

→ not necessarily constant - can be $c(n)$

c-gap problem: distinguish between

- min: $OPT \leq k$ vs. $OPT > c \cdot k$ ($c > 1$)

- max: $OPT \geq k$ vs. $OPT < k/c$ ($c > 1$)

OR: $OPT < c \cdot k$ ($c < 1$)

- promised that OPT is not in between
i.e. don't care what algorithm does in that range
- if c-gap problem is NP-hard
then so is $<c$ -approximating optimization problem
⇒ stronger type of result

(a,b)-gap SAT/CSP:

- distinguish between $OPT < a \cdot \# \text{ clauses}$
vs. $OPT \geq b \cdot \# \text{ clauses}$

⇒ gap $c = b/a$

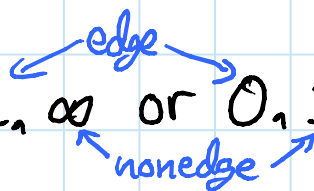
Gap-producing reductions:

- output has $OPT = k$ or $\begin{cases} \text{max: } OPT < k/c \\ \text{min: } OPT > c \cdot k \end{cases}$

- simple examples:

- Tetris: $n^{1-\epsilon}$ gap [L3]

- nonmetric TSP: weights 1, ∞ or 0, 1
reduction from Ham. cycle
⇒ exponential or infinite gap



PCP($O(\lg n), O(1)$) = Probabilistically Checkable Proof

- certificate of polynomial length } for YES instances
- $O(1)$ -time verification algorithm } (like NP)
- given certificate & $O(\lg n)$ bits of randomness
- if YES instance: algorithm says YES
- if NO instance: $\Pr\{\text{algorithm says NO}\} \geq \Omega(1)$
- boosting: apply $\lg 1/\epsilon$ times $\Rightarrow \Pr\{\text{incorrect}\} \leq \epsilon$

\rightarrow constant < 1

- ($< 1, 1$)-gap 3SAT \in PCP($O(\lg n), O(1)$):

- certificate = variable assignment
- algorithm checks random clause is satisfied
- $\Pr\{\text{wrong}\} \leq 1/\text{gap}$

\Rightarrow if ($< 1, 1$)-gap 3SAT is NP-hard
then $NP = PCP(O(\lg n), O(1))$

(based on
lecture notes
by Dana
Moshkovitz)

- if 3SAT \in PCP($O(\lg n), O(1)$)

then ($< 1, 1$)-gap 3SAT is NP-hard ($\Rightarrow O(1)$ -inapprox.)

by gap-producing reduction:

- PCP algorithm = $O(1)$ -size formula \rightarrow CNF
- take conjunction over $n^{O(1)}$ random choices
- if NO: $\Omega(1)$ fraction of terms false

i.e. $\Omega(1)$ fraction of terms have ≥ 1 false clause

$O(1)$ clauses

$\Rightarrow \Omega(1)$ fraction of clauses false

PCP theorem: $NP = PCP(O(\lg n), O(1))$ [Arora & Safra:
Arora, Lund, Motwani, Sudan, Szegedi - FOCs 1992 / J.ACM 1998]

Gap-preserving reduction $A \rightarrow B$:

instance x of A \xrightarrow{f} instance $x' = f(x)$ of B
 $|x| = n$ $|x'| = n'$

& functions $k(n), k'(n'), c(n) \geq 1, c'(n') \geq 1$ satisfying:

- min: ① $OPT_A(x) \leq k \Rightarrow OPT_B(x') \leq k'$

② $OPT_A(x) \geq c \cdot k \Rightarrow OPT_B(x') \geq c' \cdot k'$

- max: ① $OPT_A(x) \geq k \Rightarrow OPT_B(x') \geq k'$

② $OPT_A(x) \leq k/c \Rightarrow OPT_B(x') \leq k'/c'$

- transitive

- gap amplifying if $c' > c$

Example: [Håstad - J.ACM 2001] & [Williamson & Shmoys book, 2010]

Max E3-X(N)OR-SAT: (linear equations, = 3 terms)

- $(\frac{1}{2} + \epsilon, 1 - \epsilon)$ -gap is NP-hard $\forall \epsilon > 0$ (PCP version)

