

## Lecture 14 — March 30, 2010

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## 1 Overview

In the last lecture we covered the Separator Decomposition, which rearranges any tree into a balanced tree, and the ART/leaf-trimming Decomposition, which is a tree decomposition used to solve the marked ancestor problem and decremental connectivity problem.

In this lecture we talk about solutions to the static and dynamic **dictionary problem**. Our goal is to store a small set  $S = \{1, 2, \dots, n\}$  of keys from a large universe  $U$ , with perhaps some information associated to every key. We want to find a compact data structure with low pre-processing time that will support  $\text{Query}(x)$  in the static case and  $\text{Query}(x)$ ,  $\text{Insert}(x)$ , and  $\text{Delete}(x)$  in the dynamic case.  $\text{Query}(x)$  checks if  $x \in S$ , and returns any information associated with  $x$ .

In particular, **FKS hashing** achieves  $O(1)$  worst-case query time with  $O(n)$  expected space and takes  $O(n)$  construction time for the static dictionary problem. **Cuckoo Hashing** achieves  $O(n)$  space,  $O(1)$  worst-case query and deletion time, and  $O(1)$  amortized insertion time for the dynamic dictionary problem.

## 2 Hashing with Chaining

Our first attempt at a dictionary data structure is *hashing with chaining*. We find a **hash function**  $h : U \rightarrow \{1, 2, \dots, m\}$ , and maintain a table  $T$  with  $m$  rows, where  $T[j]$  = a linked list (or chain) of  $\{x \in S : h(x) = j\}$ .

Key look up takes  $\frac{\sum |T[j]|^2}{2 \sum |T_j|}$  expected time, so we want to make the chains as equal as possible. We also generally want  $h$  to be easy to evaluate. Luckily, such hash functions exist<sup>1</sup>:

### 2.1 Universal Hashing

**Definition 1.** A class of functions  $\mathcal{H}$  is  $c$ -universal if and only if for all  $x \neq y$ ,

$$|\{h \in \mathcal{H} : h(x) = h(y)\}| \leq c \cdot \frac{|\mathcal{H}|}{m}.$$

In particular, if  $h$  is picked at random from  $\mathcal{H}$ ,  $\text{Pr}[h(x) = h(y)] \leq \frac{c}{m}$ .

We assume for the rest of this section that  $m = O(n)$ .

<sup>1</sup>It's worth noting that a random function from  $U$  to  $\{1, \dots, m\}$  would actually have  $O(1)$  expected query time (provided  $n = O(m)$ ). However, such a random function would be infeasibly inefficient to store and evaluate.

Define  $Z_x := |\{y \in S : h(x) = h(y)\}|$ , namely, the collisions with  $x$  in the set of elements we want to store. We can also write this as  $Z_x = \sum_y \delta_{h(x),h(y)}$ , where  $\delta$  is the Kronecker delta ( $\delta_{a,b} = 1$  if  $a = b$  and 0 otherwise). The average query time is simply  $E[Z_x]$ , and we have

$$E[Z_x] = E \left[ \sum_y \delta_{h(x),h(y)} \right] = \sum_y E[\delta_{h(x),h(y)}] = 1 + \sum_{y \neq x} Pr[h(x) = h(y)] = 1 + \frac{nc}{m} = O(1).$$

All that remains then is to find a class of such  $c$ -universal functions. An example of a 2-universal class is

$$\mathcal{H} = \{h_a(x) = (ax \pmod{p}) \pmod{m}\}_{0 < a < p}$$

for a prime  $p > m$ .

The drawback here is the worst case situation (ie. the longest chain) is  $\Theta(\log n / \log \log n)$  [1]. We can actually do a bit better, by using  $2d$  hash functions, and inserting the item into the shortest of the  $2d$  possible lists, after which the worst case lookup time becomes  $\Theta(\log \log n / \log d)$  [2].

## 2.2 Perfect Hashing

If we don't care about linear space, we can build a hash function with *no* collisions in the static case. Let

$$Z(h) = \sum_{\substack{x < y \\ x, y \in S}} Pr[h(x) = h(y)]$$

which is the expected number of collisions. Pick  $h$  randomly from a  $c$ -universal class of hash functions. We have from above that for any given  $x, y$ ,  $Pr[h(x) = h(y)] \leq \frac{c}{m}$ , so  $Z(h) \leq \binom{n}{2} \frac{c}{m}$ . If we choose  $m = cn^2$ , we have that the expected number of collisions is  $< 1/2$ , and by Markov's inequality,  $Pr(h \text{ has no collisions}) > 1/2$ . This means that we can pick a collision-free  $h$  in  $O(1)$  trials.

This is great, except of course that  $m = cn^2$  is a lot of space.

## 3 FKS – Fredman, Komlós, Szemerédi (1984) [3]

*FKS hashing* is a two-layered hashing solution to the static dictionary problem that achieves  $O(1)$  worst-case query time in  $O(n)$  expected space, and takes  $O(n)$  time to build.

