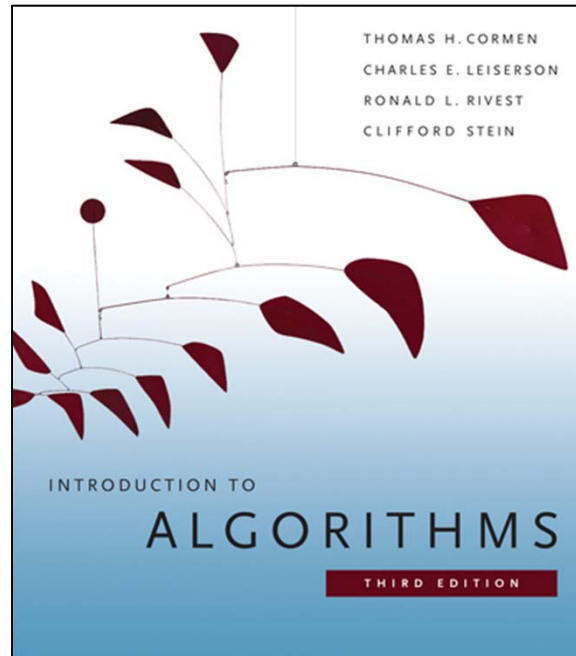


6.006

Introduction to Algorithms



Lecture 15: Shortest Paths II

Prof. Erik Demaine

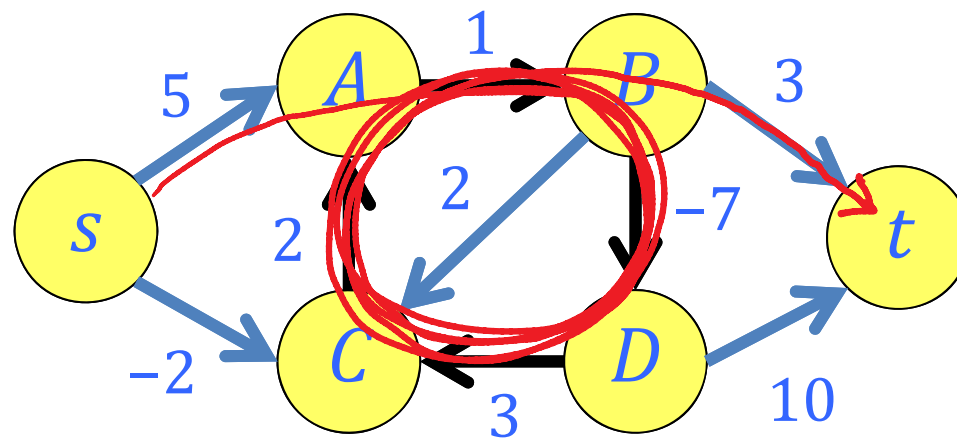
Today

- **Bellman-Ford algorithm**
for single-source shortest paths
- Running time
- Correctness
- Handling negative-weight cycles
- Directed acyclic graphs

Recall: Shortest Paths

- $\delta(u, v) = \inf \{w(p) : p \text{ is a path from } u \text{ to } v\}$
- $\delta(u, v) = \infty$ if there's no path from u to v
- $\delta(u, v) = -\infty$ if there's a path from u to v that visits a negative-weight cycle

Example:

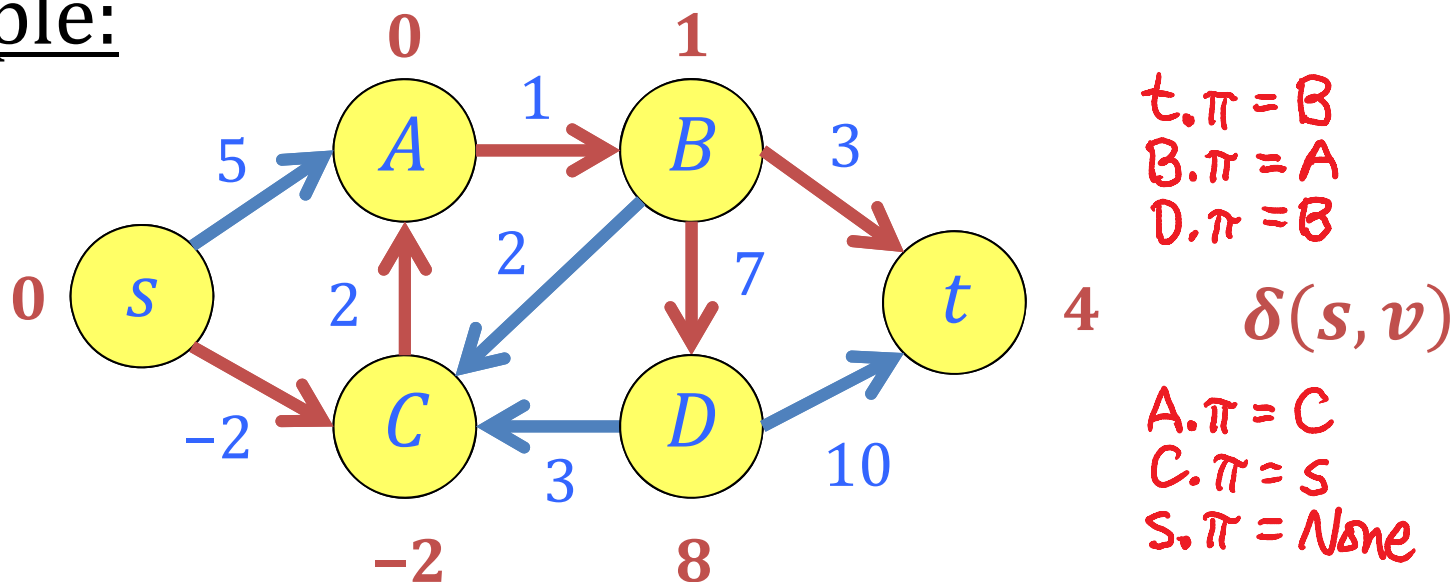


$$\delta(s, t) = -\infty$$

Recall: Single-Source Shortest Paths

- Problem: Given a directed graph $G = (V, E)$ with edge-weight function $w : E \rightarrow \mathbb{R}$, and a **source** vertex s , compute $\delta(s, v)$ for all $v \in V$
 - Also want shortest-path tree represented by $v.\pi$

Example:



Recall: Relaxation Algorithm

for v in V :

$v.d = \infty$

$v.\pi = \text{None}$

$s.d = 0$

while some edge (u, v) has $v.d > u.d + w(u, v)$:

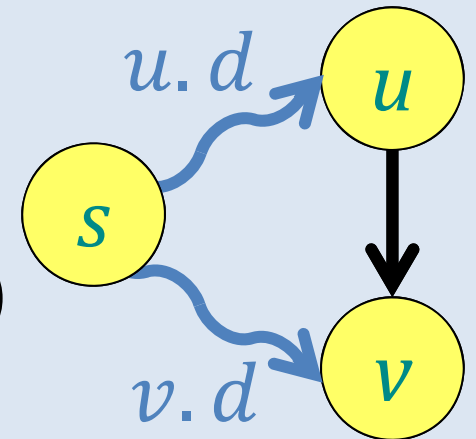
pick such an edge (u, v)

relax (u, v) :

if $v.d > u.d + w(u, v)$:

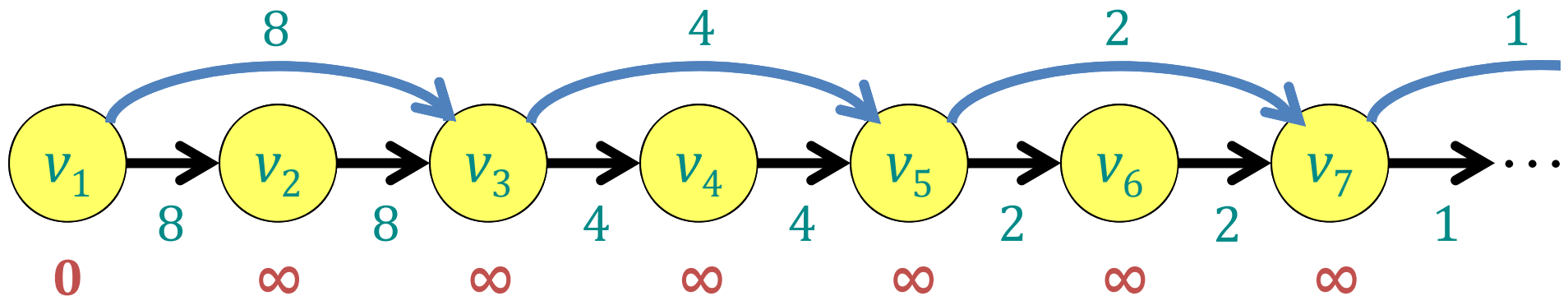
$v.d = u.d + w(u, v)$

$v.\pi = u$



Relaxation Algorithm Issues

- Never stop relaxing in a graph with negative-weight cycles: infinite loop!
- A poor choice of relaxation order can lead to exponentially many relaxations:



Bellman & Ford



Richard E. Bellman
(1920–1984)
IEEE Medal of Honor, 1979

<http://www.amazon.com/Bellman-Continuum-Collection-Works-Richard/dp/9971500906>



Lester R. Ford, Jr.
(1927–)
president of MAA, 1947–48

<http://www.maa.org/aboutmaa/maaapresidents.html>

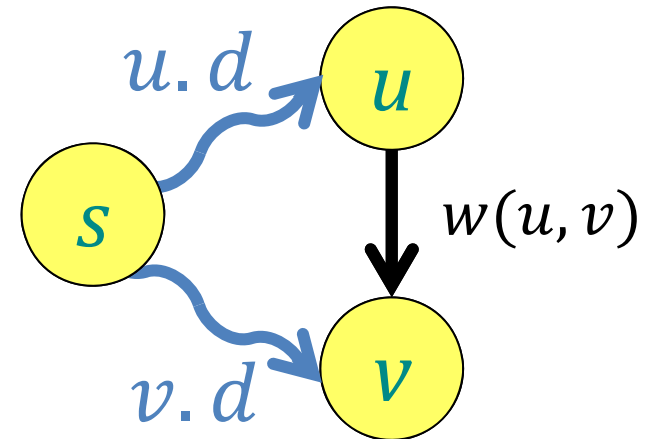
Bellman-Ford Algorithm

- Relaxation algorithm
- “Smart” order of edge relaxations
- Label edges e_1, e_2, \dots, e_m
- Relax in this order:

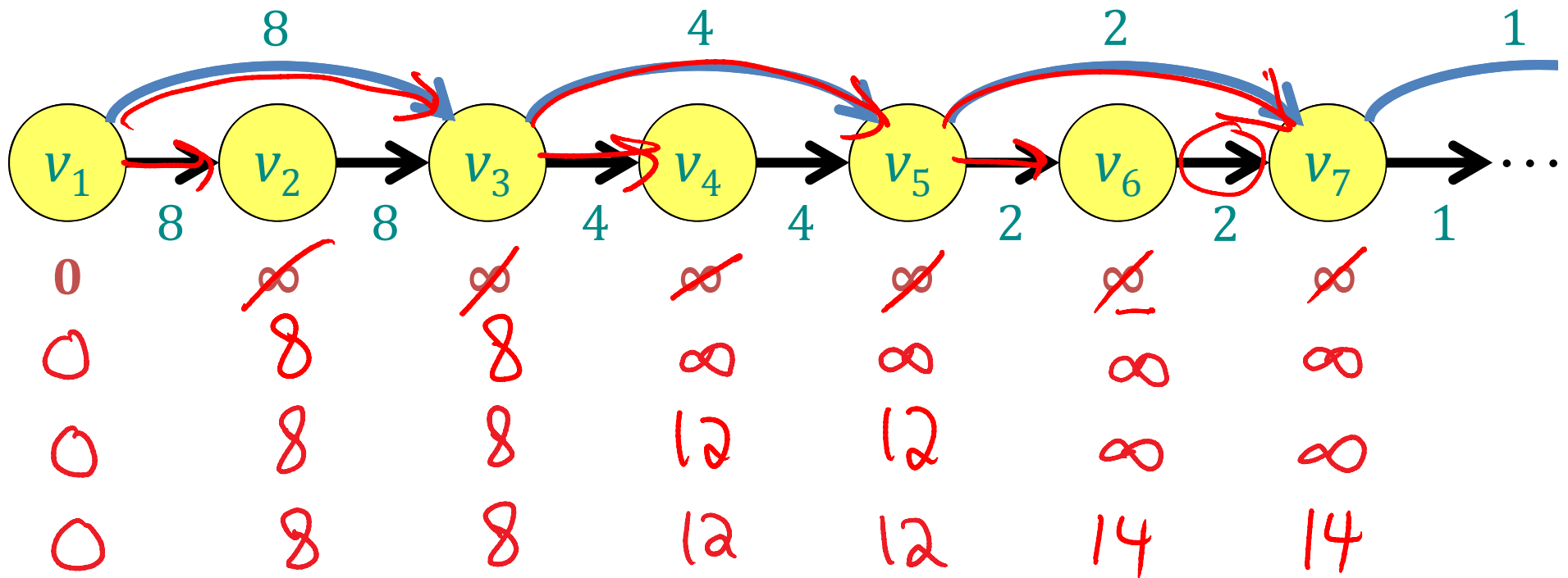
$\underbrace{e_1, e_2, \dots, e_m; e_1, e_2, \dots, e_m; \dots \dots; e_1, e_2, \dots, e_m}_{|V| - 1 \text{ repetitions}}$

Bellman-Ford Algorithm

```
for  $v$  in  $V$ :  
     $v.d = \infty$   
     $v.\pi = \text{None}$   
 $s.d = 0$   
for  $i$  from 1 to  $|V| - 1$ :  
    for  $(u, v)$  in  $E$ :  
        relax( $u, v$ ):  
            if  $v.d > u.d + w(u, v)$ :  
                 $v.d = u.d + w(u, v)$   
                 $v.\pi = u$ 
```

