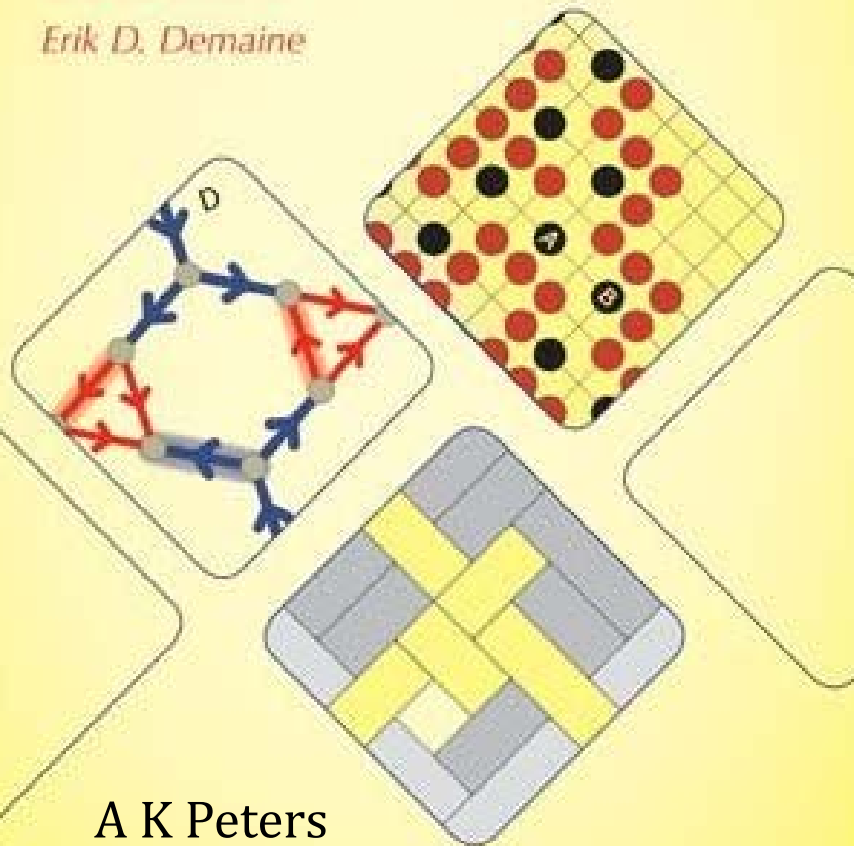


Games, Puzzles, & Computation

Robert A. Hearn
Erik D. Demaine



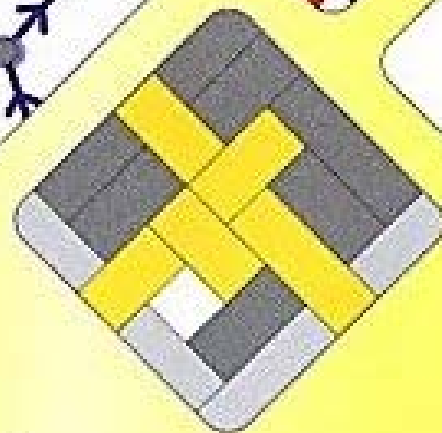
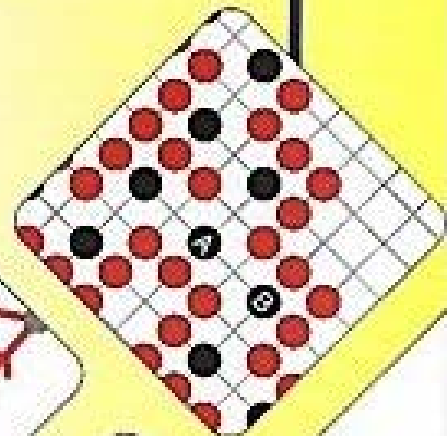
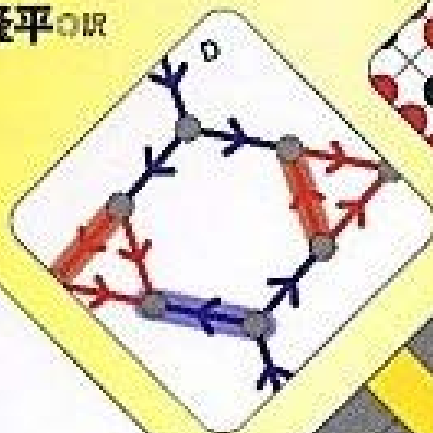
A K Peters
July 2009

