

Network Flows

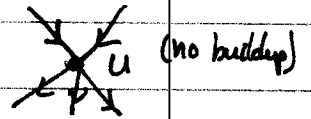
Flow network: directed graph $G=(V,E)$ with source vertex (s) and sink (t) ; each edge $(u,v) \in E$ has non-negative capacity $c(u,v)$; if $(u,v) \notin E$, then $c(u,v) = 0$.

Flow on G is a function $f: V \times V \rightarrow \mathbb{R}$ satisfying

① Capacity constraint: $f(u,v) \leq c(u,v) \quad \forall u,v \in V$

② Flow conservation: $\sum_{v \in V} f(u,v) = 0 \quad \forall u \in V - \{s,t\}$

③ Skew symmetry: $f(u,v) = -f(v,u)$

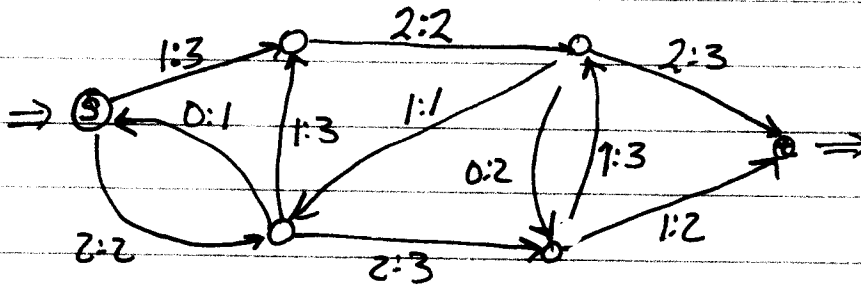


Flow Value, $|f| = \sum_{v \in V} f(s,v)$, is total flow out of source.

notation: (cp. letter indicates implicit summation)

Can be shown that this is equal to flow into sink

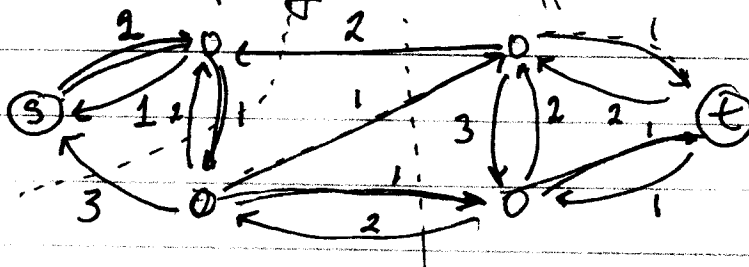
Goal: FINDING Maximum Flow Value



Residual Capacity

Residual Capacity of $(u,v) = c_f(u,v) = c(u,v) - f(u,v) \geq 0$

Residual Network G_f is graph of edges with strictly positive residual capacity (that can support more flow)



Augmenting Path is a path from s to t in G_f .

Because the residual network G_f contains only edges that have excess capacity, any augmenting path in G_f represents a perturbation of the flow f with increased flow value.

Flow value can be increased along augmenting path p by $C_f(p) = \min_{(u,v) \in p} \{C_f(u,v)\}$

↓ Suggests an algorithm (method)

- ① Start with Zero Flow
 - ② Find an augmenting path p in corresponding G_f
 - ③ Augment f by $C_f(p)$ and loop
- ⇒ FORD - FULKERSON ALGORITHM

Potential Problems

Convergence? Can it enter infinite loop? No, because we only accept augmenting paths.

Can we be guaranteed of finding an augmenting path if one exists? Breadth-First Search finds all shortest paths from s source. If none are found to sink, then none exist.

- Do we want a shortest path?

- Do we want a longest path?

- We really want a path of maximum capacity.

Global optimum? When no more augmenting paths can be found, how do we know we haven't found a local optimum rather than the global optimum?

Properties of Flows

Lemma (26.1 in CLRS)

For $G=(V,E)$ a flow network and f a flow in G .

- ① $f(X,X) = 0$ for all $X \subseteq V$ → ^{double} summation includes $f(x,x') + f(x',x) =$ ^{skew} $f(x,x') - f(x',x) = 0$
- ② $f(X,Y) = -f(Y,X)$ for all $X, Y \subseteq V$ (skew)
- ③ $f(X \cup Y, Z) = f(X, Z) + f(Y, Z)$ for all $X, Y, Z \subseteq V$ and $X \cap Y = \emptyset$
(expand summation, combine terms, recontract summations)

Illustrate Use:

