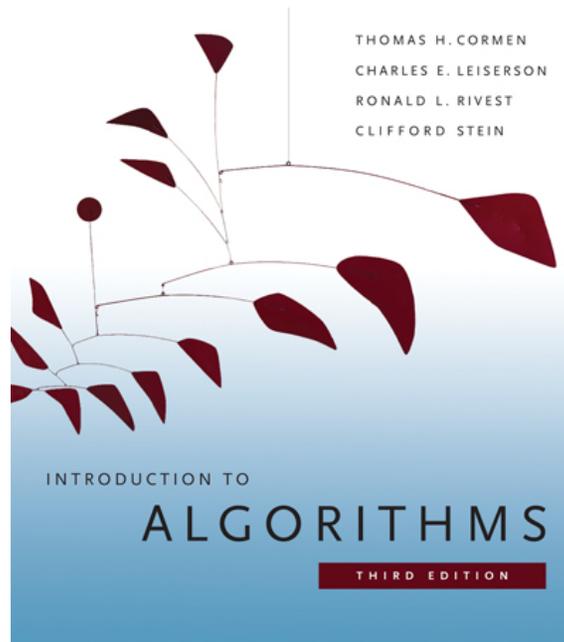


6.006- *Introduction to Algorithms*



Lecture 13

Prof. Constantinos Daskalakis

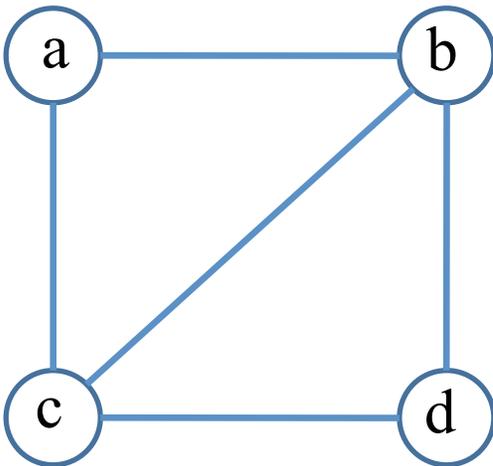
CLRS 22.4-22.5

Graphs

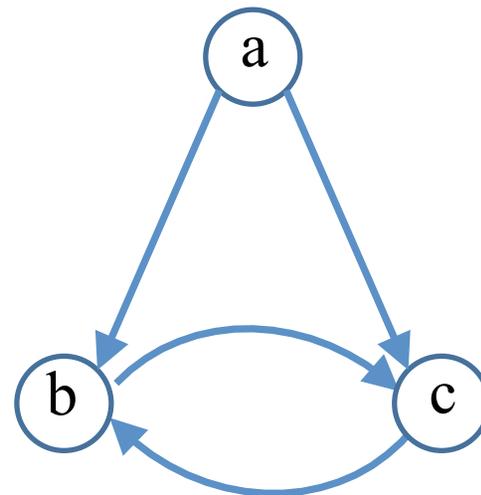
- $G=(V,E)$
- V a set of vertices
 - Usually number denoted by n
- $E \subseteq V \times V$ a set of edges (pairs of vertices)
 - Usually number denoted by m
- Flavors:
 - Pay attention to order of vertices in edge: *directed* graph
 - Ignore order: *undirected* graph

Examples

- *Undirected*
- $V = \{a, b, c, d\}$
- $E = \{\{a, b\}, \{a, c\}, \{b, c\}, \{b, d\}, \{c, d\}\}$



- *Directed*
- $V = \{a, b, c\}$
- $E = \{(a, c), (a, b), (b, c), (c, b)\}$

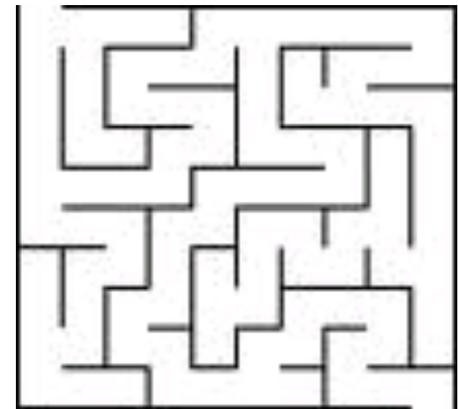


Breadth First Search

- Start with vertex v
- List all its neighbors (distance 1)
- Then all their neighbors (distance 2)
- Etc.