ゲームと パズルの 計算量

Games, Puzzles,
& Computation

Robert A. Hearn
Erik D. Demaine

ロバート・A・ハーン
エリック・D・ドメイン
上原隆平



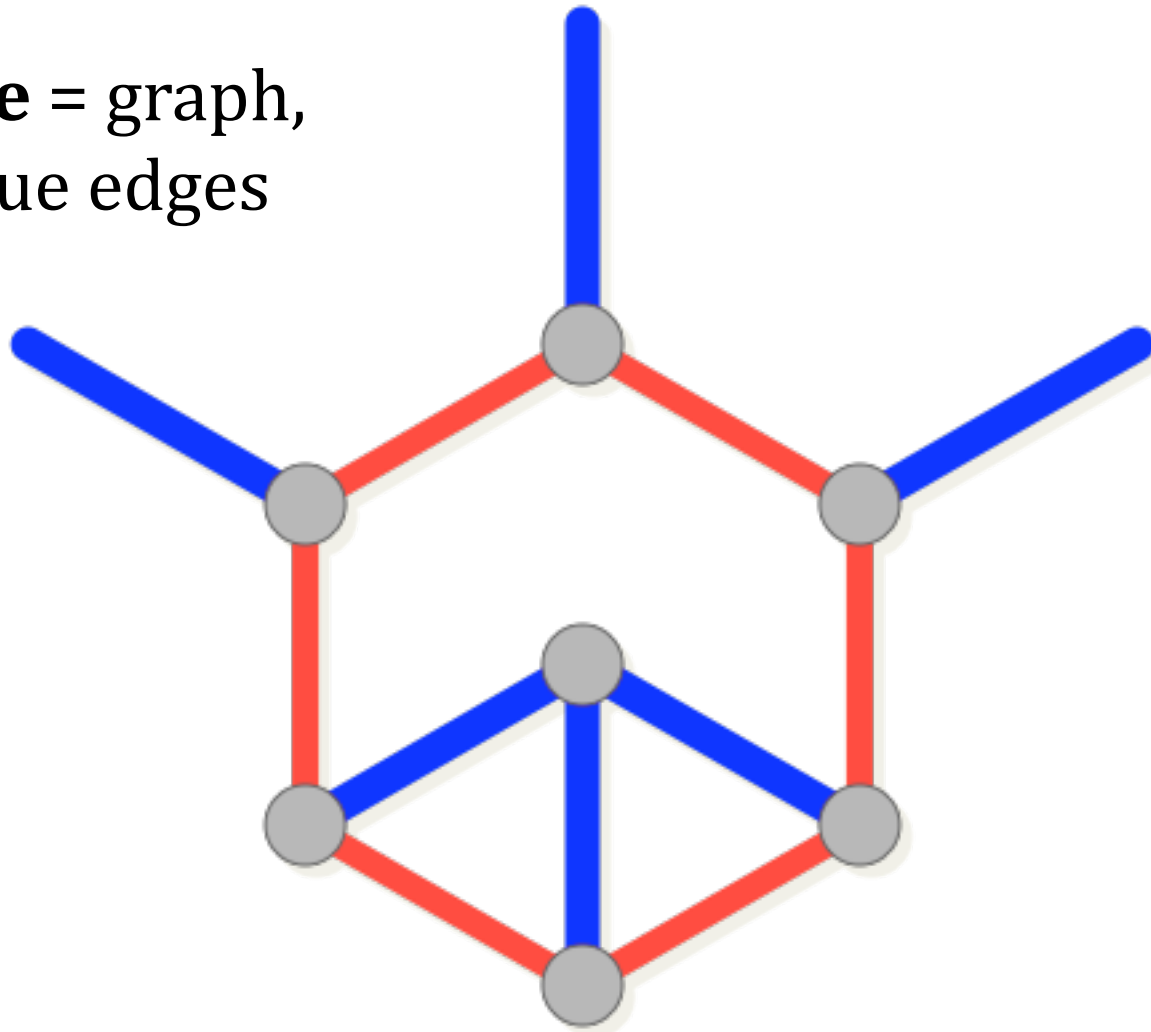
translated by
Ryuhei Uehara

近代科学社



Constraint Graphs

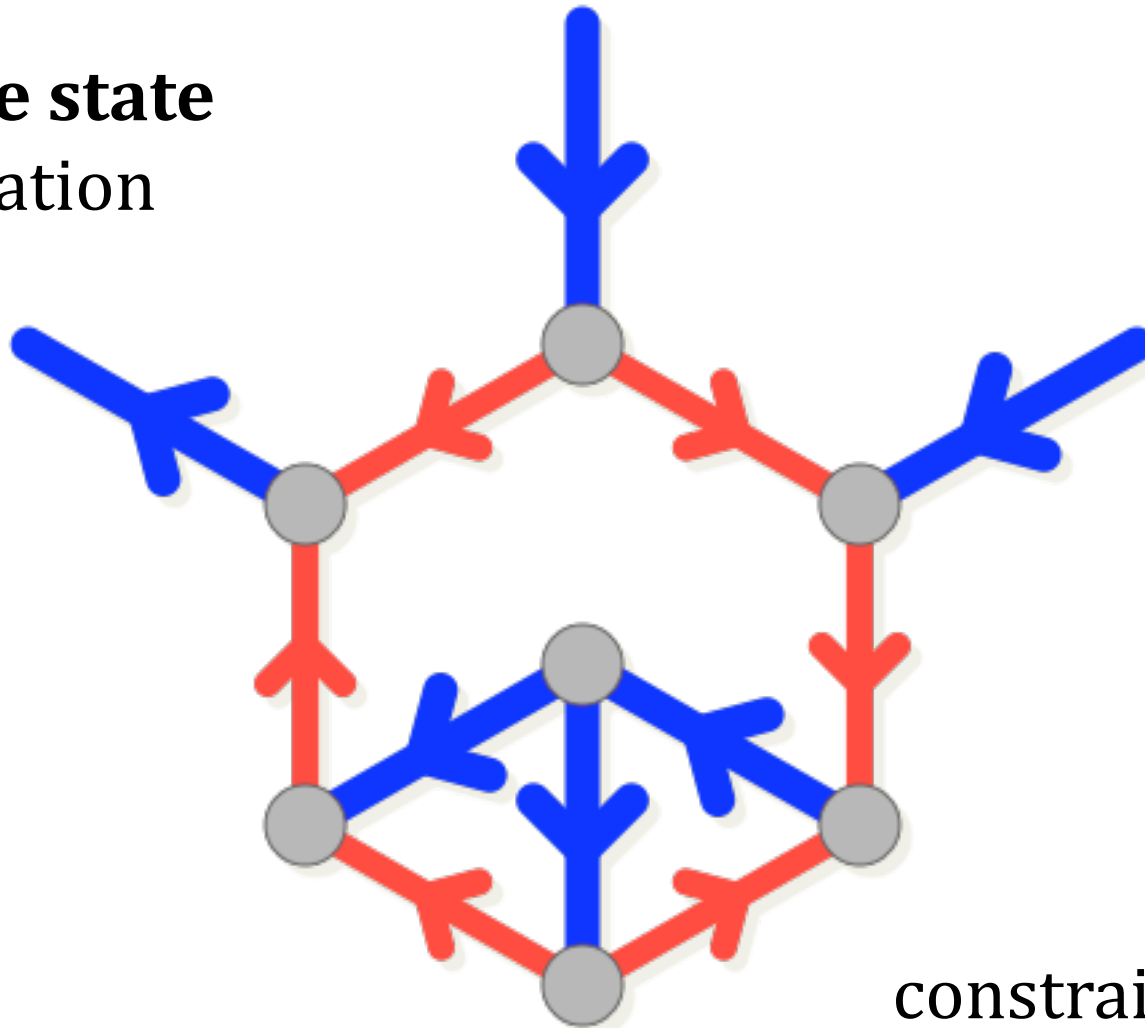
Machine = graph,
red & blue edges





Constraint Graphs

Machine state
= orientation