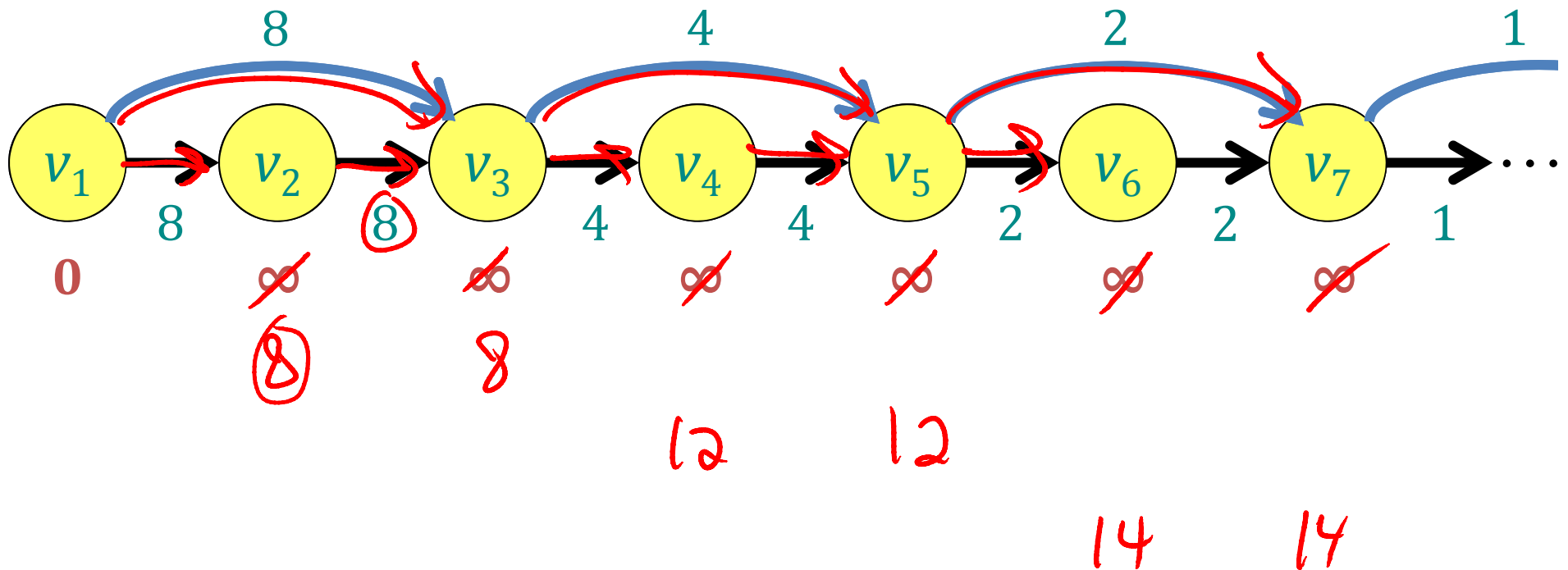


Bellman-Ford Example



edges ordered right to left

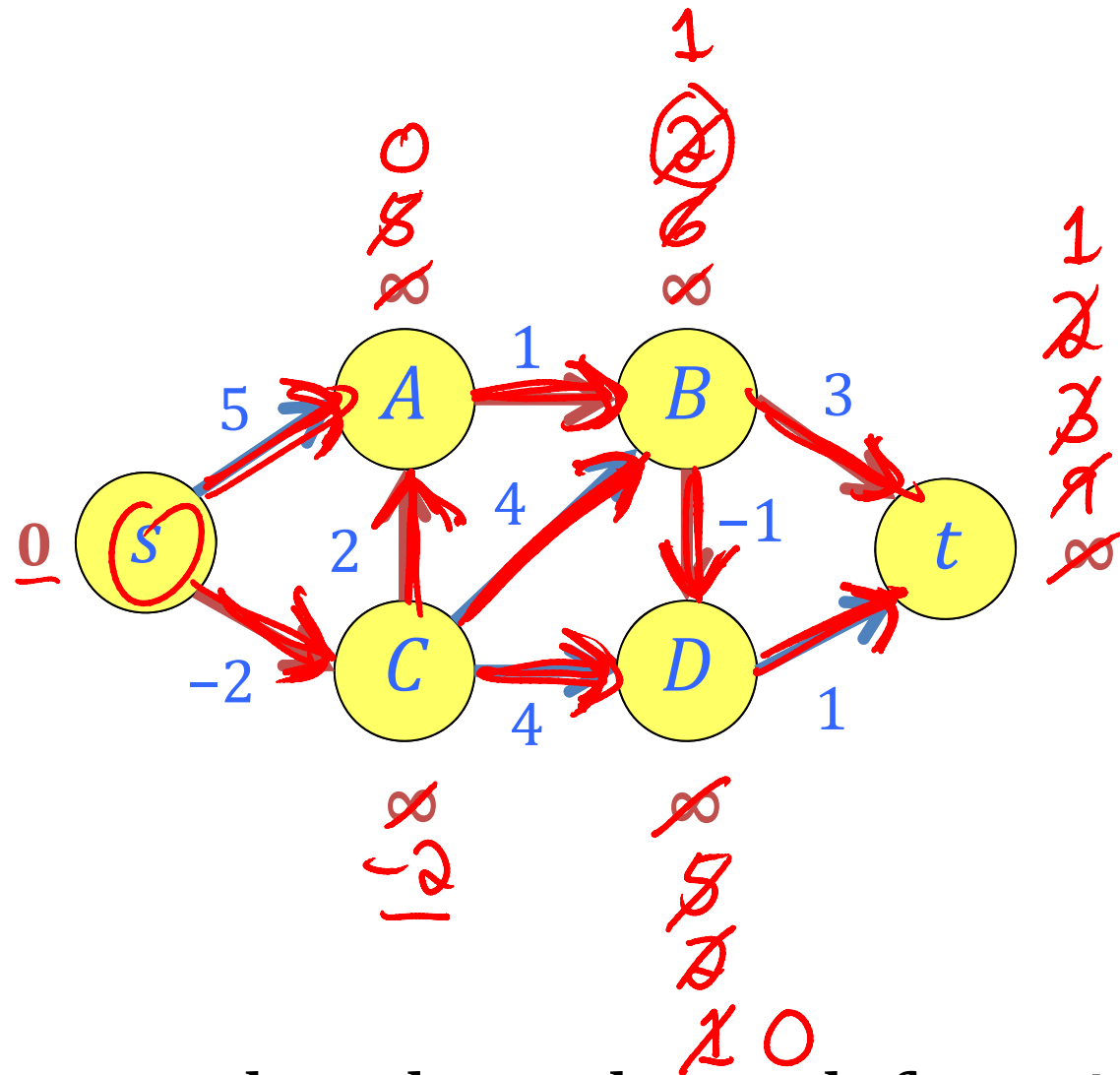
Bellman-Ford Example



one round!