Depth First Search

- Exploring a maze
- From current vertex, move to another
- Until you get stuck
- Then backtrack till you find the first new possibility for exploration



BFS/DFS Algorithm Summary

- Maintain “todo list” of vertices to be scanned
-

- Until list is empty
 - Take a vertex v from front of list
 - Mark it scanned
 - Examine all outgoing edges (v,u)
 - If u not marked, add to the todo list
 - BFS: add to end of todo list (*queue*: **FIFO**)
 - DFS: add to front of todo list (*recursion stack*: **LIFO**)

Queues and Stacks

- BFS queue is explicit
 - Created in pieces
 - (level 0 vertices) . (level 1 vertices) . (level 2 vert...)
 - the frontier at *iteration i* is *piece i* of vertices in queue
- DFS stack is implicit
 - It's the call stack of the python interpreter
 - From v , recurse on one child at a time
 - But same order if put all children on stack, then pull off (and recurse) one at a time

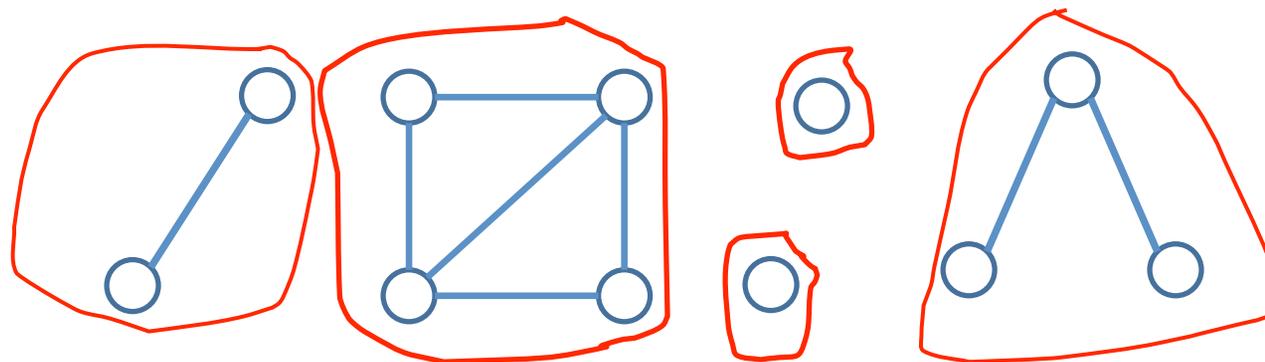
Runtime Summary

- Each vertex scanned once
 - When scanned, marked
 - If marked, not (re)added to todo list
 - Constant work per vertex
 - Removing from queue
 - Marking
 - $O(n)$ total
- Each edge scanned once
 - When tail vertex of edge is scanned
 - Constant work per edge (checking mark on head)
 - $O(m)$ total
- In all, $O(n+m)$

Connected Components

Connected Components

- Undirected graph $G=(V,E)$
- Two vertices are connected if there is a path between them
- An equivalence relation
- Equivalence classes are called components
 - A set of vertices all connected to each other



Algorithm

- DFS/BFS reaches all vertices reachable from starting vertex s
- i.e., component of s
- Mark all those vertices as “owned by” s

Algorithm

- DFS-visit (u, *owner*, o)
 - #mark all nodes reachable from u with owner o
 - for v in Adj[u]
 - if v not in *owner* #not yet seen
 - owner*[v] = o #instead of parent
 - DFS-visit (v, owner, o)
- DFS-Visit(s, owner, s) will mark $owner[v]=s$ for any vertex reachable from s