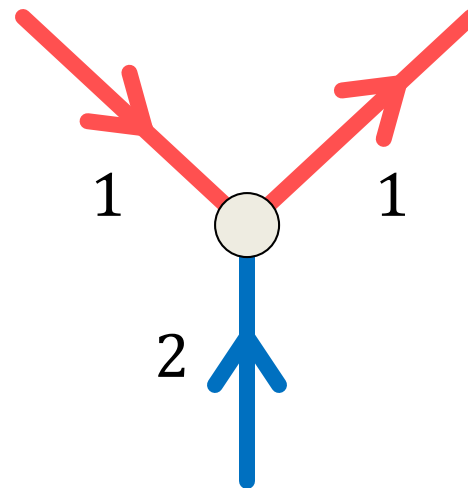
constraint graph



Constraint Logic

 = 1

 = 2



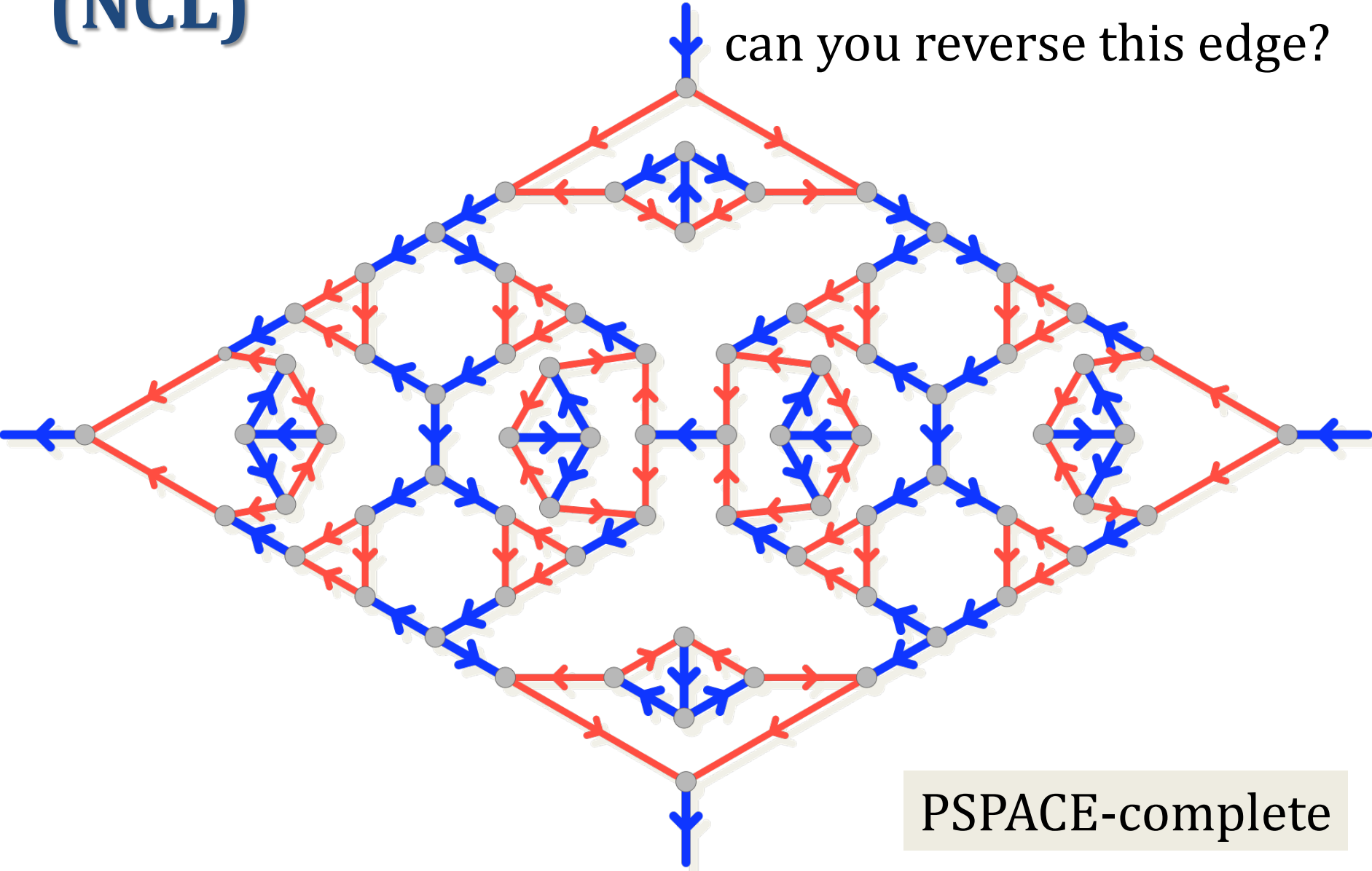
Rule: at least 2 units incoming at a vertex

Move: reverse an edge, preserving Rule



Nondeterministic Constraint Logic (NCL)

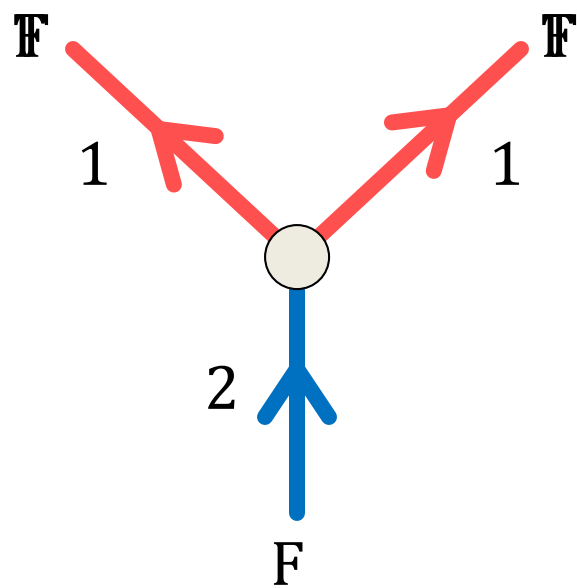
can you reverse this edge?



