

Admin:

Quizzes graded soon (tonight)

Project: meet with TAs this week

presentations start May 6th (two weeks)

Today:

Elliptic Curves

Bilinear Maps

BLS signatures

Elliptic Curves

- finite group (analogous to \mathbb{Z}_p^*)

- why?

- DL problem seems harder (exponential)
Thus can use shorter reps
(256 bits instead of 2048)

- Can (sometimes) define bilinear maps
on them, which are very cool

- why not?

- new math (?) (not really...)

- computing size of group takes some
work

$$|\mathbb{Z}_p^*| = p-1$$

$$|E_{ab}| \in [p+1-2\sqrt{p}, p+1+2\sqrt{p}]$$

(Schoof's alg)

- Curve 25519 uses $p = 2^{255} - 19$
base point $x = 9$

$$y^2 = x^3 + 48666 \overset{2^2}{6} x^2 + x$$

$$\text{order}(x) \approx 2^{252} + 27760493 \text{ (prime)}$$

Recitation 6 : Elliptic Curves & Number Theory

We review elliptic curves, finite fields $\text{GF}(2^k)$ and the extended Euclid's algorithm.

1 Elliptic Curves

We begin by defining Elliptic Curves.

Definition 1.1 (Elliptic Curve). An Elliptic Curve over a field \mathbb{F} is a curve given by an equation of the form:

$$y^2 = x^3 + ax + b,$$

where $a, b \in \mathbb{F}$ such that the discriminant $\Delta = 4a^3 + 27b^2 \neq 0$, that is, the polynomial $x^3 + ax + b$ has distinct roots.

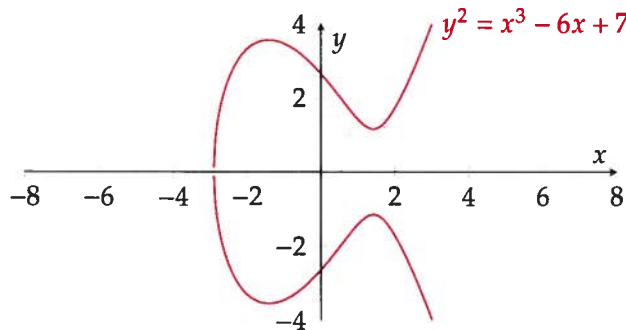


Figure 1: The Elliptic Curve defined by $y^2 = x^3 - 6x + 7$ over \mathbb{R} .

We want to define a group structure over the points on the elliptic curve. We do that next.

Definition 1.2. The Group E defined by the elliptic curve ($y^2 = x^3 + ax + b$) over field \mathbb{F} is defined as the set of points:

$$E = \{(x, y) \in \mathbb{F}^2 \mid y^2 = x^3 + ax + b\} \cup \{\infty\},$$

with the identity element ∞ and the group operation $+$ defined as follows:

Let $P(x_1, y_1)$ and $Q(x_2, y_2)$ be points in E . Then,

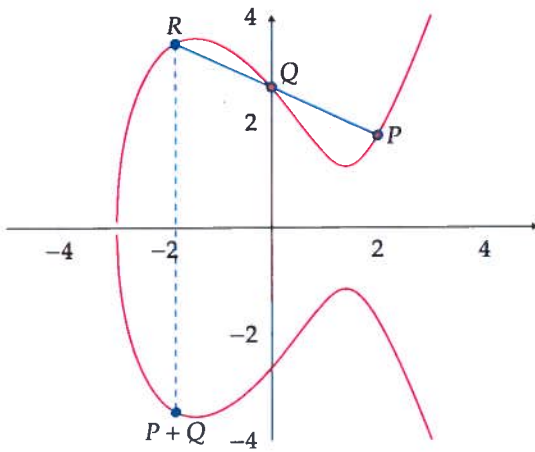
1. (Identity) $P + \infty = \infty + P = P$.
2. (Vertical Line) If $x_1 = x_2$ and $y_1 = -y_2$ then $P + Q = \infty$.
3. (Vertical Tangent) If $y_1 = 0$ then $P + P = \infty$.
4. (Tangent) $P + P = (x, y)$ where $\lambda = \frac{3x_1^2 + a}{2y_1}$, $x = \lambda^2 - 2x_1$, and $y = -(\lambda(x - x_1) + y_1)$.
5. (General Case) Let $x_1 \neq x_2$ then $P + Q = (x, y)$ where $\lambda = \frac{y_2 - y_1}{x_2 - x_1}$, $x = \lambda^2 - x_1 - x_2$ and $y = -(\lambda(x - x_1) + y_1)$.