Algorithm

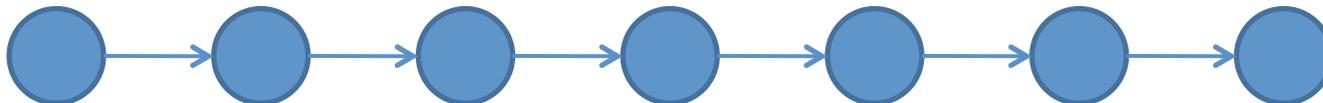
- Find component for s by DFS from s
- So, just search from every vertex to find all components
- Vertices in same component will receive the same ownership labels
- Cost?
 - n times BFS/DFS?
 - ie, $O(n(m+n))$?

Better Algorithm

- If vertex has already been reached, don't need to search from it!
 - Its connected component already marked with owner
- *owner* = {}
for s in V
 if not(s in *owner*)
 DFS-Visit(s, *owner*, s) #or can use BFS
- Now every vertex examined exactly twice
 - Once in outer loop and once in DFS-Visit
- And every edge examined once
 - In DFS-Visit when its tail vertex is examined
- Total runtime to find components is $O(m+n)$

Directed Graphs

- In undirected graphs, connected components can be represented in n space
 - One “owner label” per vertex
- Can ask to compute all vertices reachable from each vertex in a directed graph
 - i.e. the “transitive closure” of the graph
 - Answer can be different for each vertex
 - Explicit representation may be bigger than graph
 - E.g. size n graph with size n^2 transitive closure



Topological Sort

Job Scheduling

- Given
 - A set of tasks
 - Precedence constraints
 - saying “u must be done before v”
 - Represented as a **directed** graph
- Goal:
 - Find an **ordering** of the tasks that satisfies all precedence constraints

Make bus in
seconds flat

Fall out of bed

Drag a comb
across my head

Look up
(at clock)

