinge creases projecting to a vertex form a hinge
- ⑥ only one point of paper folds to each leaf

Tree method: (cont'd)

Key lemma: in any uniaxial base from convex paper,
 distance between two points on shadow tree
 \leq distance between corresponding points on paper

Proof: latter = length of line segment on paper

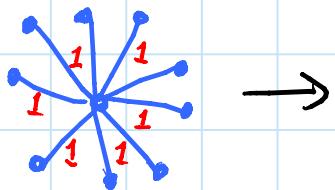
- folds to path in uniaxial
- projects to shorter path on shadow tree
- shortest path in tree is only shorter \square

Scale optimization: focus on shadow leaves i
 & placement as points p_i on paper:

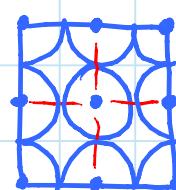
$$\left\{ \begin{array}{l} \text{maximize } \lambda \\ \text{subject to } d(p_i, p_j) \geq \lambda \cdot d(i, j) \text{ for leaves } i, j \\ \text{distance on paper} \quad \text{fixed distance in tree} \end{array} \right.$$

- quadratic constraint

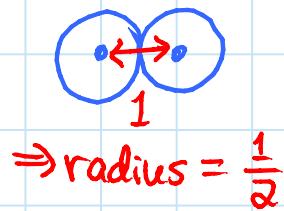
Example:



star



disk packing, centers in square



$$\Rightarrow \text{radius} = \frac{1}{2}$$

\Rightarrow with $n \times n$ piece of paper, get $(n+1)^d$ arms in star; can flatten to perimeter $\Theta(n^2)$

\rightarrow MARGULIS NAPKIN PROBLEM [Lang 2003]

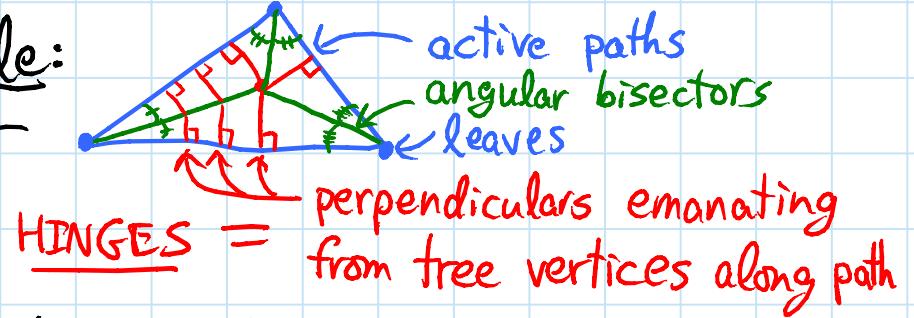
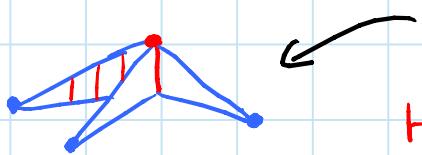
Tree method (cont'd)

Active path = path between two shadow leaves
 of length = distance in piece of paper
 - never cross each other [GFALOP Lem. 16.4.2]

Triangulation: can add artificial leaf edges to the shadow tree to make the active paths partition the piece of paper into triangles (without changing scale factor) [GFALOP, Lem. 16.6.2]

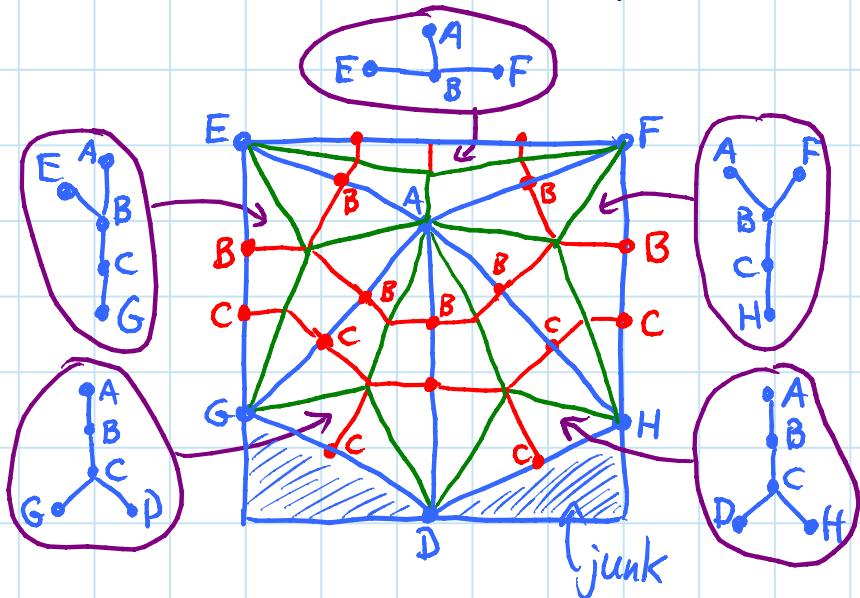
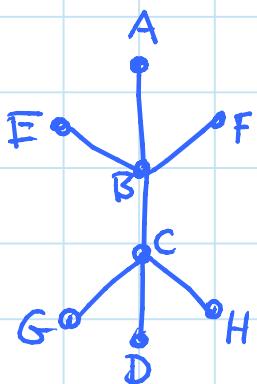
- later these leaf edges can be "folded away"
- some triangle edges are paper boundary, not active

