### Computer Vision for Medical Imaging

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### **Medical Vision Group**

Polina Golland, Eric Grimson Sandy Wells, John Fisher And many, many students



### **Medical Imaging**





### **Analysis + Visualization**







### **Medical Vision**

## Surgical planning and navigation





### Simulation

### Population modeling





### **Conventional Surgery: See the** surface





Provided by Nakajima, Atsumi et al.

### Image Guided Surgery: See under the surface



# Intelligently aiding the surgeon

- Convert medical images into models of patient's:
  - Structural anatomy
  - Functional anatomy
  - Vascular structure



### **Example patient specific models**









### **Functional information**





### Visualizing the surgical site

- Augmented reality visualizations
  - combine with real imagery
- Surgical guidance
  - planning and navigation
- Simulation of surgical navigation
  - Use image information for diagnostics



### **Augmented Reality**



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### **Multi-modal Modeling**









### **Surgical guidance**





Joint with Brigham and Women's Hospital

### Simulation: Virtual Endoscopy





### **Virtual Endoscopy**





Joint with Brigham and Women's Hospital

### **Population Studies**



How does a disease affect anatomical shape?



### **Hippocampus in Schizophrenia**





Joint with Brigham and Women's Hospital and

### **Cortical Thickness**

#### **Cortical thickness in Alzheimer's disease**







Joint with Mass General Hospital



### **fMRI Analysis**

- Brain activation
- Faces vs. other objects



94%, *p*< .03



Joint with Mass General Hospital and BCS, MIT

### **Back to Visualization**





### **Methods**

- Segmentation
- Shape Analysis
- DTI Analysis



### Image interpretation: voxel classification

- Measure distribution of intensities for each class
- Classify each voxel based on its intensity







### Problem: Bias (gain) field







### Solution: EM segmentation [Wells 1994]

- If one knew the gain field
  - correct image and use standard statistical methods
- If one knew the tissue types
  - could predict the image and find the gain field correction
- Solution:
  - Expectation Maximization (EM) method
  - iteratively solve for gain field and tissue class using probabilistic models



### **EM-Segmentation**

- Observed Variables Y
  - log transformed intensities in image
- Hidden Variables W
  - indicator variables for classification
- Model Parameters  $\, m{b} \,$ 
  - the slowly varying corrupting bias field
  - (  $Y_s, W_s, \boldsymbol{b}_s$  refer to variables at voxel s in image)



### **EM-segmentation**

E-Step

Compute tissue posteriors using current intensity correction.

$$\widetilde{P}^{(t)}(W) = P(W \mid Y, \boldsymbol{b}^{(t-1)})$$

#### M-Step

Estimate intensity correction using residuals based on current posteriors.

$$\boldsymbol{b}^{(t)} = \operatorname*{arg\,max}_{\boldsymbol{b}'} E_{\widetilde{P}^{(t)}}[\log P(\boldsymbol{b}'|W,Y)]$$



### **EM Segmentation**







### Handling local interactions: Markov Random Fields

- Prior in EM-Segmentation:
  - Independent and Spatially Stationary
- Markov Random Field (MRF)
  - probability model on a lattice
  - partially relaxes independence assumption to allow interactions between neighbors
  - used in image restoration [Geman&Geman 84]
- Use mean field approximation for MAP estimation of the label-map



### **EM-MF Algorithm [Kapur 1998]**



### **Example Results**



#### Noisy MRI EM Segmentation EM-MF Segmentation



### **Posterior Probabilities**



EM

**EM-MF** 



White matter Gray matter



### Evolution of the Model [Pohl 2002]

New E-Step:

W(T):=
$$P_x(T) \cdot P(I | T, B)$$
 $exp[-Energy(T | Neighbors)]$ EMAlgorithmMFLocal Prior

- T Labelmap
- I Log Image
- B Image Inhomogeneities



### Segmentation of 31 Structures [Pohl 2004]



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### **Segmentation of 31 Structures**



Upper Front


### **Segmentation of 31 Structures**



Lower Front



### **Segmentation of 31 Structures**





### **Boundary Localization**

• Active Contours, 'Snakes', Level Sets





### **Geodesic Active Contours**

- Snake methodology defines an energy function E(C) over a curve C as  $E(\mathcal{C}) = \beta \int |\mathcal{C}'(q)|^2 dq \lambda \int |\nabla I(\mathcal{C}(q))| dq$
- Caselles, et al. reduced the minimization problem to the expression.

$$\min_{\mathcal{C}(q)} \int g(|\nabla I(\mathcal{C}(q))|) |\mathcal{C}'(q)| dq$$

where g is a function of the image gradient of the form  $\frac{1}{1+|\nabla I|^2}$ .