Find my
coat

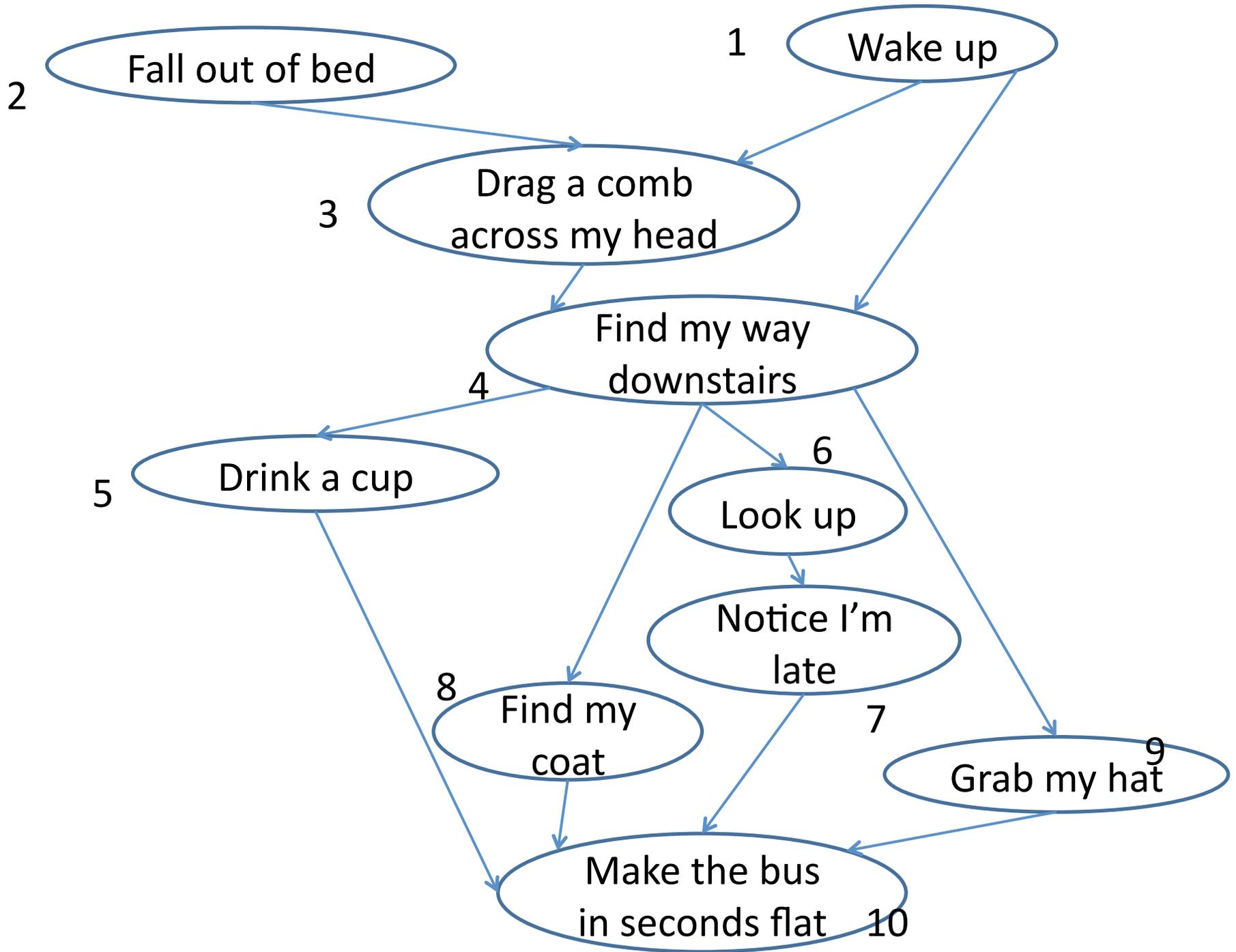
Notice that
I'm late

Drink a cup

Wake up

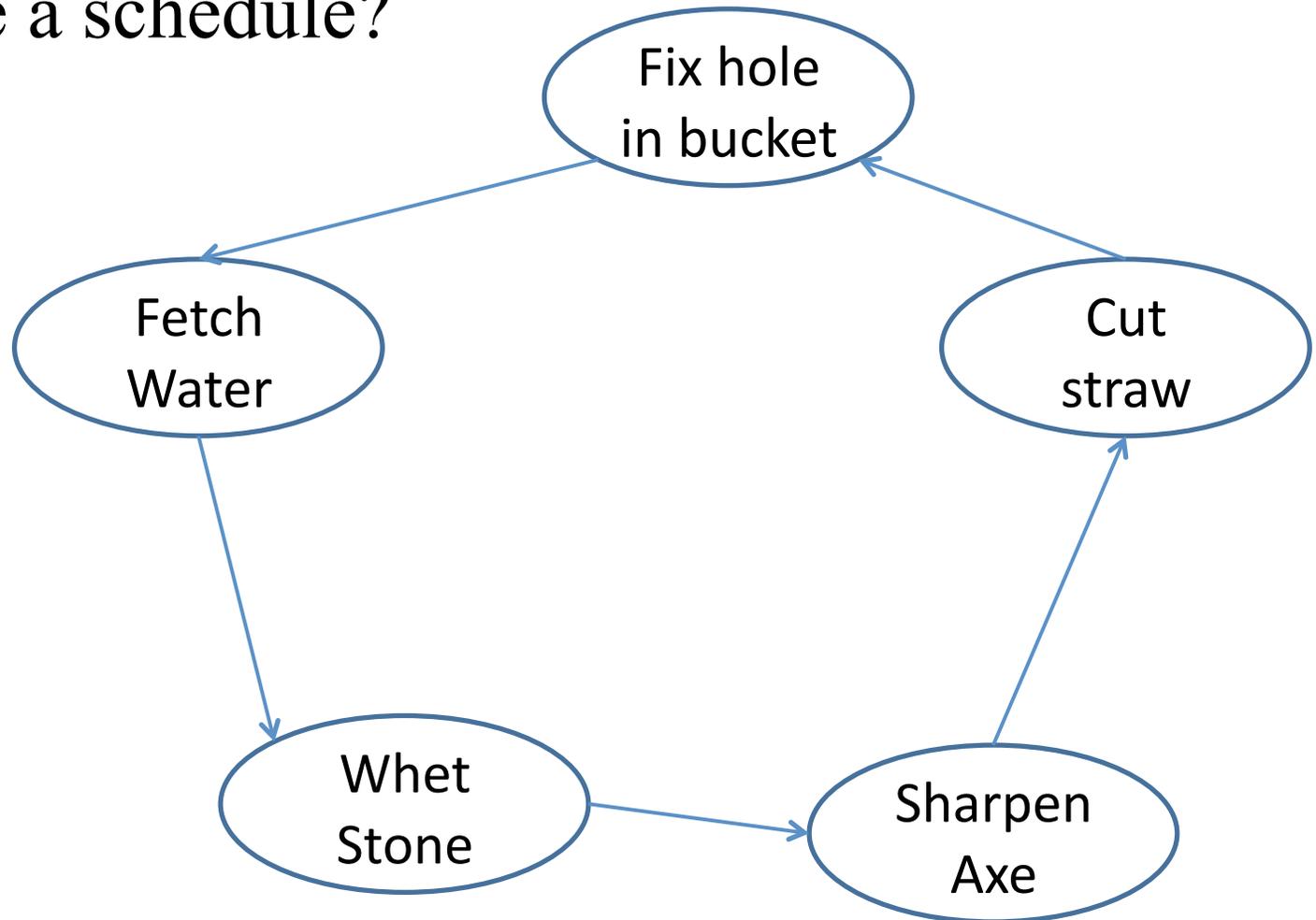
Find my way
downstairs

Grab my hat



Existence

- Is there a schedule?



DAG

- Directed Acyclic Graph
 - Graph with no cycles
- Source: vertex with no incoming edges
- Claim: every DAG has a source
 - Start anywhere, follow edges backwards
 - If never get stuck, must repeat vertex
 - So, get stuck at a source
- Conclude: every DAG has a schedule
 - Find a source, it can go first
 - Remove, schedule rest of work recursively

Algorithm I (for DAGs)

- Find a source
 - Scan vertices to find one with no incoming edges
 - Or use DFS on backwards graph
- Remove, recurse
- Time to find one source
 - $O(m)$ with standard adjacency list representation
 - Scan all edges, count occurrence of every vertex as tail
- Total: $O(nm)$

Algorithm 2 (for DAGs)

- Consider DFS
- Observe that we don't return from recursive call to $\text{DFS}(v)$ until all of v 's children are finished
- So, “finish time” of v is later than finish time of all children
- Thus, later than finish time of all **descendants**
 - i.e., vertices reachable from v
 - Descendants well-defined since no cycles
- So, reverse of finish times is valid schedule

Implementation (of Alg 2)

- *seen* = {}; *finishes* = {}; *time* = 0

DFS-visit (s)

for v in Adj[s]

