

## Today: Differential Privacy

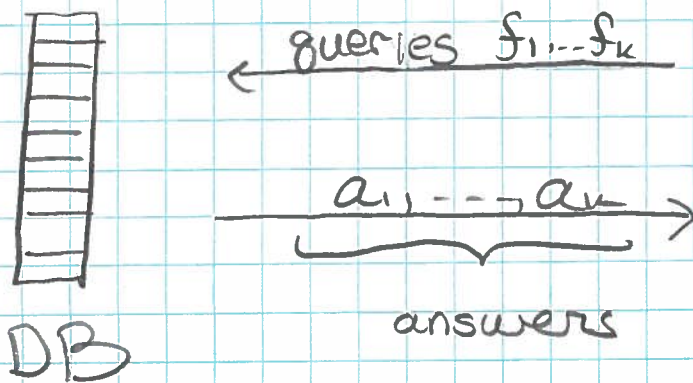
Goal: Privacy-preserving data analysis:

A trusted (and trustworthy) curator gathers sensitive information from a large number of respondents (the sample), and the goal is learning, and releasing to the public, statistical facts about the underlying population, without compromising the privacy of the individual respondents.

\* Statistical analysis of sensitive data brings tremendous benefits, but has serious privacy risks.

Example: Statistical analysis on medical records of patients.

Challenge: Reconcile statistical analysis and privacy (even in the presence of linkage attacks)

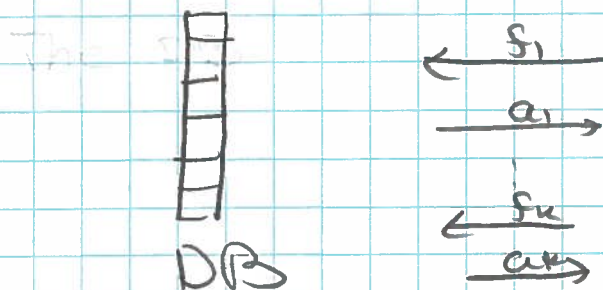
Data Analysis ModelTwo settings:

- Non-interactive setting:

Curator computes & publishes the statistics  $(a_1, \dots, a_k)$ , and the data is not used further.

- Interactive setting:

The curator sits between DB & users  
 Queries are posed adaptively.



\* We won't distinguish between these two settings.

## Two major privacy concerns:

- Linkage attacks: Protect against adversary that has partial information.
- Composition: Maintain privacy even when the data is used in multiple analyses (each privacy preserving in isolation).

## Natural Approaches:

- Anonymization: Remove "personally identifiable information", and publish the "anonymized" dataset.
- "Just" releasing statistics: Only release aggregate statistics
- Perfect Privacy: Perfect protection of individuals?

Our focus: Differential Privacy.

Data anonymization is not safe!

Example : Netflix data release [Narayanan-Shmatikov'08]

Netflix released ratings for subset of movies & users, where usernames were replaced with random IDs (& some additional perturbation)

[NS08] used this data, together with public reviews from IMDB.com to de-anonymize netflix data.

⇒ Learn about movies that IMDB users didn't want to tell the world about.

This attack is a linkage attack.

"Just" releasing statistics is not safe

Suppose data was collected about the # of HIV patients among MIT students.

And suppose it is known that no-one (except me) has HIV.

In this case, this statistics violates my privacy.

\* Auxiliary information is a common theme in privacy horror stories.

Lets aim for perfect privacy!

Semantic security ??

Anything that can be learned about participants from privacy-preserving data analysis can be learned without it.

Unachievable!

Example :

DB + Analysis : smoking causes cancer.

Aux info : I smoke in public.

⇒ I am "hurt" : insurer knows that I am at risk for cancer.

Differential Privacy

[Dwork - McSherry - Nissim - Smith 06]

Intuition : The output distribution when I am in the database or out of the database, should be similar.

⇒ Risk incurred by participation is low.

Definition : A randomized algorithm  $\mathcal{K}$  is

$\epsilon$ -differentially private if  $\forall S \subseteq \text{Range}(\mathcal{K})$  4/10

$\forall$  datasets  $D_1, D_2$  differing on at most one element,

$$\Pr[\mathcal{K}(D_1) \in S] \in (e^{-\epsilon}, e^{\epsilon}) \cdot \Pr[\mathcal{K}(D_2) \in S]$$

where the prob. is over the coin tosses of  $K$ ,

Linkage attacks? <sup>or aux input</sup>

Guarantee is for any adjacent  $D_1$  &  $D_2$

Composition?

( $D_1$  &  $D_2$  are adjacent if they differ in a single row)

$l$  (adaptively chosen) algorithms, each  $\epsilon$ -differentially private

$\Rightarrow$  Taken together is still  $l \cdot \epsilon$ -differentially private.

Thm [Composition of differential privacy]:

If  $K_1(D)$  is  $\epsilon_1$ -diff. private, &  $\forall z_1$  in range  $K_1$

$K_2(D, z_1)$  is  $\epsilon_2$ -diff. private,

then  $K(D) \triangleq (K_1(D), K_2(D, K_1(D)))$  is  $(\epsilon_1 + \epsilon_2)$ -diff. private.

