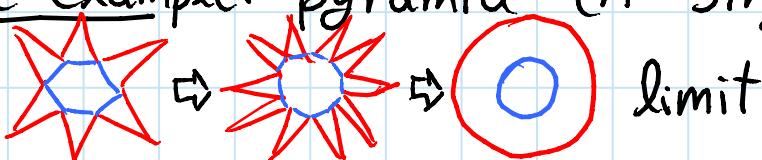


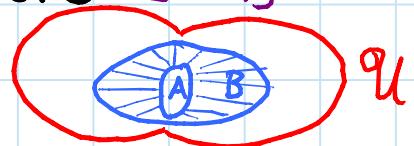
Unfolding smooth prisms: [Benbernou, Cahn, O'Rourke 2004]

- convex hull of two parallel smooth convex shapes

- keep bottom B , unroll side ribs, place top A (how?)
- simple example: pyramid ($A = \text{single point}$)



- surface area not preserved (unlike regular unfolding)
- like source unfolding of sphere [L14]



① Flat polyhedron & $A \subseteq B$

- parameterize ribs as $(a(t), b(t))$, $0 \leq t < 1$
- convexity of A & $B \Rightarrow$ tangents $\dot{a}(t)$, $\dot{b}(t)$ turn right as t increases (clockwise param.)
- also, tangents $\dot{a}(t)$ & $\dot{b}(t)$ are parallel
(discrete analog: faces of prismatoid are trapezoids)
- unfolded A : $u(t) = a(t)$ reflected thru $b(t)$

Lemma: unfolded ribs don't intersect

Proof: consider (b_1, u_1) vs. (b_2, u_2) . [$x_i = x(t_i)$]

- assume by rotation that \dot{a}_1 is horizontal

- assume by reflection that a_2 is right of a_1

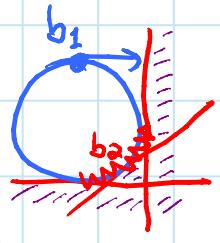
(- ditto for b_1 & b_2)



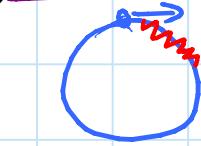
Unfolding smooth prisms: (Cont'd)

Case (a): a_2 in bottom-right quarter

- (b_2, u_2) is on outside of tangent b_2
- $A \subseteq B \Rightarrow a_2$ is left of red region
- b_1 horizontal $\Rightarrow u_2$ is left of red region
- $\Rightarrow (b_1, u_1)$ not in outside region

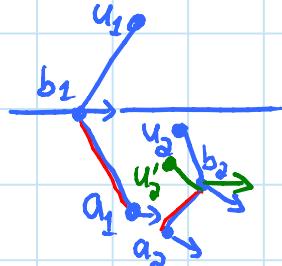


Case (b): a_2 in top-right quarter



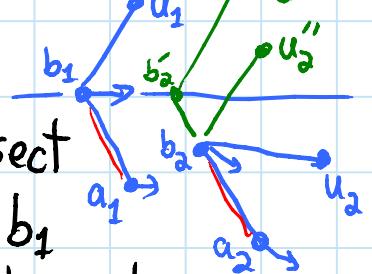
Subcase (i): rib (a_i, b_i) slopes have opposite signs

- a_1 is left of a_2
- $\Rightarrow u_1$ (straight above a_1) is left of reflection u'_2 of a_2 thru horizontal thru b_2
- rotating horizontal to true b_2 rotates u_2 clockwise \Rightarrow away from u_1



Subcase (ii): same signs

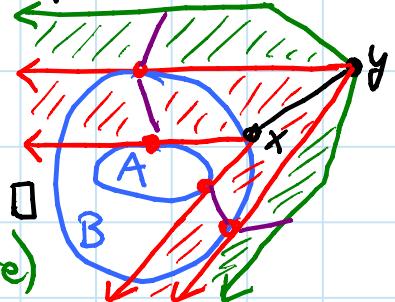
- $(a_1, b_1) \& (a_2, b_2)$ don't intersect
- \Rightarrow horizontal reflections thru b_1 (b_1, u_1) & (b'_2, u'_2) don't intersect
- $\Rightarrow (b_1, u_1)$ doesn't intersect reflection (b_2, u''_2) of (a_2, b_2) thru horiz. line thru b_2
 - translate rightward & shrink length
 - rotate clockwise to true b_2 as before \square



Unfolding smooth prismatoids: (cont'd)

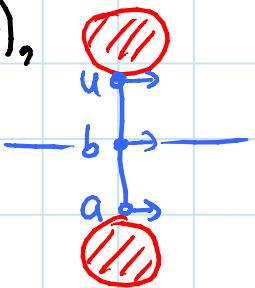
Simpler proof of rib lemma: [NEW - Matt Ince]