Flow is defined as net flow leaving source; show equal to that entering sink

demonstrate: $|f| \equiv f(s, V) = f(V, t)$

book

$$\begin{aligned}
 |f| &\equiv f(s, V) \\
 &= f(V, V) - f(V - \{s\}, V) \quad \text{lemma ②} \\
 &= 0 + f(V, V - \{s\}) \quad \text{lemma ③} \\
 &= f(V, t) + f(V, V - \{s, t\}) \quad \text{lemma ③}
 \end{aligned}$$

lemma ②: 0 by flow conservation

$$\begin{aligned}
 |f| &\equiv f(s, V) \left(+ f(V, t) - f(V, t) \right) \\
 &= f(V, t) - (f(V, s) + f(V, t)) \quad \text{lemma ③} \\
 &= f(V, t) - f(V, \{s, t\}) + f(V, V) \quad \text{lemma ①} \\
 &= f(V, t) + f(V, V - \{s, t\}) \quad \text{lemma ③} \\
 &\quad \quad \quad 0 \text{ by flow conservation}
 \end{aligned}$$

slightly more
in text

Cut is partition of V into $S \cup T$ ($S \cap T = \emptyset$)
with $s \in S$ and $t \in T$.

Capacity of cut $c(S, T) = \sum_{u \in S} \sum_{v \in T} c(u, v) = c(S, T)$

forward capacity
cut:

- Small capacity cuts serve as "barriers" to large flows.
- A minimum cut of a network is that whose capacity is a minimum over all cuts in network.

Lemma: Given any flow f , $|f| = f(S, T)$ for any cut (S, T)

Proof: $f(S, T) = f(S, V) - f(S, S) = 0$
 $= f(s, V) + \underbrace{f(S-s, V)}_0$
 $= |f|$ 0 by flow conservation

- ↳ This is like another conservation of flow idea
- by definition for flow out of source ($S = \{s\}$)
 - already proven for flow into sink ($T = \{t\}$)
 - here proven for any partition (cut) dividing s, t

The value of any flow is bounded above by the capacity of any cut.
 Proof: $|f| = f(S, T) = \sum_{u \in S} \sum_{v \in T} f(u, v) \leq \sum_{u \in S} \sum_{v \in T} c(u, v) = c(S, T)$

The Max-flow Min-Cut Theorem

The following are equivalent

- ① f is a maximum flow in G
- ② The residual network G_f contains no augmenting paths
- ③ $|f| = c(S, T)$ for some cut (S, T) of G (minimum cut)

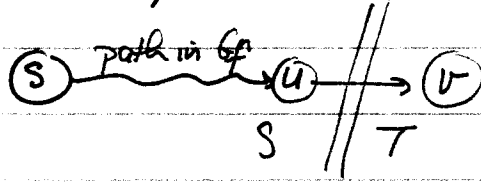
Corollary

Proof Sketch

① \Rightarrow ② Augmenting path would allow flow in G to be increased above f , contradicting its being a maximum flow

③ \Rightarrow ① By corollary, $|f|$ is bounded ^{from above} by the capacity of any cut, so $|f| = c(S, T)$ means it can't be increased

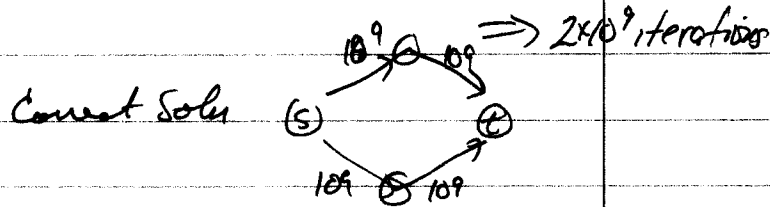
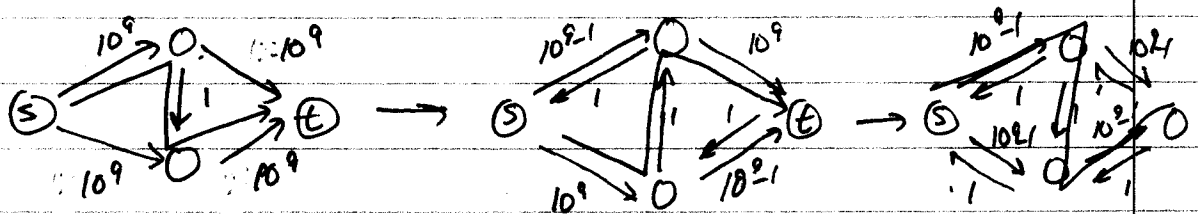
② ⇒ ③ G_f has no augmenting paths. Let $S = \{u \in V : \exists \text{ path from } s \text{ to } u \text{ in } G_f\}$ and $T = V - S$. $s \in S$ and $t \in T$ (otherwise would be augmenting path). (S, T) is a cut. $c_f(u, v) = 0$ for $u \in S, v \in T$ (otherwise v would be in S) $\therefore f(u, v) = c(u, v)$, since $c_f(u, v) = c(u, v) - f(u, v)$. $\|f\| = f(S, T) = c(S, T)$. \leftarrow summation



Thus, the Ford-Fulkerson Algorithm is guaranteed to result in successive improvements. When no more improvements are possible, the maximum flow has been found.

