

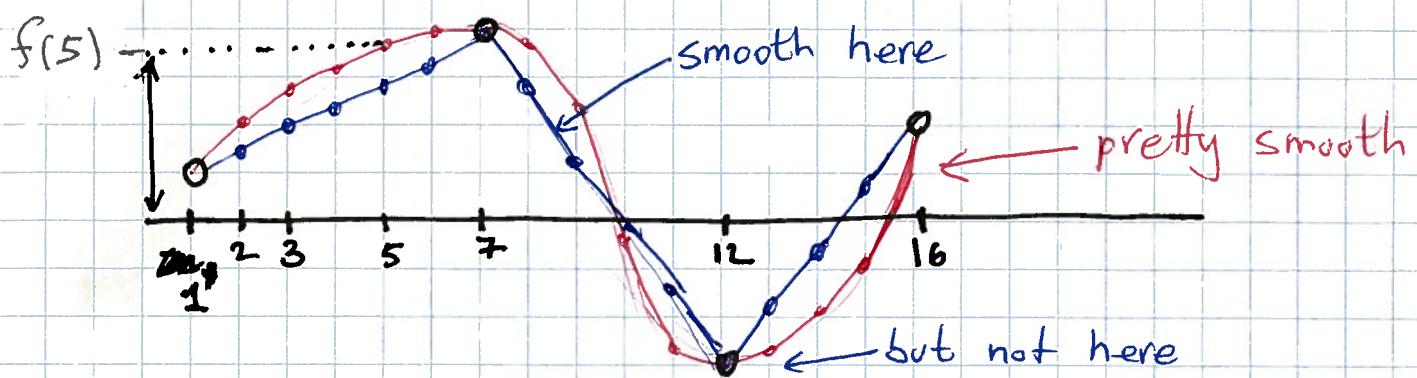
6.006 Lecture 24: Linear Equations & Least Squares

- Creating smooth meshes
- Soft and hard ~~constraint~~ constraints
- Linear least squares
- Matrix representation & upper triangular form

CLRS Ch. 28 covers this lecture & thursday's, but using a more complex and less accurate algorithm.

Reconstructing Smooth Functions

We want to find the smoothest piecewise linear function that satisfies $f(1) = 1$, $f(7) = 4$, $f(12) = -3$, $f(16) = 2$ (or any constraints of this type)



We will model smooth as " $\frac{f_{k+1}}{f_k}$ " is close to the average of $f(k-1)$ and $f(k+1)$ ".

$$\text{f(2)} \approx \frac{f(1) + f(3)}{2} \rightarrow -f(1) + 2f(2) - f(3) \approx 0$$

$$f(3) \approx \frac{f(2) + f(4)}{2} \rightarrow -f(2) + 2f(3) - f(4) \approx 0$$

we know $f(7)$ but want smoothness $\rightarrow f(7) \approx \frac{f(6) + f(8)}{2}$ \vdots "soft" smoothness constraints we have more constraints than unknowns.

$$f(1) = 1$$

$$f(7) = 4$$

$$f(12) = -3$$

$$f(16) = 2$$

"hard" equality constraints

Types of systems of linear equations

$$\begin{array}{l} x_1 + x_2 = 2 \\ x_2 = 1 \end{array} \left. \begin{array}{l} \text{consistent \&} \\ \text{determines all} \\ \text{unknowns} \end{array} \right\} \begin{array}{l} \text{overdetermined \&} \\ \text{inconsistent} \end{array}$$

$x_1 = 1$

$$\begin{array}{l} x_1 + x_2 + x_3 = 3 \\ x_2 + x_3 = 7 \\ x_1 + 2x_2 + 2x_3 = 10 \end{array} \left. \begin{array}{l} \text{underdetermined} \\ \text{still} \\ \text{underdetermined!} \end{array} \right\}$$

overdetermined systems are useful: just write down all the equations you know to be true, or even hope to make true.
 just

- We substitute the known $f(k)$'s to eliminate them:

$$\begin{aligned} -f(1) + 2f(2) - f(3) &\approx 0 \\ -1 + 2f(2) - f(3) &\approx 0 \end{aligned} \quad \begin{aligned} f(1) = 1 \\ 2f(2) - f(3) \approx 1 \end{aligned}$$