The main idea is to hash to a small table  $T$  with collisions, and have every cell  $T_i$  of  $T$  be a collision-free hash table on the elements that map to  $T_i$ .

If  $S$  is the original set, we let  $S = S_1 \dot{\cup} S_2 \dot{\cup} \dots \dot{\cup} S_m$ , where  $S_i = \{x : h(x) = i\}$  (note that  $\dot{\cup}$  denotes disjoint union). Using perfect hashing, we can find a collision-free hash function  $h_i$  from  $S_i$  to a table of size  $O(|S_i|^2)$  in constant time. To make a query then we compute  $h(x) = i$  and then  $h_i(x)$ .

The expected size of the data structure is

$$E \left( \sum |S_i|^2 \right) = E \left( \sum |S_i| \right) + 2 \cdot E \left( \sum \binom{|S_i|}{2} \right) = n + 2 \cdot Z(h) = n + O \left( \frac{n^2}{m} \right).$$

If we let  $m = O(n)$ , we have expected space  $O(n)$  as desired, and since the creation of each  $T_i$  takes constant time, the total construction time is  $O(n)$ .

## 4 More Universal Hashing

**Definition 2.** A class  $\mathcal{H}$  of hash functions is  $(c, k)$ -**universal** if for all distinct  $x_1, x_2, \dots, x_k$  and for any  $a_1, a_2, \dots, a_k$

$$\Pr(h(x_1) = a_1 \wedge h(x_2) = a_2 \wedge \dots \wedge h(x_k) = a_k) \leq \frac{c}{m^k}$$

for all  $h \in \mathcal{H}$ .

Note that  $c$ -universal is the same as  $(c, 1)$ -universal.

Siegel (1989) [4] showed that a  $(c, \log n)$ -universal class of hash functions exists, where the functions have  $O(1)$  query time and  $O(\log n)$  storage (ie. each hash function can be described in  $O(\log n)$  bits), which we will need in the next section.

## 5 Cuckoo Hashing – Pagh and Rodler (2001) [5]

*Cuckoo hashing* is inspired by the Cuckoo bird, which lays its eggs in other birds' nests, bumping out the eggs that are originally there. Cuckoo hashing solves the dynamic dictionary problem, achieving  $O(1)$  worst-case time for queries and deletes, and  $O(1)$  expected time for inserts.

Let  $f$  and  $g$  be  $(c, 6 \log n)$ -universal hash functions. As usual,  $f$  and  $g$  map to a table  $T$  with  $m$  rows. We implement the functions as follows:

- *Query*( $x$ ) – Check  $T[f(x)]$  and  $T[g(x)]$  for  $x$ .
- *Delete*( $x$ ) – Query  $x$  and delete if found.
- *Insert*( $x$ ) – If  $T[f(x)]$  is empty, we put  $x$  in  $T[f(x)]$  and are done.

Otherwise say  $y$  is originally in  $T[f(x)]$ . We put  $x$  in  $T[f(x)]$  as before, and bump  $y$  to whichever of  $T[f(y)]$  and  $T[g(y)]$  it didn't just get bumped from. If that new location is empty, we are done. Otherwise, we place  $y$  there anyway and repeat the process, moving the newly bumped element  $z$  to whichever of  $T[f(z)]$  and  $T[g(z)]$  doesn't now contain  $y$ .

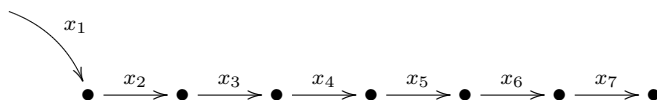
We continue in this manner until we're either done or reach a hard cap of bumping  $6 \log n$  elements. Once we've bumped  $6 \log n$  elements we pick a new pair of hash functions  $f$  and  $g$  and rehash every element in the table.

Note that at all times we maintain the invariant that each element  $x$  is either at  $T[f(x)]$  or  $T[g(x)]$ , which makes it easy to show correctness. The time analysis is harder.

It is clear that query and delete are  $O(1)$  operations. The reason *Insert*( $x$ ) is not horribly slow is that the number of items that get bumped is generally very small, and we rehash the entire table very rarely when  $m$  is large enough. We take  $m = 4n$ .

Since we only ever look at at most  $6 \log n$  elements, we can treat  $f$  and  $g$  as random functions. Let  $x = x_1$  be the inserted element, and  $x_2, x_3, \dots$  be the sequence of bumped elements in order. It is convenient to visualize the process on the *cuckoo graph*, which has vertices  $1, 2, \dots, m$  and edges  $(f(x), g(x))$  for all  $x \in S$ . Inserting a new element can then be visualized as a walk on this graph. There are 3 patterns in which the elements can be bumped.