PS: Fix  $S \subseteq \text{RANGE}(K)$ , and fix any adjacent datasets  $D, D'$ .

$$\Pr[K(D) \in S] = \sum_{(z_1, z_2) \in S} \Pr[K_1(D) = z_1] \cdot \Pr[K_2(D, z_1) = z_2]$$

$$\leq \sum_{(z_1, z_2) \in S} (e^{-\epsilon_1}, e^{\epsilon_1}) \Pr[K_1(D') = z_1] \cdot (e^{-\epsilon_2}, e^{\epsilon_2}) \Pr[K_2(D', z_1) = z_2]$$

$$= (e^{-(\epsilon_1 + \epsilon_2)}, e^{\epsilon_1 + \epsilon_2}) \sum_{(z_1, z_2) \in S} \Pr[K_1(D') = z_1] \cdot \Pr[K_2(D', z_1) = z_2] =$$

$$= (e^{-(\epsilon_1 + \epsilon_2)}, e^{\epsilon_1 + \epsilon_2}) \cdot \Pr[K(D') \in S]$$

Lec 21.8

How do we construct differentially private algorithms? [Focus: simple function.]

Example: Not differentially private.

Suppose DB contains tuples  $(name, tag \in \{0, 1\})$

Goal: approximate fraction of population with tag = 1

Answer: <sup>Approximate by</sup> Choosing a few random tags.

What if in DB only my tag is 1.

$$\Pr[K(D+me) \neq 0] \geq \frac{1}{n}$$

$$\Pr[K(D) \neq 0] = 0.$$

Not differentially private for any  $\epsilon$ .

Differentially private alg:

Output #1's + noise

This is differentially private for "proper noise".

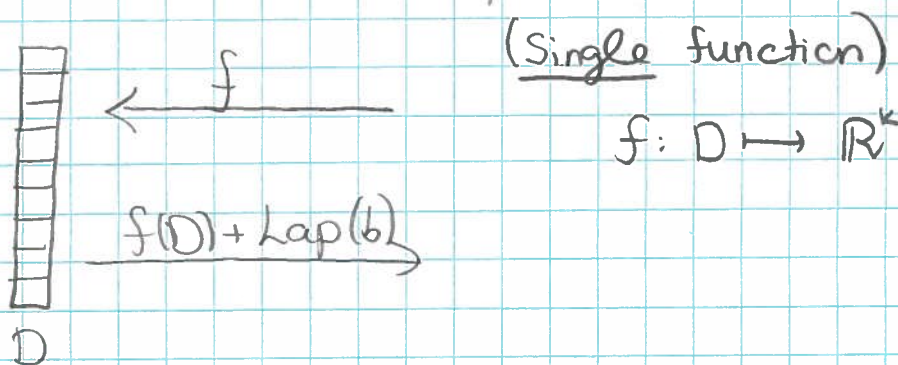


Laplacian NoiseLaplace distribution  $Y = \text{Lap}(b)$ 

density function  $\Pr[Y=y] = \frac{1}{2b} e^{-|y|/b}$

Standard deviation:  $O(b)$ 

Laplace dist. can be thought of as two exponential distributions spliced together back-to-back

 $\epsilon$ -differentially private mechanism:Q: what parameter  $b$  ??A:  $b$  depends on  $\epsilon$  & on the "sensitivity" of  $f$ .Def: For  $f: D \rightarrow \mathbb{R}^k$  the sensitivity of  $f$  is

$$\Delta f = \max_{\text{adjacent } D_1, D_2} \|f(D_1) - f(D_2)\|_1$$

In particular, for  $k=1$  the sensitivity of  $f$  is the maximum difference in the values that the function  $f$  may take on a pair of adjacent databases.

For many types of queries  $\Delta f$  is quite small.

For example, for counting queries ("how many rows have property  $P$ ?"),  $\Delta f=1$ .

The differentially private mechanism works best (i.e., introduces the least noise) when  $\Delta f$  is small.

Note that sensitivity is a function of the function alone, and is independent of the database.

The sensitivity captures how great a difference (between the value of  $f$  on two adjacent databases) must be hidden by the additive noise generated by the curator.

On query  $f$  the  $\epsilon$ -differentially private mechanism responds with:

$$f(D) + \text{Lap}(\Delta f / \epsilon)^k$$

adding noise w. distribution  $\text{Lap}(\Delta f / \epsilon)$  independently to each coordinate of  $f(D)$

Note: Decreasing  $\epsilon$  yields larger expected noise magnitude.  
Increasing the sensitivity  $\Delta f$  also yields larger expected noise magnitude.

Thm: The mechanism described above is  $\epsilon$ -differentially private.

"Pf": For  $k=1$  (and single query).

Fix any  $f: D \rightarrow \mathbb{R}$ , any  $S \subseteq \mathbb{R}$  (think of  $S$  as finite),  
any adjacent datasets  $D_1, D_2$

$$\begin{aligned} \Pr[K(D_1) \in S] &= \sum_{z \in S} \Pr[K(D_1) = z] = \sum_{z \in S} \Pr[f(D_1) + \text{Lap}(\Delta f/\epsilon) = z] \\ &= \sum_{z \in S} \Pr[\text{Lap}(\Delta f/\epsilon) = z - f(D_1)] = \sum_{z \in S} \frac{1}{2 \Delta f/\epsilon} e^{-|z - f(D_1)| / (\Delta f/\epsilon)} \\ &= \sum_{z \in S} \frac{1}{2 \Delta f/\epsilon} e^{-|z - f(D_2) + f(D_2) - f(D_1)| / (\Delta f/\epsilon)} \\ &\in \sum_{z \in S} \frac{1}{2 \Delta f/\epsilon} e^{-|z - f(D_2)| / (\Delta f/\epsilon)} \cdot \left[ e^{-|f(D_2) - f(D_1)| / \Delta f/\epsilon}, e^{|f(D_2) - f(D_1)| / \Delta f/\epsilon} \right] \\ &\in \Pr[K(D_2) \in S] \cdot (e^{-\epsilon}, e^{\epsilon}) \quad \square \end{aligned}$$