- We can't satisfy all the constraints (too many), but we can try to minimize the discrepancy

$$r_1 = 2f(2) - f(3) - 1$$

$$r_2 = -f(2) + 2f(3) - f(4) - 0$$

:

- We bring the problem to a standard form by labeling the unknowns x_1, \dots, x_n , the constants b_1, \dots, b_m ($m = \# \text{constraints}$) and the coefficients $a_{11}, \dots, a_{1n}, a_{21}, \dots, a_{2n}, \dots, a_{mn}$.

$$x_1 = f(2) \dots x_5 = f(6), x_6 = f(8) \dots x_{12} = f(15)$$

$$b_1 = 1, b_2 = 0, b_3 = 0, \dots$$

~~$a_{11} = 2 \quad a_{12} = -1 \quad a_{13} = 0 \dots n = 0$~~

~~$a_{21} = -1 \quad a_{22} = 2 \quad a_{23} = -1 \quad a_{24} = 0 \dots n = 0$~~

- Next, we'll see how to minimize the r_i 's for any a_{ij} 's and b_i 's.

Linear Least Squares Problems

- We need to minimize

$$r_1 = a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n - b_1$$

$$r_2 = a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n - b_2$$

⋮

$$r_n = a_{n1}x_1 + a_{n2}x_2 + \dots + a_{nn}x_n - b_n$$

⋮

$$r_m = a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n - b_m$$

by assigning values to the x_j 's (unknowns).

- Matrix notation

$$\begin{bmatrix} r_1 \\ \vdots \\ r_n \\ \vdots \\ r_m \end{bmatrix} = \begin{bmatrix} \sum_j a_{1j}x_j \\ \vdots \\ \sum_j a_{nj}x_j \\ \vdots \\ \sum_j a_{mj}x_j \end{bmatrix} - \begin{bmatrix} b_1 \\ \vdots \\ b_n \\ \vdots \\ b_m \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ \vdots & \vdots & & \vdots \\ a_{n1} & \dots & \dots & a_{nn} \\ \vdots & & & \vdots \\ a_{m1} & \dots & \dots & a_{mn} \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \\ \vdots \\ x_m \end{bmatrix} - \begin{bmatrix} b_1 \\ \vdots \\ b_n \\ \vdots \\ b_m \end{bmatrix}$$

r

Ax

b

A

x

or simply $Ax - b$

- How to measure how small is a vector $r = Ax - b$ with many components? Possible answers:

- max; $|r_i|$

- $\sum_i r_i^2$ ← easy to minimize & sensible with respect to a few large r_i 's.

- $\sum_i |r_i|$

least squares

- One solution strategy is to find a solution assuming that A has a specific pattern of zeros and non-zeros, and then to find an algorithm to transform any A to this pattern (There is really only one other strategy; not in 6.006).

Consider the following structure:

$$a_{11}x_1 + a_{12}x_2 + a_{13}x_3 + \dots + a_{1n}x_n = b_1$$

$$0x_1 + a_{21}x_2 + a_{23}x_3 + \dots + a_{2n}x_n = b_2$$

$$0x_1 + 0x_2 + a_{33}x_3 + \dots + a_{3n}x_n = b_3$$

⋮

$$0x_1 + 0x_2 + 0x_3 + \dots + a_{nn}x_n = b_n$$

$$0x_1 + 0x_2 + 0x_3 + \dots + 0x_n = b_{n+1}$$

⋮

$$0x_1 + 0x_2 + 0x_3 + \dots + 0x_n = b_m$$

- Clearly, $r_{n+1} = b_{n+1}, \dots, r_m = b_m$ no matter how we set the x_j 's.

- We can usually make all the other r_i 's zero.

Set $x_n = \frac{b_n}{a_{nn}}$ so $r_n = 0$ (we ignore for now the case $a_{nn} = 0$).

Now substitute x_n in the other expressions

$$x_{n-1} = \frac{b_{n-1} - a_{n-1,n}x_n}{a_{n-1,n-1}} \leftarrow \text{now known}$$