Analysis on integer capacities. $\|f\|$ is max flow. $\exists \in \mathbb{Z}$ is time to find path [Ford-Fulkerson] $\Rightarrow \mathcal{O}(\|f\|/E)$

Possible Efficiency Problem:



Edmonds-Karp Algorithm

- Use BFS to find breadth-first augmenting path (weights equal to unity) \leftarrow positive nonzero edges in G_f have
 - Time to find an augmenting path $\mathcal{O}(VE)$ $\Rightarrow \mathcal{O}(E^3)$ if all vertices reachable from source
 - Claim number of augmentations limited to $\mathcal{O}(VE)$ \leftarrow see below
- \Rightarrow Running time $\mathcal{O}(VE^3)$

Monotonicity Lemma

Let $\delta(v) = \delta_f(s, v)$ be breadth-first distance $s \rightarrow v$ in G_f . Suppose
 [During E-K op., $\delta(v)$ increases monotonically.] \rightarrow algorithm augments f to produce f'
 Prove $\delta'(v) \geq \delta(v)$ by induction on $\delta(v)$

Base: $\delta'(s) = \delta(s) = 0$

Inductive Step: Consider BF path $s \rightarrow \dots \rightarrow u \rightarrow v$ in G_f

$\delta'(v) = \delta'(u) + 1$ because subpaths of shortest paths are shortest paths

$(u, v) \in E_f$ [What about E_f ?] \rightarrow 2 cases

Case 1: $(u, v) \in E_f$

$$\begin{aligned} \text{then } \delta(v) &\leq \delta(u) + 1 && \text{1 unequal} \\ &\leq \delta'(u) + 1 && \text{induction} \\ &= \delta'(v) && \text{BF (above) } \checkmark \end{aligned}$$

Case 2: $(u, v) \notin E_f$

Augmenting path must have included (v, u) \leftarrow How else could this edge have ~~been~~ ~~removed~~ in ~~the~~ ~~residual~~ network?

$$\begin{aligned} \text{then } \delta(v) &= \delta(u) - 1 && \text{BF path} \\ &\leq \delta'(u) - 1 && \text{induction} \\ &= \delta'(v) - 2 && \text{BF path (above)} \\ &< \delta'(v) && \checkmark \end{aligned}$$

Theorem: # Augmentation Steps in Edmonds-Karp of s is $O(VE)$.

Proof:

Let p be an augmenting path

Residual capacity of some edge $(u, v) \in p$ is $c_f(p) = c_f(u, v)$
 $\Rightarrow (u, v)$ called critical

Augmentation removes (u, v) from critical path (for now)

Must wait until (v, u) augmented before reappears.

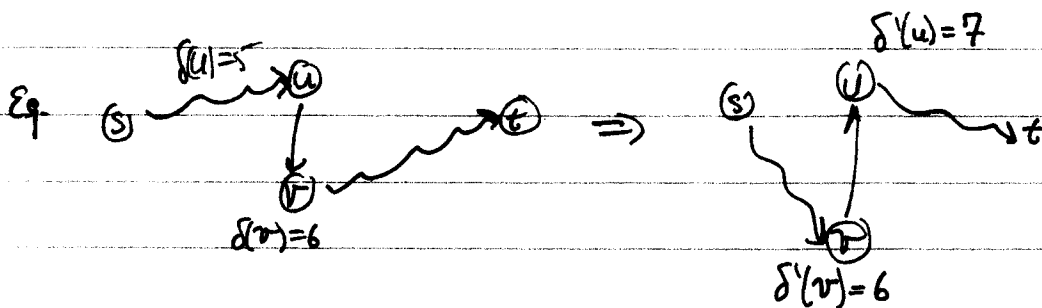
Before p augmented $(u, v) : \delta(v) = \delta(u) + 1$ (p : BF path)

Before augmenting (v, u) later:

$$\delta'(u) = \delta'(v) + 1 \quad (\text{BF path})$$

$$\geq \delta(v) + 1 \quad (\text{monotonicity lemma})$$

$$= \delta(u) + 2 \quad (\text{above})$$



$\Rightarrow \delta(u)$ increases ≥ 2 between times when (u, v) is critical.

Each $\delta(u)$ starts ≥ 0 , never decreases, and remains $\leq |V| - 1$ until unreachable.

$\Rightarrow (u, v)$ is critical at most $O(V)$ times

$O(E)$ edges in $G_f \Rightarrow O(V^2)$ augmentations

Corollary: $O(V^2)$

Fastest Known Algorithm: King, Rao, Tarjan: $O(VE \log_{E/(V|G|)} V)$ time