Observe that the computation as described is independent of which field is used.

Theorem 1.3. $(E, +)$ is a group.

The identity, commutativity, inverse all follow from the definition. We will not prove that the operation is associative, but it is. We describe the geometric intuition behind these and the corresponding calculations next.

The General Case : $P + Q$



The line between (x_1, y_1) and (x_2, y_2) is given by

$$y = \frac{y_2 - y_1}{x_2 - x_1}(x - x_1) + y_1$$

where $\lambda = (y_2 - y_1)/(x_2 - x_1)$ is the slope and $v = y_1 - \lambda x_1$ is the intercept. So, to compute the point $R(x_3, y_3)$, we need to compute the intersection of the curve E with the line above. That is,

$$(\lambda x + v)^2 = x^3 + ax + b$$

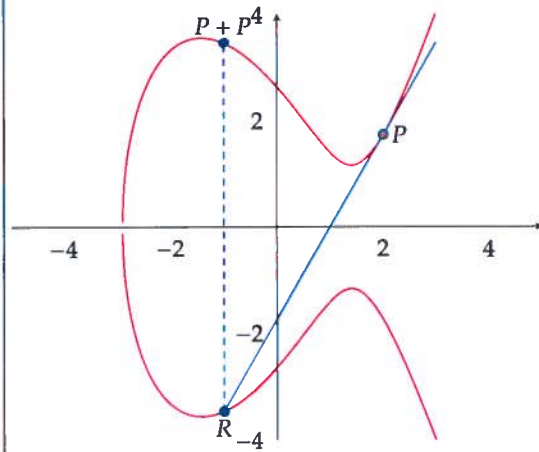
Simplifying, we get that,

$$x^3 - \lambda^2 x^2 + x(a - 2\lambda v) + (b + v^2)$$

We know two of the roots: x_1, x_2 . To find the third, use the fact that the second term is the sum of roots.^a Hence, $\lambda^2 = x_1 + x_2 + x_3$. Hence $x_3 = \lambda^2 - x_1 - x_2$. And $y_3 = \lambda(x_3 - x_1) + y_1$. Then the point $P + Q$ is $(x_3, -y_3)$.

^aThis follows from comparing $(x-x_1)(x-x_2)(x-x_3) = x^3 - (x_1 + x_2 + x_3)x^2 + \dots$ with the equation above.

Tangents: $P + P$



The tangent at $y = f(x)$ has slope $f'(x)$ (the derivative). In this case, $y = \sqrt{x^3 + ax + b}$. Hence,

$$\lambda = f'(x) = \frac{(3x^2 + a)}{\sqrt{x^3 + ax + b}} = \frac{3x^2 + a}{2y}$$

So, the line through (x_1, y_1) is,

$$y = \lambda(x - x_1) + y_1$$

Here also, we need to find the intersection of the curve with the line, knowing that x_1 is a repeated root. So, we get $x_3 = \lambda^2 - 2x_1$ and $y_3 = (\lambda(x_3 - x_1) + y_1)$. Then the point $P + P$ is $(x_3, -y_3)$.

"Gap group" is one in which

- DDH is easy ("Decision Diffie Hellman")

[Recall: given (g, g^a, g^b, g^c) , to
decide if $ab = c \pmod{\text{order}(g)}$]

- but • CDH is hard ("Computational Diffie Hellman")

[Recall: given (g, g^a, g^b) , to
compute g^{ab}]

(Note that CDH easy \Rightarrow DDH easy)

This difference in difficulty between DDH ("easy")
and CDH ("hard") forms a "gap".

- How can one construct a "gap group"?
- What good would that be?

Bilinear maps

Suppose: G_1 is group of prime order q , with generator g

→ G_2 is group of prime order q , with generator h

[we use multiplicative notation for both groups]

and there exists a (bilinear) map

$$e: G_1 \times G_1 \rightarrow G_2$$

such that

$$(\forall a, b) e(g^a, g^b) = h^{ab} \quad !!!$$

$$= e(g, g^{ab})$$

$$= e(g, g)^{ab}$$

$$= e(g, g^b)^a$$

$$= e(g, g^a)^b$$

$$= e(g^b, g^a)$$

...