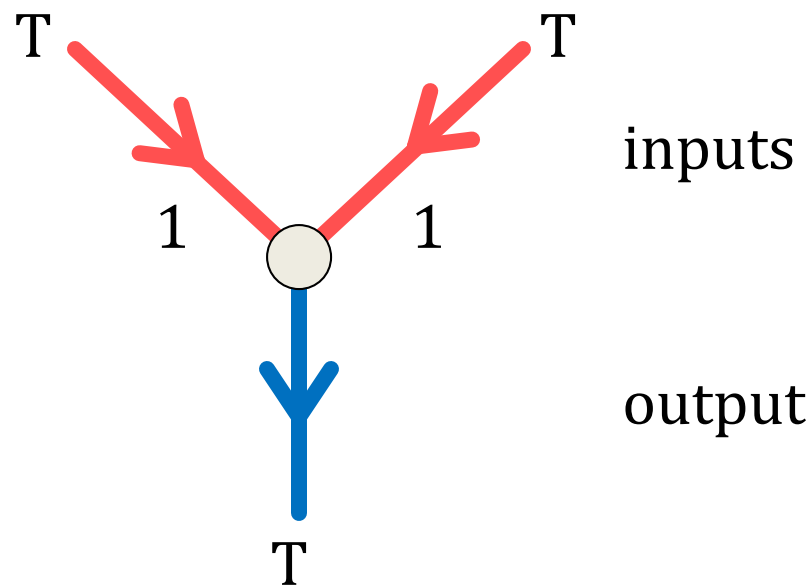
PSPACE-complete



AND vertex



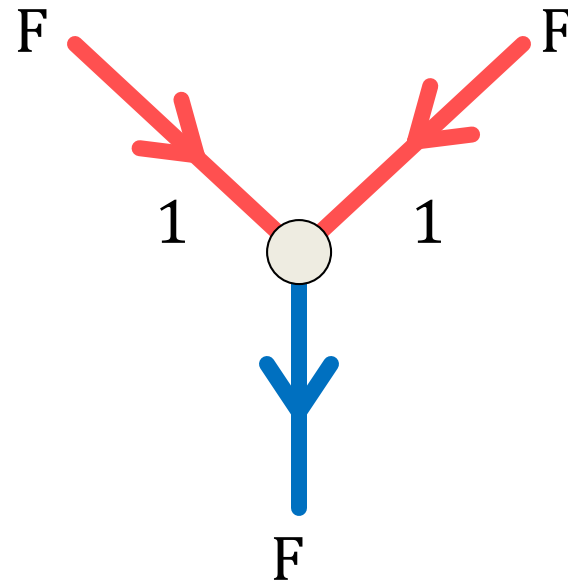
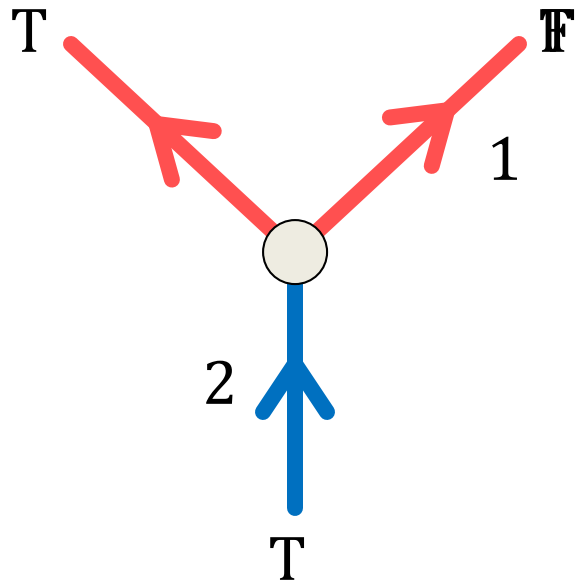
not your usual
AND gate!



Rule: at least 2 units
incoming at a vertex



SPLIT vertex



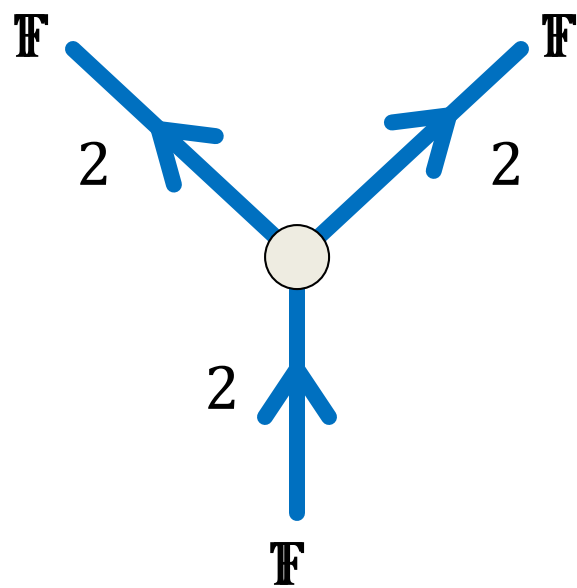
outputs

input

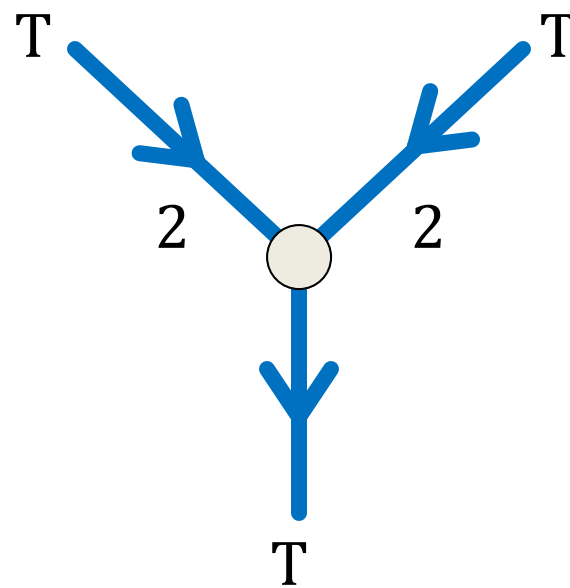
Rule: at least 2 units incoming at a vertex



OR vertex



not your usual
OR gate!