• The following curve evolution equation can be derived using Euler-Lagrange.  $\frac{\partial \mathcal{C}(t)}{\partial t} = g\kappa \mathcal{N} - (\nabla g \cdot \mathcal{N})\mathcal{N}$ 

where  $\kappa$  is the curvature and N is the normal.

 By defining an embedding function u of the curve C, the update equation for the higher dimensional surface is given by (Osher, Sethian '88):

$$\frac{\partial u}{\partial t} = g \kappa |\nabla u| + \nabla u \cdot \nabla g$$



## Shape Prior for Segmentation [Leventon 2001]

### • Train on a set of shapes

- Mean shape
- PCA-based model of variation
- Bias the segmentation towards likely shapes



## **Training Data**

 The training set, T, consists of a set of surfaces: T = {u<sub>1</sub>, u<sub>2</sub>, ..., u<sub>n</sub> }

$$T = \left\{ \begin{array}{c} & & \\ & &$$

• The mean shape

$$\mu = \bigcirc$$



### **Principal Modes of Variation** (using PCA)





### **Shape Distribution**





A





D



Е





### Regularization

#### **Prior Model of Curvature**



Histograms of the Curvature of the training objects



## **Modified Evolution Equation**





## **Corpus Callosum Segmentation**





## **Corpus Callosum Segmentation**





### **Spine Modes**

• 3D Models of seven thoracic vertebrae (T3-T9)





### **Spine Mean Shape**





### **Spine 1<sup>st</sup> Mode of Variation**









### **Segmentation of the Vertebrae**



## **Comparison to human expert**





## **Segmentation Summary**

- EM for bias field correction
- MRFs for spatial priors on image labelings
- Shape and appearance priors for segmentation



# Learning Shape from Images

• Building quantitative models of natural shapes and their variability from images.

• Creating useful representations and visualizations of the learned concepts.



## **Neuroimaging Studies**



### How does the brain develop? How does a disease affect its structure and function?

Learn from observing the population.



### **Problem:**

Given two (small) sets of shapes, what are the differences, if any?





### **Solution**



#### Discriminative direction



# Challenges

- Complexity of shapes
  - rich representations
  - classification framework

Visualization of the statistical model
discriminative direction

- High dimensionality of data
  - need less data than suggested by conventional analysis



# **Analysis Framework**

1. Feature extraction



2. Statistical modeling



- 3. Classifier analysis
  - discriminative direction
  - statistical significance





# Discriminative direction [Golland 2001]

Move the input example towards the other class without introducing irrelevant changes.

- Linear case  $f(\mathbf{x}) = \langle \mathbf{x} \cdot \mathbf{w} \rangle + b$
- Discriminative direction is *w*.



 General case: search for direction dx that minimizes irrelevant changes with respect to f(x).

## Study of shape

### Hippocampus shape in schizophrenia





# fMRI Analysis [Golland et al 2003]

- Brain activation
  - fMRI analysis
  - visual stimuli
- Faces vs. other objects



94%, *p*< .03



# **DTI: Neural Structure and MRI**

- MRI signal is from protons in water
- Membranes restrict water diffusion
- Diffusion causes MRI signal loss
- 3D shape of water diffusion









## **Diffusion tensor MRI**

- Complex data can only be partially visualized
  - Show subset of diffusion measurements (eigenvector)





### **DT-MRI Tractography**



H.J. Park, M.E. Shenton, C.-F. Westin



## **Issues in Tractography**

- Single path:
  - shows strongest connection only
- Errors accumulate
- Fiber crossing:
  - ambiguous path due to local decisions



# Diffusion-Based Connectivity [O'Donnell 2002]

- Use anisotropic diffusion equation
  - Sources and sinks in the tensor field
  - Steady-state concentration and flow



the diffusion tensor

• Flow along a path reflects connectivity





### **Steady-State Flow**





### **Diffusion-Based Connectivity**







# Distance-Based Connectivity [O'Donnell 2002]

- Connectivity should be proportional to distance in some metric space  $|v|_G^2 = v^T G v$
- Probabilistic interpretation:





Metric Tensor

# **Distance Map**

initial point

- Input:
  - Riemannian metric tensor G
  - initial point
- Output:
  - geodesic paths
  - distances between points


# **Distance-Based Connectivity**

- Proportional to length of the geodesic
- Normalize by Euclidean length

 $C = \frac{L_{Euclidean}}{L_{Geodesic}}$ 





# **Distance-Based Connectivity**

- Computed connectivity measure in 3D
- Tractography: highest-connectivity region





### **Multi-modal Pre-operative model**







#### Visualization of DTI and fMRI





### Summary

- Interesting, hard problems looking for principled methods
- Methods
  - Segmentation
  - Shape analysis
  - fMRI, DTI analysis
- Applications
  - Surgical planning
  - Neuroscience