Bilinear maps also called "pairing functions"

They have an enormous number of applications.*

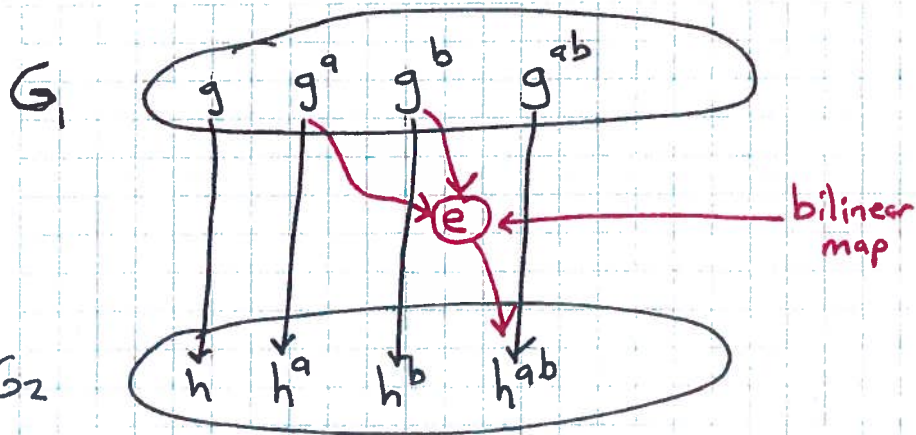
We are, of course, interested in efficiently computable bilinear maps.

* google: "The pairing-based crypto lounge"

"shadow group"

See Fig. (next page)

$$e(g, g) = h$$



"shadow group"

G_2

$$|G_1| = |G_2| = q \text{ (prime)}$$

g generates G_1

h generates G_2

CDH hard in G_1 & in G_2

DDH easy in G_1 (using e)

Note: If discrete log was easy in G_2

then it would be easy in G_1 .

$$DL_{G_1, g}(g^a) = DL_{G_2, h}(h^a) = a$$

$e(g^a, g) = h^a$
computes
"shadows"

Theorem:

If there is a bilinear map

$$e: G_1 \times G_1 \rightarrow G_2$$

between two groups of prime order g ,

then DDH is easy in G_1 .

Proof:

Given (g, g^a, g^b, g^c) (elements of G_1)

then

$$c = ab \pmod{g} \iff e(g^a, g^b) = e(g, g^c)$$

$$\underbrace{h^{ab}}_{=} = h^c$$

$$ab = c \pmod{g}$$

So: accept (g, g^a, g^b, g^c) iff $e(g^a, g^b) = e(g, g^c)$.



Even though DDH is easy in G_1 , CDH may still be hard; we may have a "gap group".

How to construct gap groups (with bilinear maps):

- This is not simple! We give just a sketch.
- G_1 will be "supersingular" elliptic curve

e.g. elliptic curve defined by points on

$$y^2 = x^3 + ax + b \pmod{p}$$

where $p \equiv 2 \pmod{3}$, $p \geq 5$

$$a = 0$$

$$b \in \mathbb{Z}_p^* \quad (\text{can choose } b=1)$$

- G_2 is finite field \mathbb{F}_{p^k} for some small k
(can use subgroups of G_1 & G_2 by choosing
generators of order $\approx 2^{160}$ say...)
- e (bilinear map) is implemented as a
"Weil pairing" or a "Tate pairing".

Application 1:

Digital signatures

(Boneh, Lynn, Shachem (2001))

Signatures are short (e.g. 160 bits)!

Public: groups G_1, G_2 of prime order q
pairing function $e: G_1 \times G_1 \rightarrow G_2$

g = generator of G_1

H = hash fn (c.r.) from messages to G_1

Secret key: x where $0 < x < q$

Public key: $y = g^x$ (in G_1)

To sign message M :

Let $m = H(M)$ (in G_1)

→ Output $\sigma = \sigma_x(M) = m^x$ (in G_1)

To verify (y, M, σ) :

Check $e(g, \sigma) \stackrel{?}{=} e(y, m)$ where $m = H(M)$
↓ ↓
 $e(g, m)^x$ in both cases

Theorem: BLS signature scheme secure against
existential forgery under chosen message attack in ROM
assuming CDH is hard in G_1 .