- *Case 1* Items  $x_1, x_2, \dots, x_k$  are all distinct. The bump pattern looks something like<sup>2</sup>

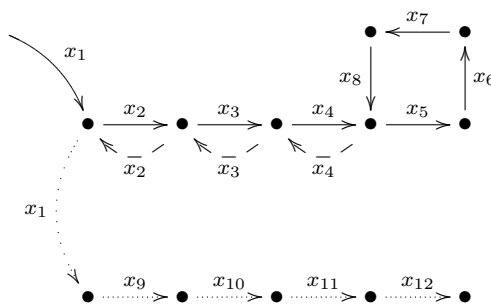


The probability that at least one item (ie.  $x_2$ ) gets bumped is

$$Pr(T[f(x)] \text{ is occupied}) = Pr(\exists y : f(x) = g(y) \vee f(x) = f(y)) < \frac{2n}{m} = \frac{1}{2}.$$

The probability that at least 2 items get bumped is the probability the first item gets bumped ( $< 1/2$ , from above) times the probability the second item gets bumped (also  $< 1/2$ , by the same logic). By induction, we can show that the probability that at least  $t$  elements get bumped is  $< 2^{-t}$ , so the expected running time ignoring rehashing is  $< \sum_t t 2^{-t} = O(1)$ . The probability of a full rehash in this case is  $< 2^{-6 \log n} = O(n^{-6})$ .

- *Case 2* The sequence  $x_1, x_2, \dots, x_k$  at some point bumps an element  $x_i$  that has already been bumped, and  $x_i, x_{i-1}, \dots, x_1$  get bumped in turn after which the sequence of bumping continues as in the diagram below. In this case we assume that after  $x_1$  gets bumped all the bumped elements are new and distinct.

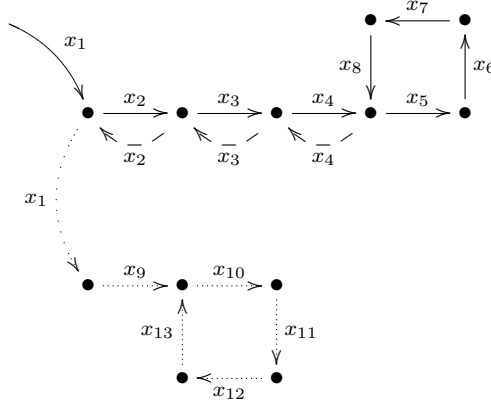


The length of the sequence ( $k$ ) is at most 3 times  $\max\{\#\text{solid arrows}, \#\text{dashed arrows}\}$  in the diagram above, which is expected to be  $O(1)$  by Case 1. Similarly, the probability of a full rehash is  $O(2^{-\frac{6 \log n}{3}}) = O(n^{-2})$ .

- *Case 3* Same as Case 2, except that the dotted lines again bump something that has been bumped before (diagram on next page).

In this case, the cost is  $O(\log n)$  bumps plus the cost of a rehash. We compute the probability Case 3 happens via a counting argument. The number of Case 3 configurations involving  $t$

<sup>2</sup>Diagrams courtesy of Pramook Khungurn, Lec 1 scribe notes from when the class was taught (as 6.897) in 2005



distinct  $x_i$  given some  $x_1$  is ( $\leq n^{t-1}$  choices for the other  $x_i$ )  $\cdot$  ( $< t^3$  choices for the index of the first loop, where the first loop hits the existing path, and where the second loop hits the existing path)  $\cdot$  ( $m^{t-1}$  choices for the hash values to associate with the  $x_i$ )  $= O(n^{t-1}t^3m^{t-1})$ .

The total number of configurations we are choosing from is  $\binom{m}{2}^t = O(2^{-t}m^{2t})$ , since each  $x_i$  corresponds to a possible edge in the cuckoo graph. So the total probability of a Case 3 configuration (after plugging in  $m = 4n$ ) is

$$\sum_t \frac{O(n^{t-1}t^3m^{t-1})}{O(2^{-t}m^{2t})} = O(n^{-2}) \sum_t \frac{t^3}{2^{3t}} = O(n^{-2}).$$

If there is no rehash, the cost of insertion is  $O(1)$  from Cases 1 and 2. The probability of a rehash is  $O(n^{-2})$ . So, we have  $\text{Cost-of-Insert} = \text{Pr}(\text{rehash}) \cdot (O(\log n) + n \cdot \text{Cost-of-insert}) + (1 - \text{Pr}(\text{rehash})) \cdot O(1) = O(1/n) \cdot \text{Cost-of-insert} + O(1)$ , so overall Cost-of-Insert is  $O(1)$  in expectation.

## References

- [1] G. Gonnet, *Expected Length of the Longest Probe Sequence in Hash Code Searching*, Journal of the ACM, 28(2):289-304, 1981.
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- [3] M. Fredman, J. Komlós, E. Szemerédi, *Storing a Sparse Table with  $O(1)$  Worst Case Access Time*, Journal of the ACM, 31(3):538-544, 1984.
- [4] A. Siegel, *On universal classes of fast hash functions, their time-space tradeoff, and their applications*, 30<sup>th</sup> FOCS, p. 20-25, Oct. 1989.
- [5] R. Pagh, F. Rodler, *Cuckoo Hashing*, Journal of Algorithms, 51(2004), p. 122-144.