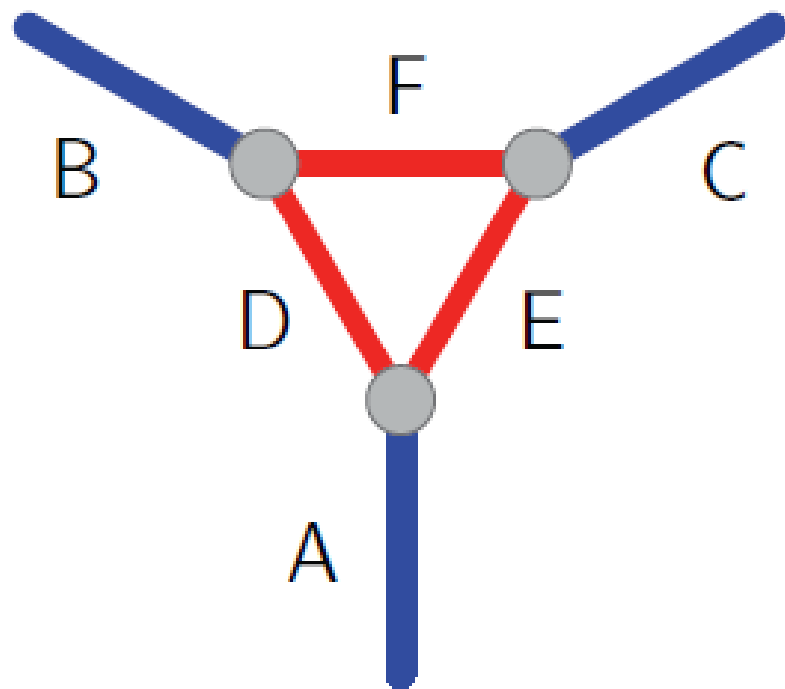
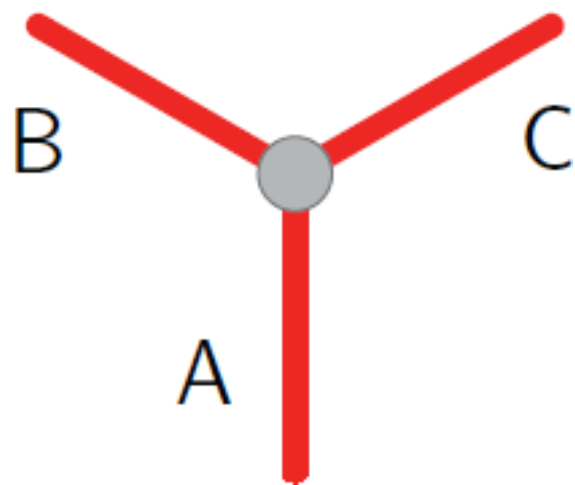
inputs

