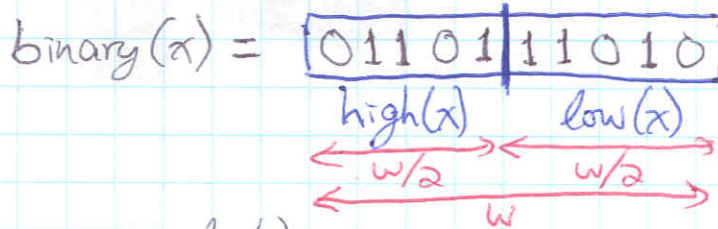


Van Emde Boas (VEB)

6.897
L9.3
Mar. 3, 2005

- $O(\lg w)$ time means we "binary search" on bits of query word x



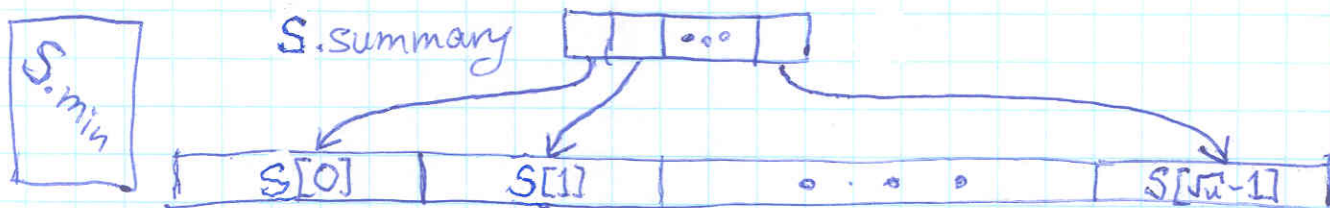
- low-order bits ^{low(x)} distinguish $2^{w/2} = \sqrt{u}$ consecutive items
- high-order bits high(x) distinguish $2^{w/2} = \sqrt{u}$ of these clusters:



- VEB structure follows this recursion:

VEB structure S of size $u =$

- substructures $S[0], S[1], \dots, S[\sqrt{u}-1]$ each of size \sqrt{u} representing partition of universe (above)
- substructure S .summary of size \sqrt{u} where $x \in S$.summary $\Leftrightarrow S[x]$ is nonempty
- minimum element S .min
 - not stored recursively in an $S[i]$ (but still counts as making S nonempty)
- S .min = none $\Leftrightarrow S$ is empty



- also augment to store S .max (stored recursively)

Successor(x, S):

- if $x < S.min$: return $S.min$
- x is at position $low(x)$ in $S[high(x)]$
- if $low(x) < S[high(x)].max$ ← key: augmentation
 then: return $high(x) \cdot \sqrt{|S|} + Successor(low(x), S[high(x)])$
- else: $i \leftarrow Successor(high(x), S.summary)$
 return $i \cdot \sqrt{|S|} + S[i].min$ ←

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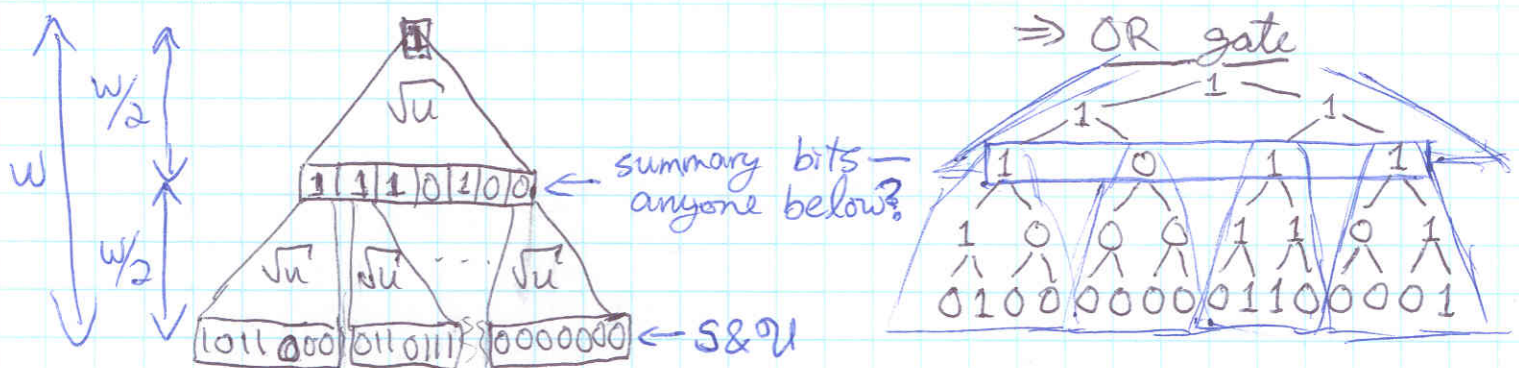
Insert(x, S):