- extend \vec{a}_1, \vec{a}_2 till intersection point x
- extend \vec{b}_1, \vec{b}_2 till intersection point y
- xy divides red wedge into two regions, one per rib
- reflections disjoint by convexity \square
(positive curvature)



Mutual tangency: if top attaches at $a(t)$,
locally avoid overlap

- $\Leftrightarrow \dot{a}(t)$ is parallel to $\dot{u}(t)$
- maximize $|a(t) - u(t)|$
 \Rightarrow mutual tangency
& $u(t)$ on convex hull of U
 \Rightarrow global nonoverlap



② Flat polyhedron, A & B arbitrary

- argue max. $|a(t) - b(t)|$ still mutual tangency

③ Nonflat polyhedron

- show "easier": rounded out more
- more algebra

OPEN: edge unfolding of polyhedral prismatoids?

Flexible polyhedra: (rigid faces & hinged edges)

Convex polyhedra are rigid:

- Cauchy's Rigidity Theorem \Rightarrow any motion must make polyhedron nonconvex
- can't happen immediately (if no flat edges)
- in fact, convex polyhedra are (second-order) rigid with finitely many creases (flat edges) [Connelly 1980]

Square-bottom paper bag: contrasting example

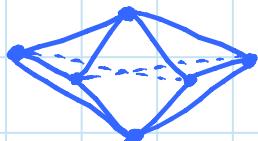
(convex, with boundary) [Balkcom, Demaine, Demaine 2004]

- rigid with usual creases
- flattenable with additional creases

Generic/almost all triangulated polyhedra are infinitesimally rigid [Gluck 1986; Euler 1766 conjecture]

Flexible nonconvex polyhedra exist nonetheless:

- Bricard "octahedron" [~1900]
 - self-intersecting (more of linkage)
- Connelly polyhedron [1978]
 - modification to avoid self-intersection
 - 30 faces, 50 edges, 22 vertices
- Steffen's polyhedron [Klaus Steffen]
 - simplification with 14 triangles, 9 vertices
 - need ≥ 9 vertices \Rightarrow optimal



Flexible polyhedra: (cont'd)

Bellows Theorem: [Connelly, Sabitov, Walz 1997]

volume remains constant during any flex of a nonconvex polyhedron

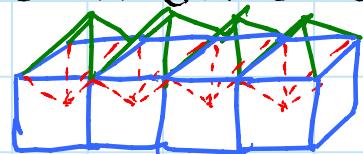
Volume polynomials: [Sabitov 1996; Astrelin & Sabitov 1999]

volume of a polyhedron is a root of a polynomial $p(x)$ determined by just combinatorial structure & face geometries

⇒ constant during continuous motion (finite set)

— degree must be exponential:

— Each house can pop in or out



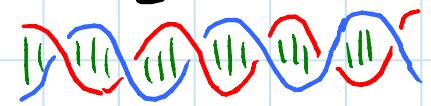
— degree $\leq 2^{\# \text{edges}}$ [Fedorchuk & Pak 2004]

— true even for generalized (self-intersecting) polyhedra: volume = sum of signed volumes of tetrahedra from (any) point

Protein folding: some biochemistry background

DNA (Deoxyribonucleic Acid)

- genetic information in every cell & many viruses
- essentially a string over alphabet {A, C, G, T}
 - Adenine
 - Cytosine
 - Guanine
 - Thymine
- geometrically, two complementary strings woven together in double helix [Watson & Crick 1953]



RNA (Ribonucleic Acid)

- similar but (usually) one strand & T → U (Uracil)
- short-term "DNA" for transfer out of cell

Protein: fundamental building block of life

- form enzymes, cytoskeleton, antibodies, etc.
- essentially chain of amino acids (20 kinds)
- translated from (portions of) RNA/DNA by genetic code: by triples of acids
 - AUG & GUG: "start"
 - UAG, UGA, UAA: "stop"
 - AUG → Methionine (also)
 - UGG → Tryptophan
 - CGG, CGC, CGA, CGG, AGA, AGG → Arginine
 - UUA, UUG, CUU, CUC, CUA, CUG → Leucine
 - UCU, UCC, UCA, UCG, AGU, AGC → Serine
 - ...
- { Nirenberg, Mathaei, & Leder by 1965 }
- { codes }
- { uniques }
- { most popular }

Protein folding: proteins fold into 3D structure

- quickly (milliseconds to seconds)
- fairly consistently... but how?
- influenced by ribosome & chaperones

Motivation: geometry strongly influences function

- protein misfolding correlated with several diseases: mad cow, Alzheimer's, cystic fibrosis, cancer
- synthetic protein design (drug design)

Two aspects:

① mechanics: linkages, geometry, algorithms

- how might protein fold
- "relatively tractable"

② energetics: modeling, simulation, optimization

- problems less clearly specified
- thermodynamics hypothesis: protein globally minimizes free-energy function
 - which energy function?
 - really global? simplest models NP-hard