

Problem Set 2, Part b

Due: Wednesday, March 15, 2006

Problem sets will be collected in class. Please hand in each problem on a separate page, with your name on it.

Reading

Time sync Fan, Lynch: Gradient clock sync

Attiya, Hay, Welch: Optimal clock sync paper

Topology control Li, *et. al*: Cone-based topology control algorithm

Bahramgiri *et. al*: Fault tolerant distributed topology control algorithm

Reading for next week

Local infrastructure Chockler *et. al*: Consensus and collision detector

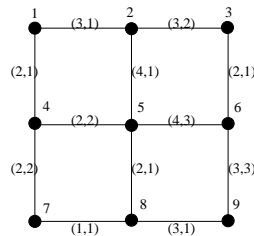
Broadcast Kowalski, Pelc: Deterministic broadcasting paper

Bar-Yehuda *et. al*: Time complexity of broadcast

Bar-Yehuda *et. al*: Efficient emulation of single-hop radio network

Problems

1. Consider the lower bound in the gradient clock synchronization paper.
 - (a) Outline the design of a simple clock synchronization protocol, for the setting described in the paper.
 - (b) Now construct a “bad execution”, in which a large clock skew is produced between two adjacent nodes. Try to make the skew as large as possible (try for $\Omega(D)$). You may use the strategy described in the lower bound proof, or any other strategy you like, in trying to devise your bad execution.
2. Consider the 9-node undirected grid graph depicted below. Each label (d, u) on an edge represent the average delay d and uncertainty u , as in the Attiya, Hay, Welch paper.



Assume that nodes 1 and 9 are source nodes.

- (a) Give a “shallow forest” satisfying the optimality constraint given in the paper.

- (b) What are the upper bounds on clock skew for the 9 nodes that arise from your shallow forest?
 - (c) For node 5, describe an actual execution of the algorithm of the paper (the one that precomputes the tree is fine) in which the upper bound you determined for 5 is actually attained.
3. The proof of Theorem 8 in the BHM paper is nice, simple, and short. Can you give a similar proof for Theorem 3.2 of LH?
 4. The algorithms considered in LH and BHM are of a very particular kind: they use local information only, and depend on the same fixed α everywhere. We can consider what might happen if these rules were loosened.
 - (a) Draw a graph G in the Euclidean plane with the property that the actual connectivity of the graph G_{α}^{-} , where $\alpha = \frac{5\pi}{6}$, is much greater than 1.
 - (b) Now suppose that the processes at the nodes of your graph know the entire graph, and can use this knowledge to determine their power levels. Is there a way they can set their power levels to be much smaller than what would arise from the LH algorithm, yet still preserve connectivity?