edges ordered left to right

Bellman-Ford Example



edges ordered top down, left to right

Bellman-Ford in Practice

- Distance-vector routing protocol
 - Repeatedly relax edges until convergence
 - Relaxation is local!
- On the Internet:
 - Routing Information Protocol (RIP)
 - Interior Gateway Routing Protocol (IGRP)

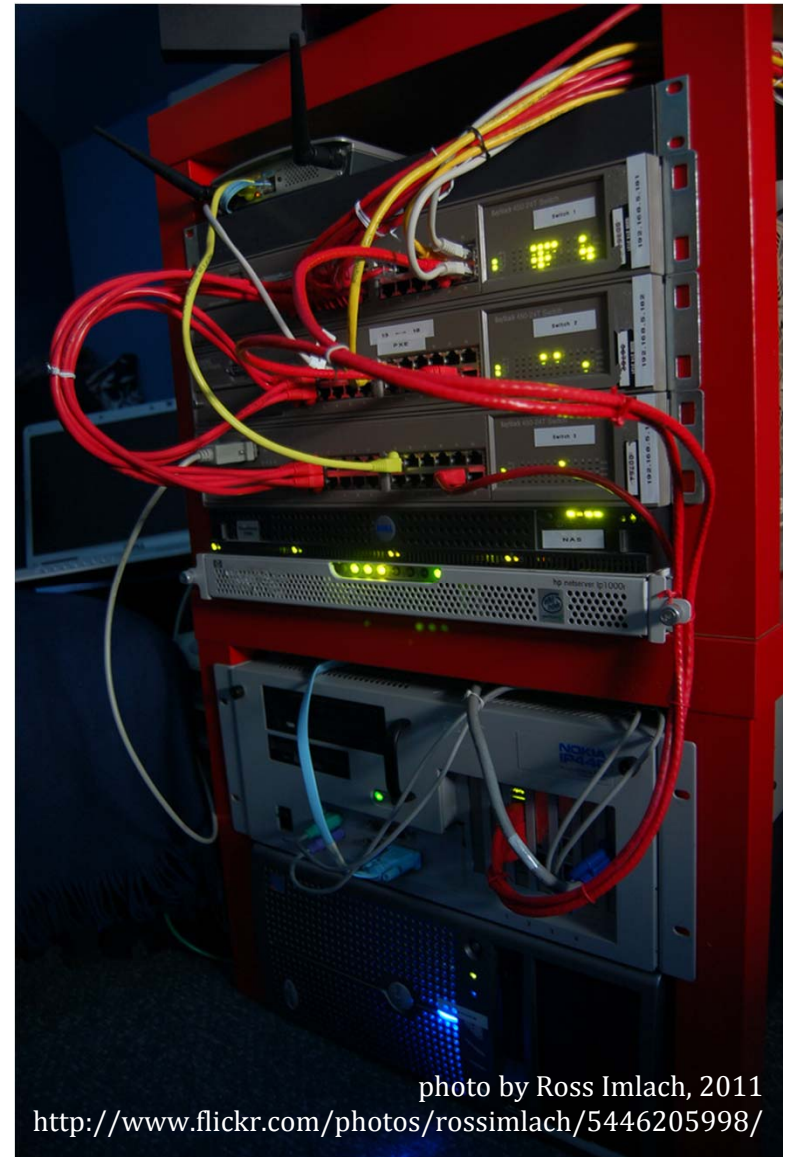
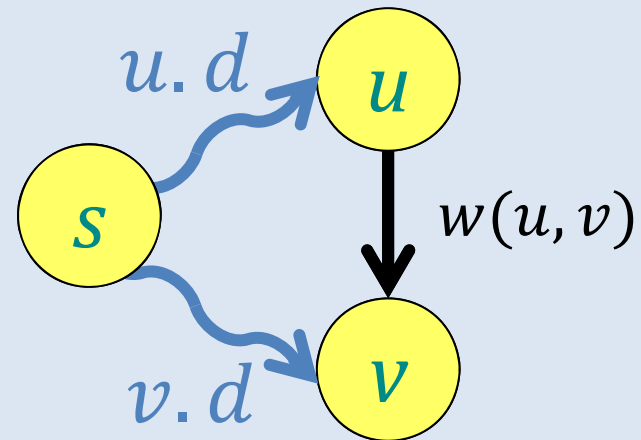


photo by Ross Imlach, 2011
<http://www.flickr.com/photos/rossimlach/5446205998/>

Bellman-Ford Algorithm with Negative-Weight Cycle Detection

```
for  $v$  in  $V$ :  
     $v.d = \infty$   
     $v.\pi = \text{None}$   
 $s.d = 0$   
for  $i$  from 1 to  $|V| - 1$ :  
    for  $(u, v)$  in  $E$ :  
        relax( $u, v$ )  
for  $(u, v)$  in  $E$ :  
    if  $v.d > u.d + w(u, v)$ :  
        report that a negative-weight cycle exists
```