output

Rule: at least 2 units
incoming at a vertex

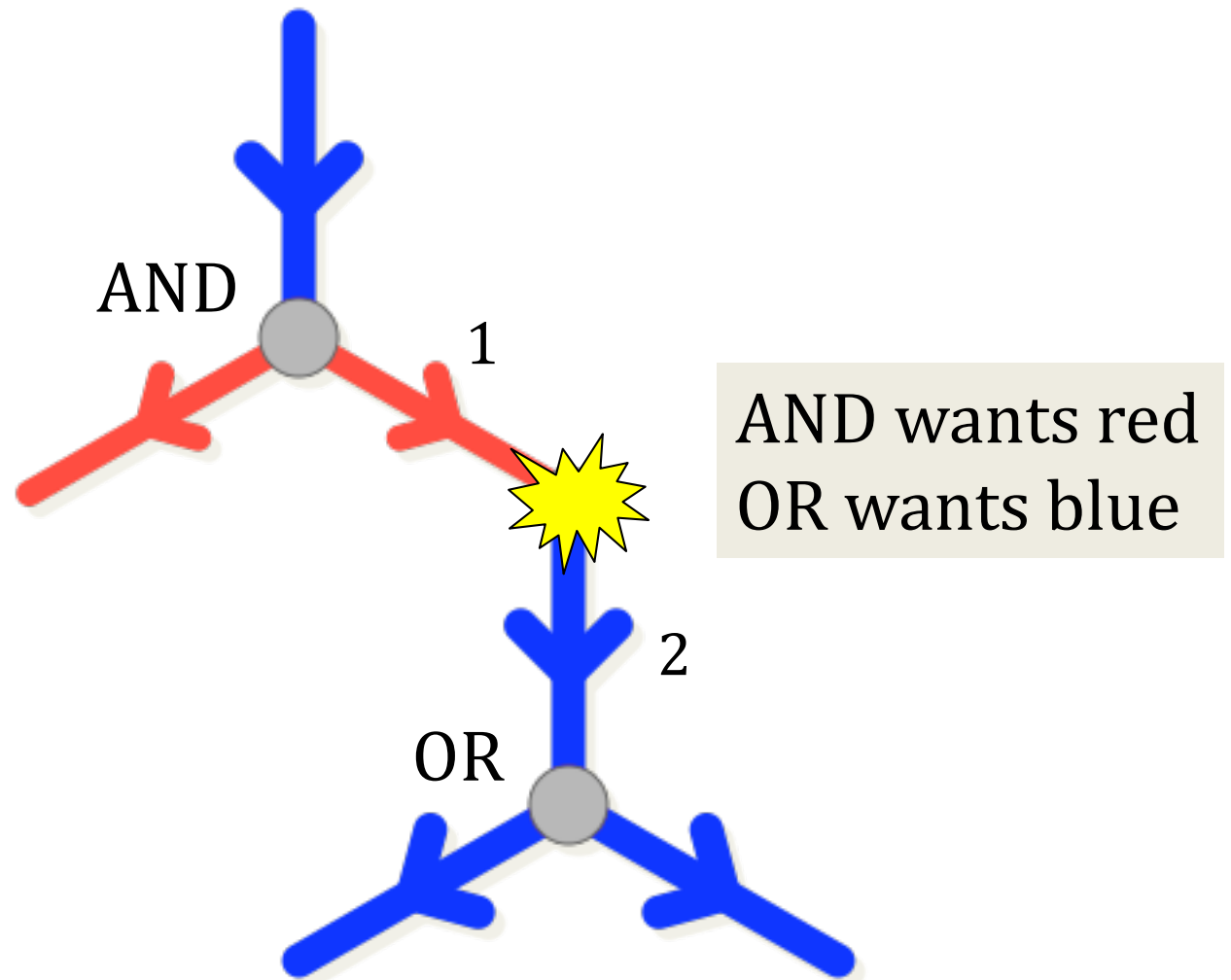


CHOICE vertex





Wiring Vertices Together





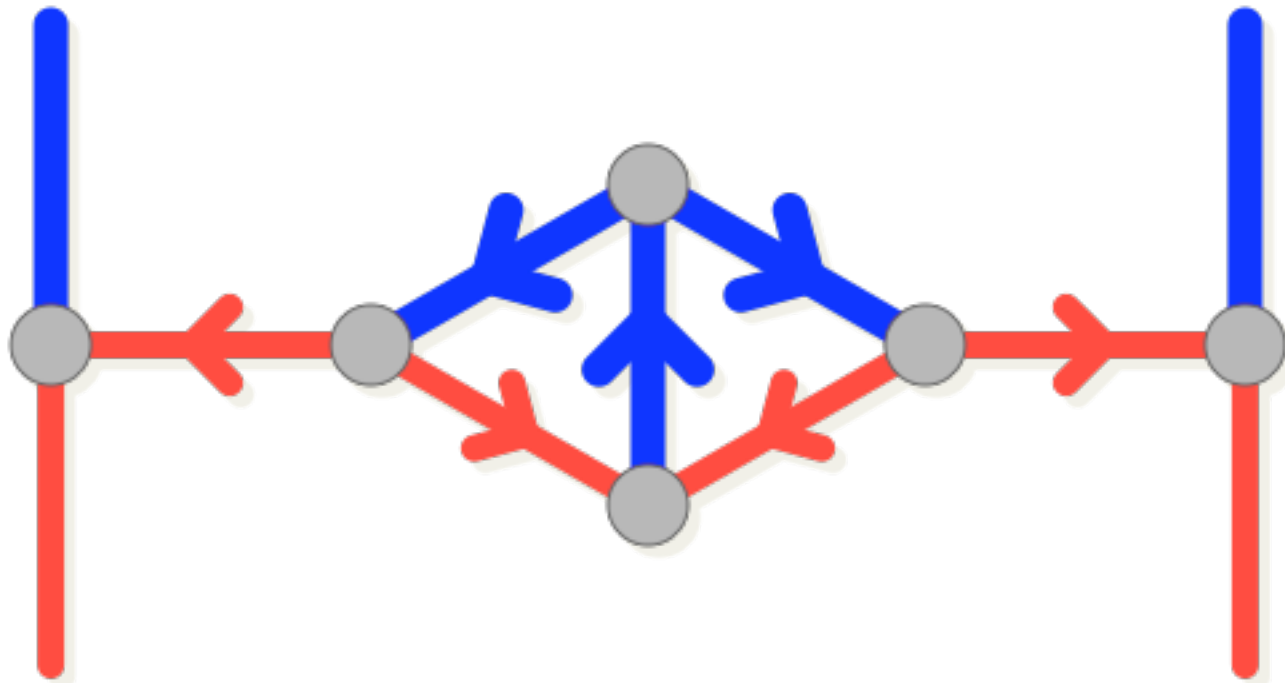
Red-Blue Conversion



assume an even number of conversions