- if $S.min = none$ then $S.min \leftarrow x$
 stop
- if $S[high(x)]$ is empty ($.min = none$)
 then: $S[high(x)].min \leftarrow low(x)$ ← key: not stored recursively
 Insert($high(x), S.summary$)
- else: Insert($low(x), S[high(x)]$)

Analysis:

- keys one recursive call on word half the size
 $\Rightarrow O(\lg w)$
- Predecessor & Delete similar

Expand recursion: tree view



- can't afford to update all these bits ~
 but the ones really needed by Successor are there
- not storing min recursively avoids a lot of these updates

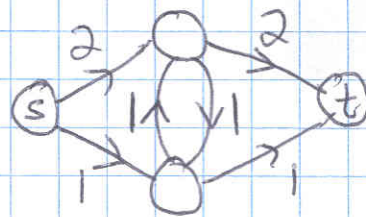
Network Flow / Maximum Flow

CONCISE VERSION
WITHOUT RAW/
POSITIVE FLOWS
(JUST NET FLOWS)

6.854
L6.1
Sept. 24, 2003

Network:

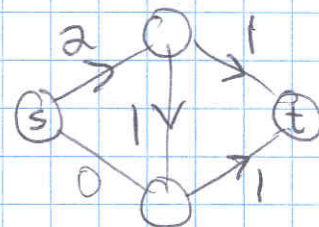
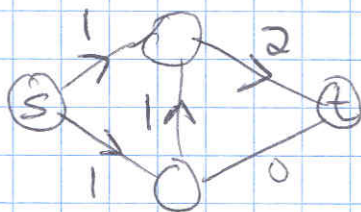
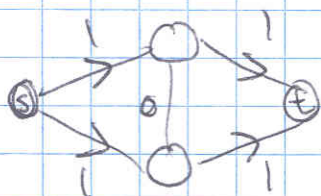
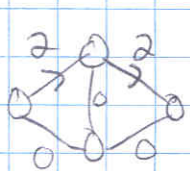
- directed graph
- source vertex s
- sink vertex t
- capacity $u(e) = u(v,w) > 0$
for each directed edge $e = (v,w)$
<<"u" not "c" - "c" used for cost later>>
- $u(v,w) = 0$ if (v,w) not an edge



Treat as one (bidirectional) edge in flow - can use just one

Flow: real number $f(v,w) \forall v,w$ (nonzero only if (v,w) or (w,v) an edge) satisfying:

- skew symmetry: $f(v,w) = -f(w,v)$
- conservation: $\sum_w f(v,w) = 0$ unless $v = s$ or t
- capacity: $f(v,w) \leq u(v,w)$ (flow is feasible)



Value of flow f : $|f| = \sum_w f(s,w)$

Max-flow problem: find flow of maximum value

Intuition: $f(e)$ is a rate, not quantity
(so don't have to worry about startup delays etc.)

E.g.: water pipes,
routing commodities,
messages under bandwidth constraints, ...

Residual network G_f of flow f in network G

- capacities $u'(v,w) = u(v,w) - f(v,w)$

- f feasible $\Rightarrow u'(v,w) \geq 0$

& $\leq 2 \cdot u(v,w)$ [$f(v,w)$ might be negative]

- G_f has edges (v,w) whenever $u'(v,w) > 0$.

MAX FLOW IN G_f
= MAX FLOW IN G
(JUST ADD/SUB f)

Augmenting path is a ^{directed} path from s to t in residual network

- can push additional flow along such a path in original network G :

$$\min \{ u'(s, v_1), u'(v_1, v_2), \dots, u'(v_n, t) \}$$

- augmenting path exists \Rightarrow not max. flow

- no augmenting path \Rightarrow max flow??

MORE GENERALLY:
CAN ADD ANY
FLOW IN G_f
TO FLOW IN G

Cut is a partition of vertices into 2 groups: S & $\bar{S} = V \setminus S$.
s-t cut has $s \in S$ and $t \in \bar{S}$.



All s-t cuts carry same flow:

- net flow along cut S : $f(S) = \sum_{v \in S} \sum_{w \in \bar{S}} f(v,w) =: f(S, \bar{S})$

- claim: $f(S) = |f|$ for all s-t cuts S, \bar{S} .

- true for $\{s\}, V \setminus \{s\}$.