Note use of
multiplicative
notation here

Note:
Signature may
be short!

Just one
element of G_1 .

↑
To represent point on
elliptic curve, just
give x , then one more
bit to say which y
is wanted (there are
only two square roots
of $y^2 = x y$)

Application 2:Three-way key agreement (Joux, generalizing DH)

Recall DH:

$$A \rightarrow B: g^a$$

$$B \rightarrow A: g^b$$

$$\text{key} = g^{ab}$$

Joux: Suppose G_1 has generator g
 Suppose $e: G_1 \times G_2$ is a bilinear map.

$$A \rightarrow B, C: g^a$$

$$B \rightarrow A, C: g^b$$

$$C \rightarrow A, B: g^c$$

$$A \text{ computes } e(g^b, g^c)^a = e(g, g)^{abc}$$

$$B \text{ computes } e(g^a, g^c)^b = e(g, g)^{abc}$$

$$C \text{ computes } e(g^a, g^b)^c = e(g, g)^{abc}$$

$$\text{key} = e(g, g)^{abc}$$

Secure assuming "BDH" \equiv

$$\text{given } g, g^a, g^b, g^c, e$$

$$\text{hard to compute } e(g, g)^{abc}$$

Four-way key agreement is open problem!

(multilinear maps!)

Bilinear
Diffic-Hellman
 problem

Application 3:Identity-based encryption (IBE) [Boneh, Franklin '01]TTP (trusted third party) publishes

G_1, G_2, e (bilinear map), g (generator of G_1), y
 where $y = g^s$ & s is TTP's master secret.

Let H_1 be random oracle mapping names (e.g. "alice@mit.edu")
 to elements of G_1^*

Let H_2 be random oracle mapping G_2 to $\{0,1\}^*$ (PRG).

Want to enable anyone to encrypt message for Alice
knowing only TTP public parameters & Alice's name

Encrypt (y, name, M):

$$r \xleftarrow{R} \mathbb{Z}_g^* \quad (\text{here prime } g = |G_1| = |G_2|)$$

$$g_A = e(Q_A, y) \quad \text{where } Q_A = H_1(\text{name})$$

$$\text{output } (g^r, M \oplus H_2(g_A^r))$$

Decrypt ciphertext $c = (u, v)$:

- Alice obtains $d_A = Q_A^s$ from TTP (once is enough) where $Q_A = H_1(\text{name})$.

This is Alice's decryption key.

Note that TTP also knows it!

Note that message may be encrypted before Alice gets d_A .

- Compute $v \oplus H_2(e(d_A, u))$

$$= v \oplus H_2(e(Q_A^s, g^r))$$

$$= v \oplus H_2(e(Q_A, g)^{rs})$$

$$= v \oplus H_2(e(Q_A, g^s)^r)$$

$$= v \oplus H_2(e(Q_A, y)^r)$$

$$= v \oplus H_2(g_A^r)$$

$$= M$$

Security: Semantically secure in ROM assuming BDH.

note
use of
additive
notation

ID-based signature (Hess 2002; Dutta survey §4.10)

master secret = s
 master public = $P_{pub} = sP$ (P generates G_1)

$H_1: \{0,1\}^* \rightarrow G_1$
 $H: \{0,1\}^* \times G_2 \rightarrow \mathbb{Z}_q^*$

Extract: user gives ID. Public id = $H_1(ID) = Q_{ID}$
 Secret key = $s \cdot Q_{ID} = S_{ID}$

Sign (S_{ID}, m): $P_1 \in_R G_1^*$
 $k \in_R \mathbb{Z}_q^*$
 $r = e(P_1, P)^k$
 $v = H(m, r)$
 $u = vS_{ID} + kP_1$ } = signature

Verify: ($Q_{ID}, m, (u, v)$):
 $r = e(u, P) \cdot e(Q_{ID}, -P_{pub})^v$
 accept iff $v = H(m, r)$

Secure against existential forgery in ROM under adaptive chosen message attack assuming weak-DH problem is hard.

Given (P, Q, sP) for $P, Q \in G_1$
 output sQ