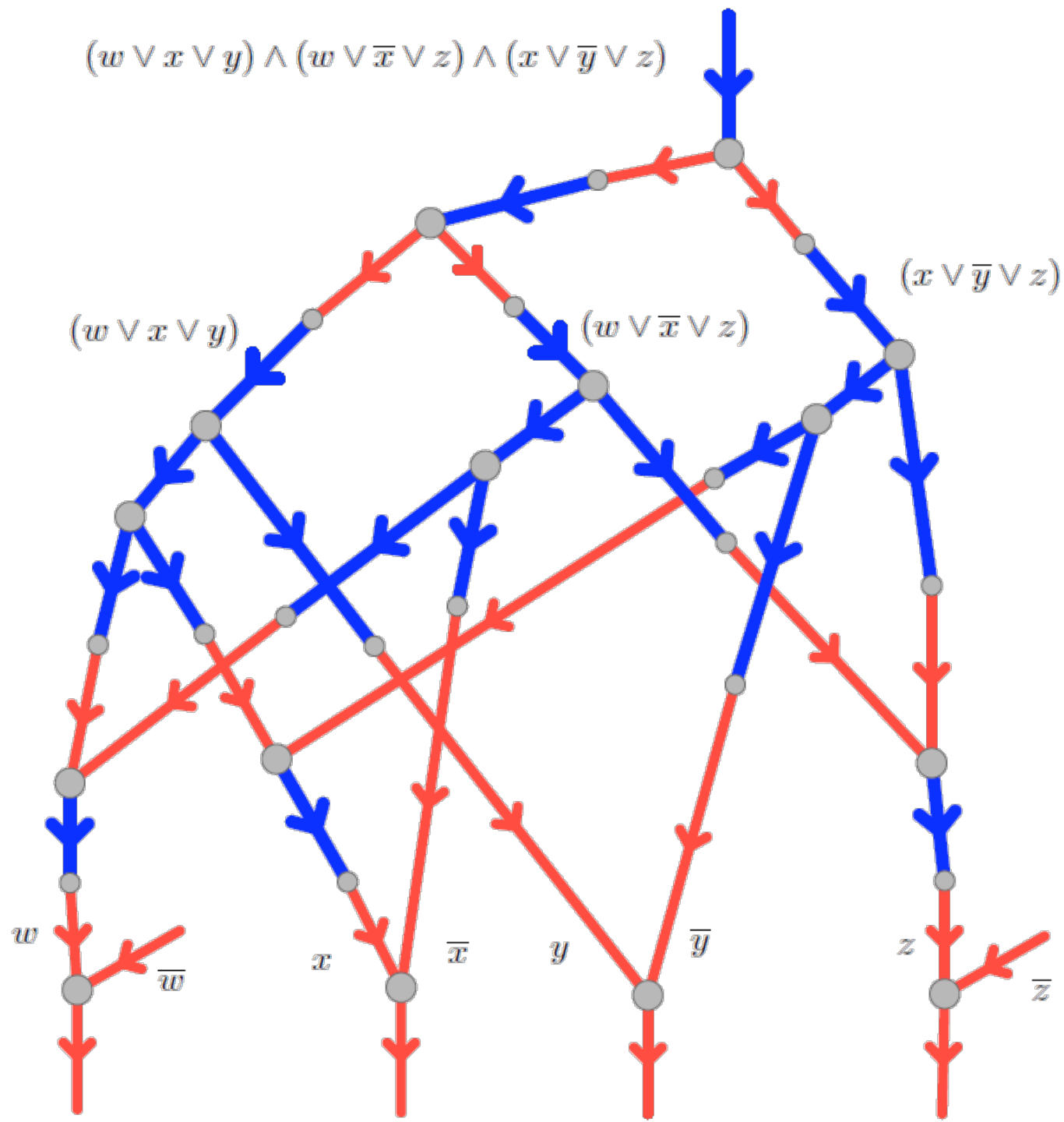
Red-Blue Conversion



assume an even number of conversions

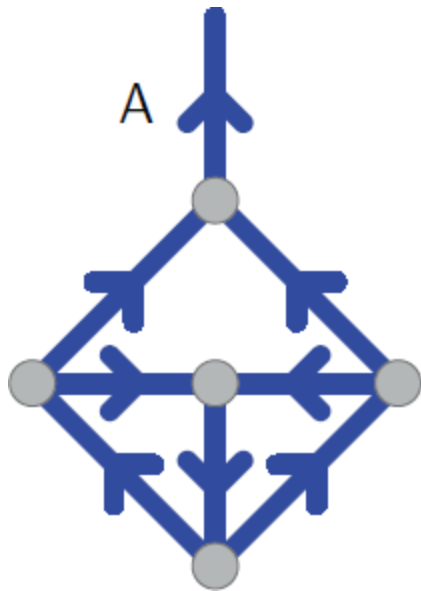


CNF Formula

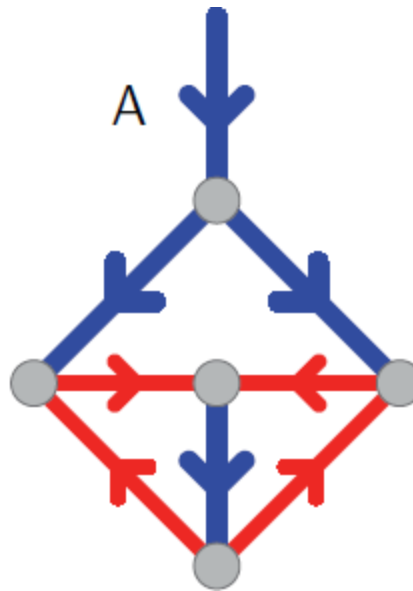




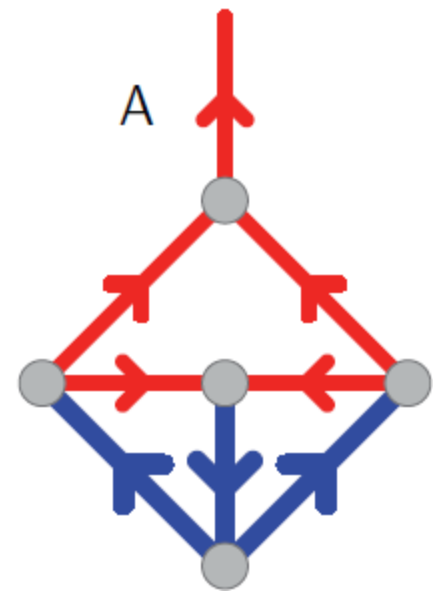