Bellman-Ford Analysis

```
for  $v$  in  $V$ :  
     $v.d = \infty$   
     $v.\pi = \text{None}$   
 $s.d = 0$   
for  $i$  from 1 to  $|V| - 1$ :  
    for  $(u, v)$  in  $E$ :  
        relax( $u, v$ )  
for  $(u, v)$  in  $E$ :  
    if  $v.d > u.d + w(u, v)$ :  
        report that a negative-weight cycle exists
```

TOTAL: $O(VE)$

Handwritten annotations in the image:

- A blue curly brace groups the initialization for v (the first three lines), labeled $O(V)$.
- A green curly brace groups the inner loop (lines 5-6), labeled $O(E)$.
- A blue curly brace groups the outer loop (lines 4-6), labeled $O(VE)$.
- A green curly brace groups the final check loop (lines 7-8), labeled $O(E)$.

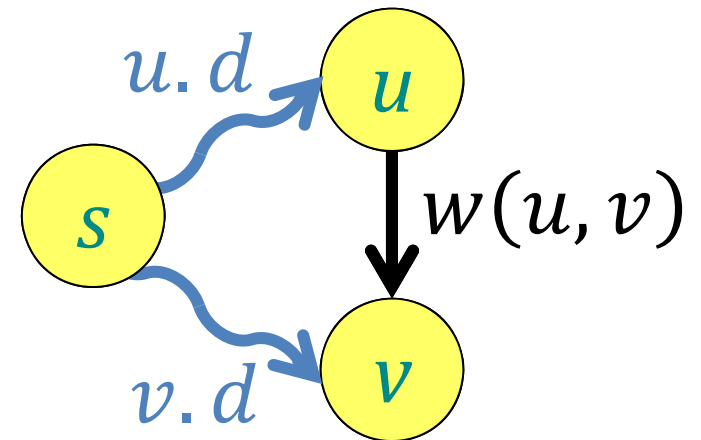
Recall: Relaxing Is Safe

- Lemma: The relaxation algorithm maintains the invariant that $v.d \geq \delta(s, v)$ for all $v \in V$.
- Proof: By induction on the number of steps.

- Consider $\text{relax}(u, v)$
- By induction, $u.d \geq \delta(s, u)$
- By triangle inequality,

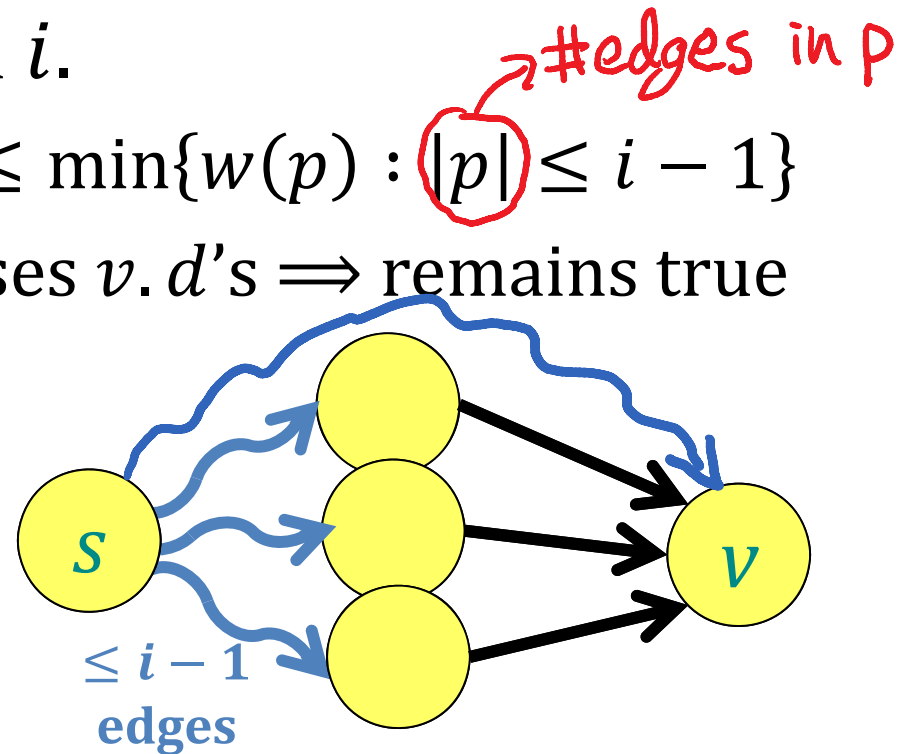
$$\begin{aligned}\delta(s, v) &\leq \delta(s, u) + \delta(u, v) \\ &\leq u.d + w(u, v)\end{aligned}$$

- So setting $v.d = u.d + w(u, v)$ is “safe” ■



Bellman-Ford Correctness

- Claim: After iteration i of Bellman-Ford, $v.d$ is at most the weight of every path from s to v using at most i edges, for all $v \in V$.
- Proof: By induction on i .
 - Before iteration i , $v.d \leq \min\{w(p) : |p| \leq i - 1\}$
 - Relaxation only decreases $v.d$'s \Rightarrow remains true
 - Iteration i considers all paths with $\leq i$ edges when relaxing v 's incoming edges ■