$\Rightarrow (\frac{1}{2} + \epsilon)$ -inapproximable

- $\frac{1}{2}$ -approximation: uniform random assignment

$\Rightarrow \Pr\{\text{right parity for equation}\} = 1/2$

Max E3SAT:

- L-reduction from Max E3-X(N)OR-SAT:

$$- x_i \oplus x_j \oplus x_k = 1 \rightarrow (x_i \vee x_j \vee x_k) \wedge (\bar{x}_i \vee \bar{x}_j \vee x_k) \\ \wedge (x_i \vee \bar{x}_j \vee \bar{x}_k) \wedge (\bar{x}_i \vee x_j \vee \bar{x}_k)$$

$$- x_i \oplus x_j \oplus x_k = 0 \rightarrow (\bar{x}_i \vee \bar{x}_j \vee \bar{x}_k) \wedge (x_i \vee x_j \vee \bar{x}_k) \\ \wedge (\bar{x}_i \vee x_j \vee x_k) \wedge (x_i \vee \bar{x}_j \vee x_k)$$

- satisfied \Rightarrow all 4 clauses satisfied

- not satisfied \Rightarrow exactly 3 clauses satisfied

\Rightarrow additive error preserved $\Rightarrow \beta = 1$

$$- \text{OPT}_{E3SAT} = \text{OPT}_{E3X(N)OR} + 3 \cdot \# \text{ equations} \\ \leq 7 \cdot \text{OPT}_{E3X(N)OR} \quad \text{by 2-approx.}$$

$$\Rightarrow \alpha = 7$$

- no $(1 - \frac{1}{2})$ -approx. for Max E3-X(N)OR-SAT

\Rightarrow no $(1 - \frac{1}{2}/\alpha\beta)$ -approx. for Max E3SAT

$$= 1 - \frac{1}{14} = \frac{13}{14}$$

- gap argument:

- yes instance $\Rightarrow \geq (1 - \epsilon) \cdot m$ equations satisfied

$\rightarrow \geq (1 - \epsilon)m \cdot 4 + \epsilon m \cdot 3$ clauses satisfied

$$= (4 - \epsilon)m \quad \text{out of } 4m$$

- no instance $\Rightarrow < (\frac{1}{2} + \epsilon) \cdot m$ equations satisfied

$\rightarrow < (\frac{1}{2} + \epsilon)m \cdot 4 + (\frac{1}{2} - \epsilon)m \cdot 3$ clauses satisfied

$$= (\frac{7}{2} + \epsilon)m \quad \text{out of } 4m$$

$\Rightarrow (\frac{7}{8} + \epsilon, 1 - \epsilon)$ -gap Max E3SAT is NP-hard

$\Rightarrow (\frac{7}{8} + \epsilon)$ -gap Max E3SAT is NP-hard

$\Rightarrow (\frac{7}{8} + \epsilon)$ -inapproximable

- $\frac{7}{8}$ -approximation: random assignment *tight!*

Label Cover: Min-Rep & Max-Rep

[Arora, Babai, Stern, Sweedyk - JCSS 1997]

- given bipartite graph $G = (A \cup B, E)$
where $A = A_1 \cup A_2 \cup \dots \cup A_k$, $|A| = n$, $|A_i| = \frac{n}{k}$
 $B = B_1 \cup B_2 \cup \dots \cup B_k$, $|B| = n$, $|B_i| = \frac{n}{k}$
- choose $A' \subseteq A$ & $B' \subseteq B$ group \uparrow
- superedge (A_i, B_j) if ≥ 1 edge in $A_i \times B_j$
- covered if $(A' \times B') \cap (A_i \times B_j) \cap E \neq \emptyset$

Max-Rep:

- choose exactly 1 vertex from each group
i.e. $|A' \cap A_i| = |B' \cap B_i| = 1 \quad \forall i$
- maximize # edges in $A' \times B'$ (i.e. induced by $A' \cup B'$)
= # covered superedges

Min-Rep:

- allow > 1 from each group
- cover every superedge (A_i, B_j)
- minimize $|A'| + |B'|$

