

<b>Port</b>	<b>Mode</b>	<b>Usage</b>
0	Servo	servo 0 (arm shoulder)
1	Servo	servo 1 (arm grasper)
2	Digital	servo 2 (arm elbow)
3	Digital	servo 3 (expansion)
4	SonarPulse	sonar 0 (front)
5	SonarEcho	sonar 0 (front)
6	SonarPulse	sonar 1 (back)
7	SonarEcho	sonar 1 (back)
8	Digital	bump 0 (left)
9	Digital	bump 1 (front left)
10	Digital	bump 2 (front right)
11	Digital	bump 3 (right)
12	Analog	light sensor 0 (left)
13	Analog	light sensor 1 (right)
14		
15	gyro	gyro?
16	QuadPhase0A	encoder 0 (left motor)
17	QuadPhase0B	encoder 0 (left motor)
18	QuadPhase1A	encoder 1 (right motor)
19	QuadPhase1B	encoder 1 (right motor)