Rabbit-ear molecule:



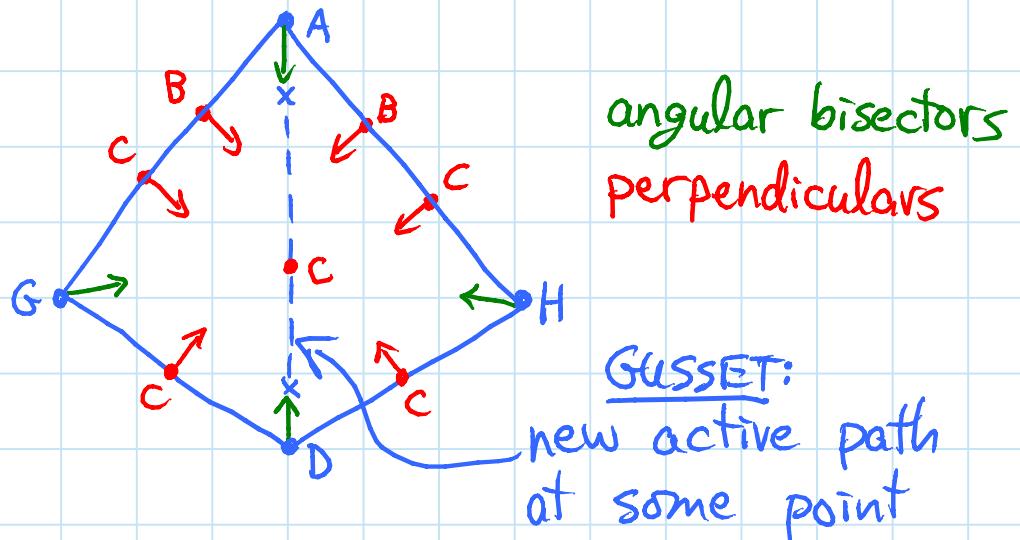
- put them together to form entire shadow tree

Example:

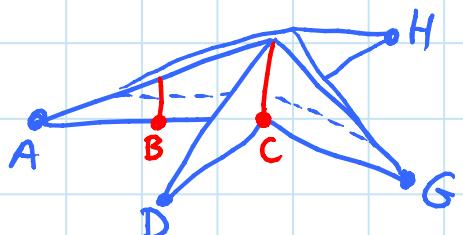
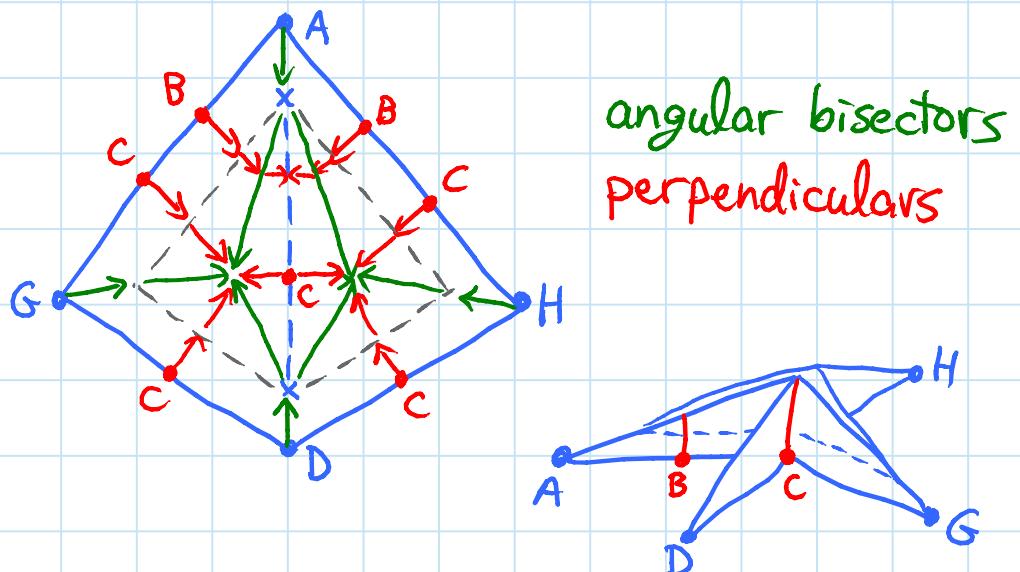


More practically:

- use convex decomposition instead of triangulation
(in practice by letting tree edge lengths vary a bit)
- Lang Universal Molecule folds convex polygon



GUSSET:
new active path
at some point



2 kinds of events:

① gusset: new active path →
split shrunken polygon

② two vertices meeting →
continue along new angular bisector