Bellman-Ford Correctness

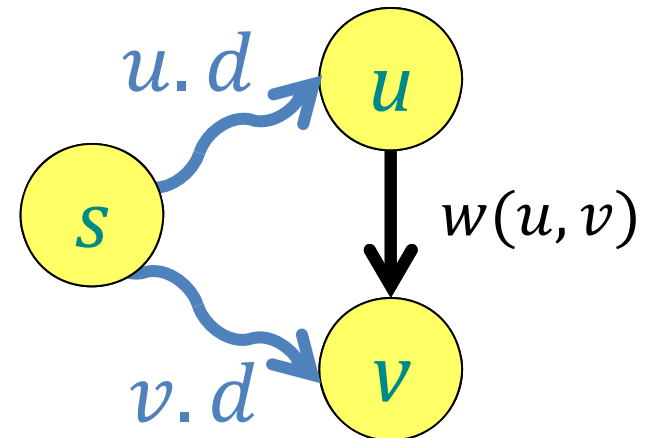
- Theorem: If $G = (V, E, w)$ has no negative-weight cycles, then at the end of Bellman-Ford, $v.d = \delta(s, v)$ for all $v \in V$.
- Proof:
 - Without negative-weight cycles, shortest paths are always simple
 - Every simple path has $\leq |V|$ vertices, so $\leq |V| - 1$ edges
 - Claim $\Rightarrow |V| - 1$ iterations make $v.d \leq \delta(s, v)$
 - Safety $\Rightarrow v.d \geq \delta(s, v)$ ■

Bellman-Ford Correctness

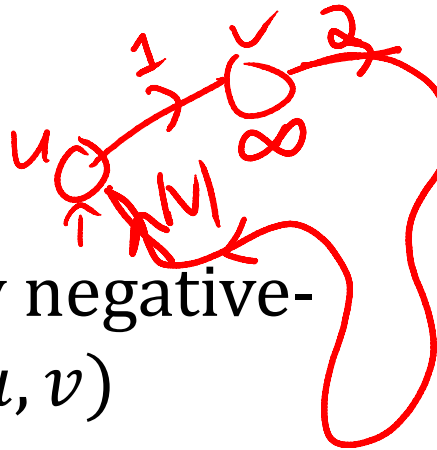
- Theorem: Bellman-Ford correctly reports negative-weight cycles reachable from s .
- Proof:
 - If no negative-weight cycle, then previous theorem implies $v.d = \delta(s, v)$, and by triangle inequality, $\delta(s, v) \leq \delta(s, u) + w(u, v)$, so Bellman-Ford won't incorrectly report a negative-weight cycle.
 - If there's a negative-weight cycle, then one of its edges can always be relaxed (once one of its d values becomes finite), so Bellman-Ford reports. ■

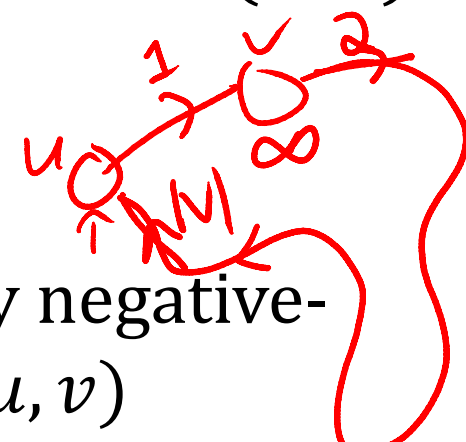
Computing $\delta(s, v)$

```
for  $v$  in  $V$ :  
     $v.d = \infty$   
     $v.\pi = \text{None}$   
 $s.d = 0$   
for  $i$  from 1 to  $|V| - 1$ :  
    for  $(u, v)$  in  $E$ :  
        relax( $u, v$ )  
for  $j$  from 1 to  $|V|$ :  
    for  $(u, v)$  in  $E$ :  
        if  $v.d > u.d + w(u, v)$ :  
             $v.d = -\infty$   
             $v.\pi = u$ 
```