- if we move v from \bar{S} to S

then add $f(v, \bar{S})$

& subtract $f(S, v) = -f(v, S)$

} really $S \rightarrow \{v\}$
 $\bar{S} \rightarrow \{v\}$

- total change: $f(v, \bar{S}) + f(v, S) = f(v, V) = 0$
(conservation)

Capacity/

Value of cut: $u(S) = u(S, \bar{S}) = \sum_{v \in S} \sum_{w \in \bar{S}} u(v,w)$

value of any flow = net flow along any s-t cut \leq value of cut
 $|f| = f(S) \leq u(S)$

G.354
 L6.3
 Sept. 24, 2003

$\Rightarrow |\max \text{ flow}| \leq u(\min \text{ s-t cut})$

Max-flow min-cut theorem: $|\max \text{ flow}| = u(\min \text{ s-t cut})$

- max flow has no augmenting paths

foreshadowing
 more general
 duality in LP

\Rightarrow residual graph G_f is s-t disconnected

$\Rightarrow S = \{\text{vertices reachable from } s \text{ in } G_f\}$ is an s-t cut

- all edges (v,w) leaving S have 0 residual
 $\Rightarrow u(v,w) = f(v,w)$

$\Rightarrow u(S) = f(S) = |f|$

\Rightarrow s-t cut S has value $|f| = |\max \text{ flow}|$

$\Rightarrow u(\min \text{ s-t cut}) \leq |\max \text{ flow}|$ \square

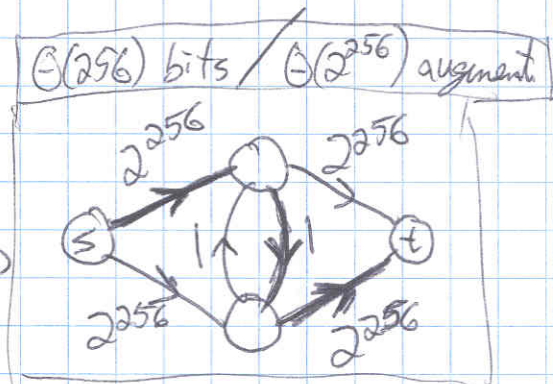
Ford-Fulkerson max-flow algorithm

- start with $f(v,w) = 0$

- DFS to find an augmenting path

- augment flow

- repeat until DFS fails



Running time:

$O(m \cdot |f|)$

• if capacities are integral: $= O(m \cdot \max u)$ where $u = \max u$

INTEGRALITY

- weakly polynomial: polynomial in unary encoding of input numbers

• if capacities are rational: still terminates but slower

• if capacities are real: may not terminate

\ll What if we choose a good augmenting path? \gg

Bit scaling

- shift in one bit of capacities (high-order first)
- run naive augmenting paths
- repeat

G.854
L6.4
Sept. 24, 2003

(UNCOVERED -
DELAYED TO L7)

Analysis:

- before ^{next} bit shift, some cut has residual capacity 0
 - after next bit shift, that cut has ~~capacity~~ residual capacity $\leq m$
 - shifting left 1 bit ($\times 2$) has no effect
 - introducing new low-order bit \Rightarrow ~~+~~ +0 or +1.
 - at most m edges straddle cut
- $\therefore \leq m$ augmentations restore max flow
- $\lg U$ iterations ($U = \max u$)

Total time: $O(m^2 \lg U)$

- polynomial in bit complexity of input
- not strongly polynomial i.e. polynomial in combinatorial complexity m, n

Maximum-capacity augmenting path

6.854
L6.5
Sept. 24, 2003

- choose augmenting path that improves flow value most
 - can find this path in $O(m \lg n)$ time using Dijkstra-like algorithm (ignore cycles)

Lemma: can decompose any flow into $\leq m$ paths with values

- follow any path of positive ^{net} flow from s to t
(once started, can always continue to extend path by conservation)
- anti-augment: ~~remove~~ subtract augmenting path of maximum possible value } add to set of paths
- at least one edge hits 0 flow
- repeat $\leq m$ times because $\leq m$ edges can hit 0 flow
- ~~remaining~~ remaining cycles of flow similarly find \square

- apply lemma to max flow in residual graph (discarding cycles)
 \Rightarrow set of m candidate augmenting paths whose total value = total residual ~~capacity~~ flow

- at least one of these paths carries $\geq 1/m$ fraction of residual flow
 \Rightarrow max-capacity augmenting path ~~value~~ reduces $|f|$ to $\leq (1-1/m)|f|$

- after $m \ln f$ iterations, $(1-1/m)^{m \ln f} \cdot f \sim (1/e)^{\ln f} \cdot f = 1$
 \Rightarrow ~~total residual~~ ^{total residual} capacity in $[0, 1]$

- if capacities are integral, one more step suffices.

$\Rightarrow \leq m \ln f$ augmentations

$\Rightarrow O(m^2 \ln f \lg n)$ time

- also polynomial but not strongly polynomial

- also works for rational capacities