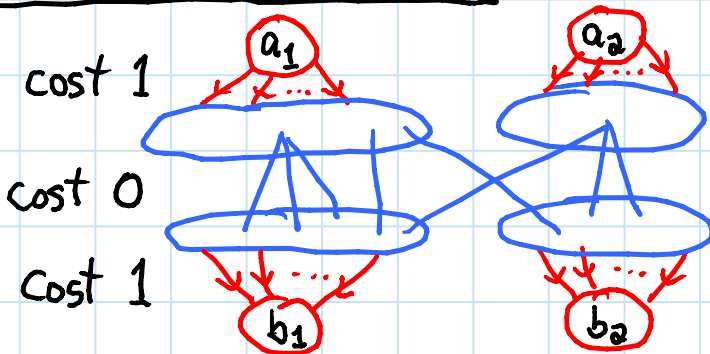
Special cases:

- regular = graph of superedges has uniform degree
- star property: each vertex $\in B_j$ adjacent to ≤ 1 vertex $\in A_i \Rightarrow$ edges in $A_i \times B_j$ form disjoint stars
- word puzzle: A_i = set of words (e.g. "animal"), B_j = alphabet
star = word letters in order [Moshkovitz]
- unique game: edges in $A_i \times B_j$ form a matching

Hardness:

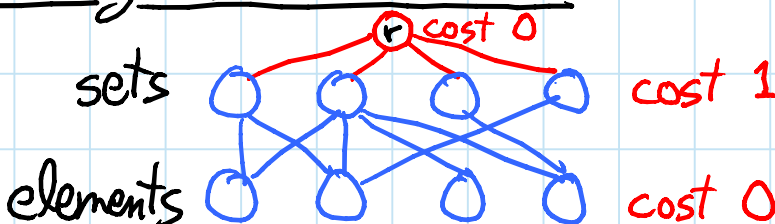
- (a, b) -gap Max-Rep: distinguish between a & b fraction of superedges covered
- (a, b) -gap Min-Rep: distinguish between $OPT < a(2k)$ & $OPT \geq b(2k)$ ($2k = \text{super matching}$)
- $(\epsilon, 1)$ -gap Max-Rep is NP-hard [Raz - SICOMP 1998]
 - $\rightarrow \forall \epsilon > 0 \Rightarrow \notin APX$ (reducing to self)
 - even if $\epsilon = 1/\log^\epsilon n$ [Moshkovitz & Raz - FOCS 2008]
- $(1/p^k, 1)$ -gap Max-Rep $\in P \Rightarrow NP \subseteq DTIME(n^{O(k)})$
 - \rightarrow constant
 - ditto $(1, p^k)$ -gap Min-Rep $\forall k$
- \Rightarrow no $1/2^{\log^{1-\epsilon} n}$ -approximation algorithm unless $NP \subseteq DTIME(n^{\text{poly log } n}) \leftarrow \text{"quasipolynomial"}$
- best approx.: $\tilde{O}(n^{1/3})$ [Charikar, Hajiaghayi, Karloff - ESA 2009]
- $(O(n^{1/4}), 1)$ -gap $\in P$ [Manurangsi & Moshkovitz - ESA 2013]

Directed Steiner forest: strict reduction from Min-Rep



... require $a_i \rightarrow b_j$ path for each superedge (A_i, B_j)

Node-weighted Steiner tree: strict reduction from Set Cover



Unique Games Conjecture: [Khot-FOCS 2002]

$(\epsilon, 1-\epsilon)$ -gap unique game is NP-hard $\forall \epsilon > 0$ ($\delta < \frac{1}{2}$)

\Rightarrow Max 2SAT 0.940-approx., Max Cut 0.878-approx.,
Vertex Cover 2-approx. tight [Khot survey-ccc2010]

- cf. 0.954, 0.941, 1.166-inapprox. via PCP

[Håstad-JACM 2001]

- for every CSP, inapproximability factor ϵ less than
integrality gap of natural SDP relaxation

\Rightarrow SDP is ultimate approximation technique (here)

[Raghavendra-STOC 2008]

- e.g. for Vertex Cover, integrality gap = 2
for LP or SDP