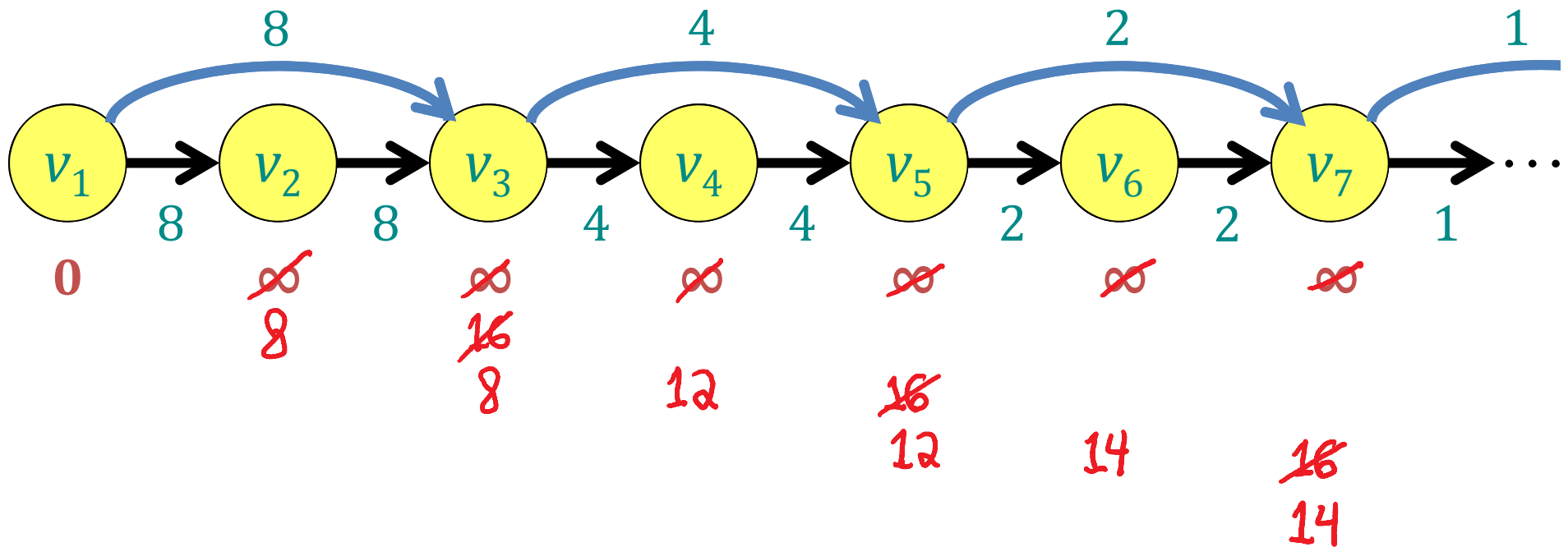


Correctness of $\delta(s, v)$

- Theorem: After the algorithm, $v.d = \delta(s, v)$ for all $v \in V$.
 - Proof:
 - As argued before, after i loop, every negative-weight cycle has a relaxable edge (u, v)
 - Setting $v.d = -\infty$ takes limit of relaxation
 - All reachable nodes also have $\delta(s, x) = -\infty$
 - Path from original u to any vertex x (including u) with $\delta(s, x) = -\infty$ has at most $|V|$ edges
 - (So relaxation is impossible after j loop.) ■
- 



Why Did This Work So Well?



- It's a **DAG** (directed acyclic graph)
- We followed a **topological sorted order**

edges ordered left to right

Shortest Paths in a DAG

- Simplified Bellman-Ford: no iteration, no cycles

for v in V :

$v.d = \infty$

$v.\pi = \text{None}$

$s.d = 0$

topologically sort the vertices V

now $(u, v) \in E \implies \text{rank}(u) < \text{rank}(v)$ in V

for u in V : (in order)

for v in u .neighbors:

relax(u, v)

$O(V)$

$O(V+E)$

$O(E)$

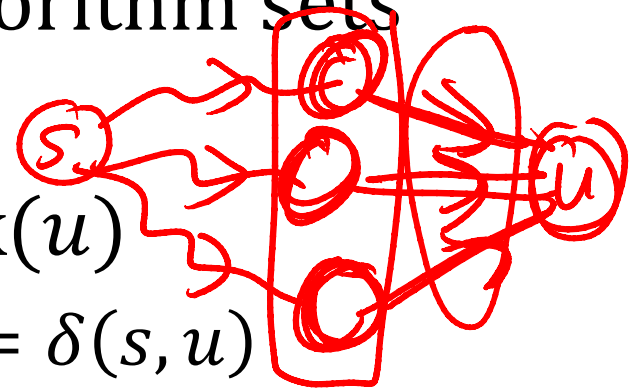
$O(1)$

Correctness in DAG

- Theorem: In a DAG, this algorithm sets $u.d = \delta(s, u)$ for all $u \in V$.

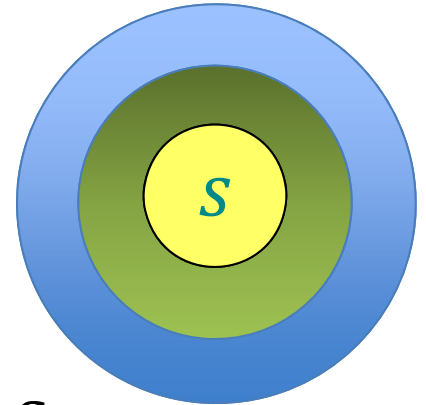
- Proof: By induction on $\text{rank}(u)$

- Claim by induction that $u.d = \delta(s, u)$ when we hit u in outer loop
- Base case: $s.d = 0$ correct (no cycles)
- When we hit u , we've already hit all previous vertices, including all vertices with edges into u
- By induction, these vertices had correct d values when we relaxed the edges into u ■



→ other base cases have $d = \infty$

Next Up



- **Dijkstra's algorithm**
 - Relax edges in a growing ball around s
 - Fast: nearly linear time
 - Only one pass through edges, but need logarithmic time to pick next edge to relax
 - Doesn't work with negative edge weights