if v not in *seen*

seen[v] = 1

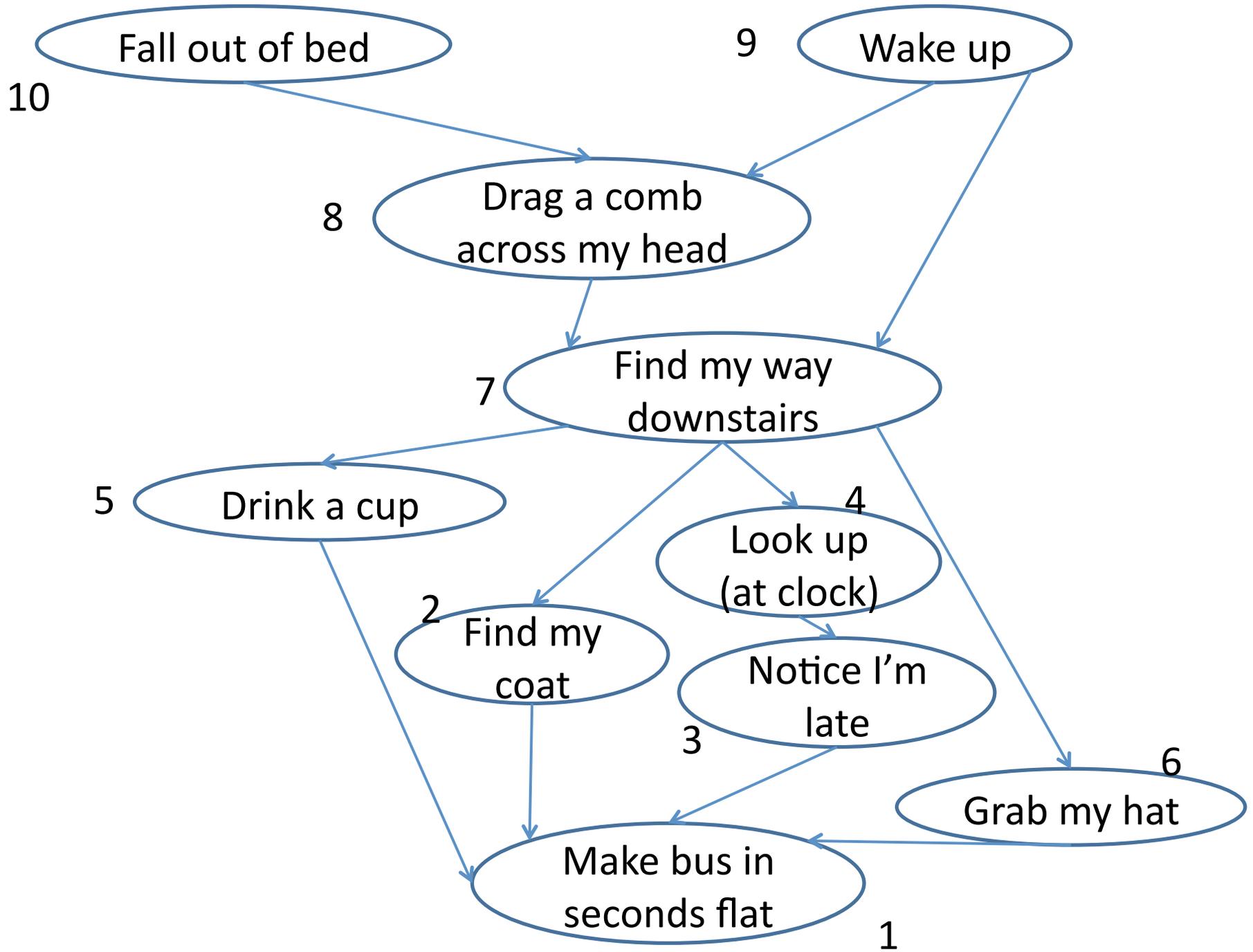
DFS-visit (v)

time = *time*+1

finishes[v] = *time*

*only set finishes if
done processing all
edges leaving v*

- TopologicalSort
for s in V
DFS-visit(s)
- Sort vertices by *finishes*[] key



Analysis

- Just like connected components DFS
 - Time to DFS-Visit from all vertices is $O(m+n)$
 - Because we do nothing with already seen vertices
- Might DFS-visit a vertex v before its ancestor u
 - i.e., start in middle of graph
 - Does this matter?
 - No, because $\text{finish}[v] < \text{finish}[u]$ in that case

Handling Cycles

- If two jobs can reach each other, we must do them at same time
- Two vertices are **strongly connected** if each can reach the other
- Strongly connected is an equivalence relation
 - So graph has **strongly connected components**
- Can we find them?
 - Yes, another nice application of DFS
 - But tricky (see CLRS)
 - You should understand algorithm, not proof