Wire Terminators



unconstrained
blue terminator



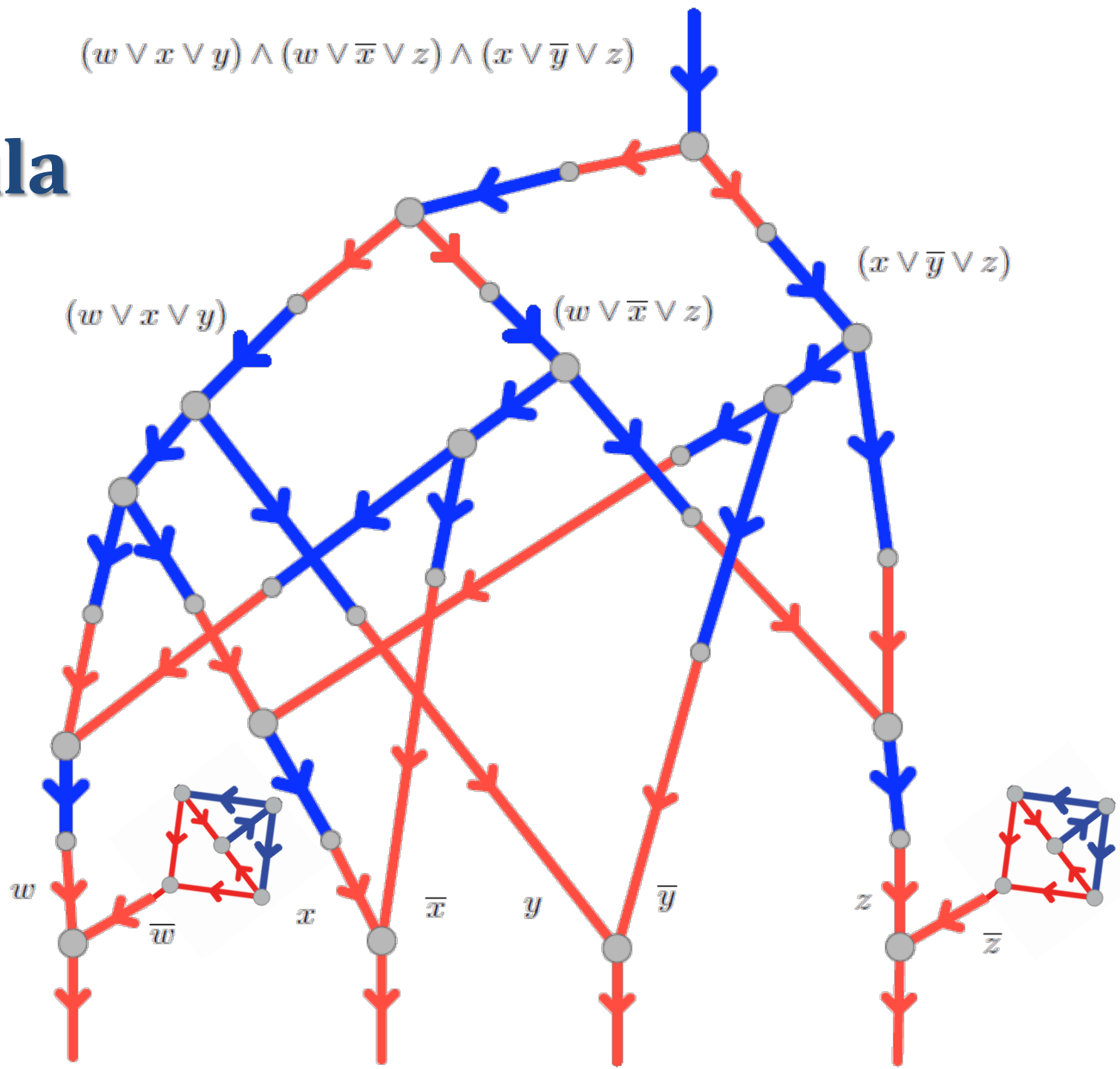
forced-inward
blue terminator



unconstrained
red terminator

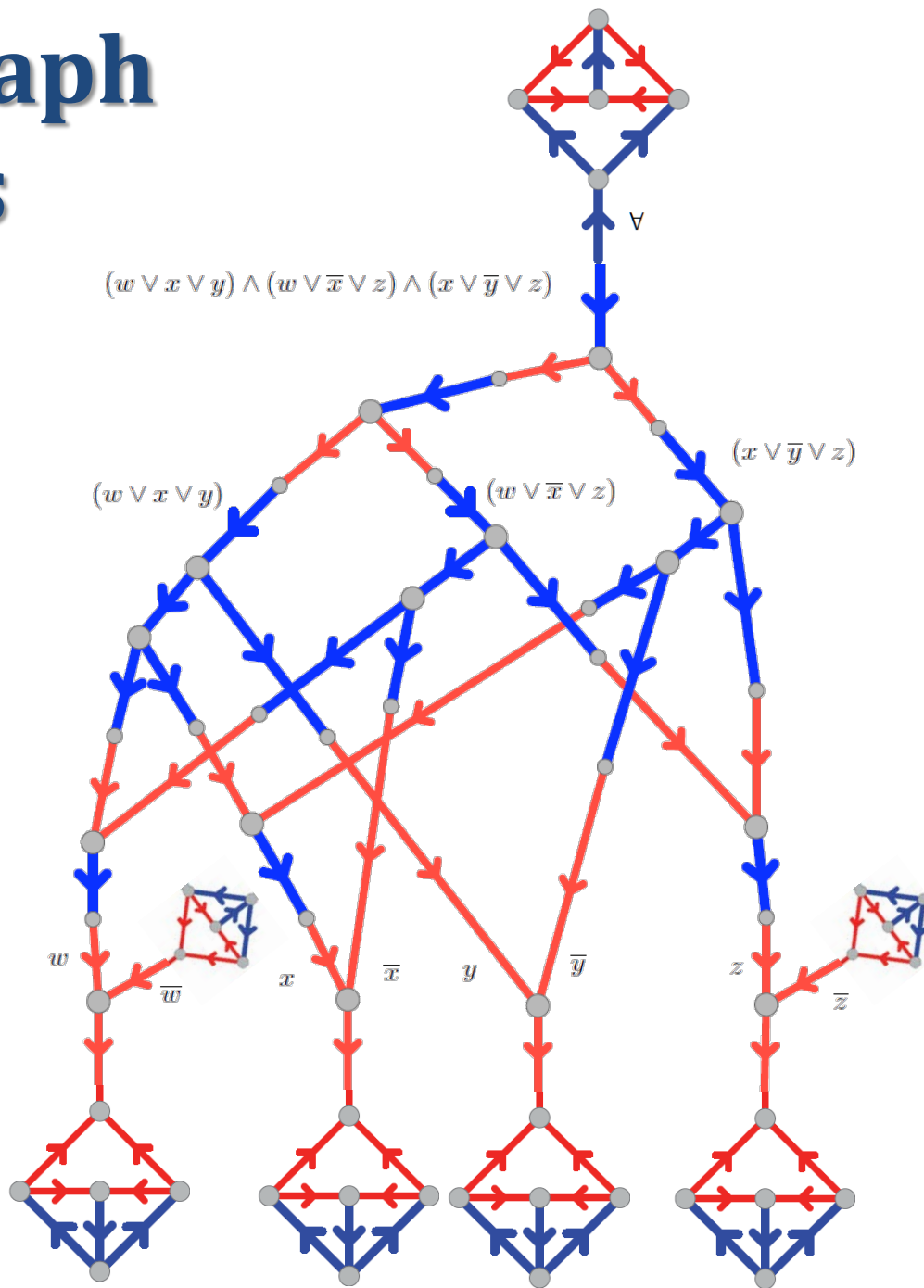


CNF Formula





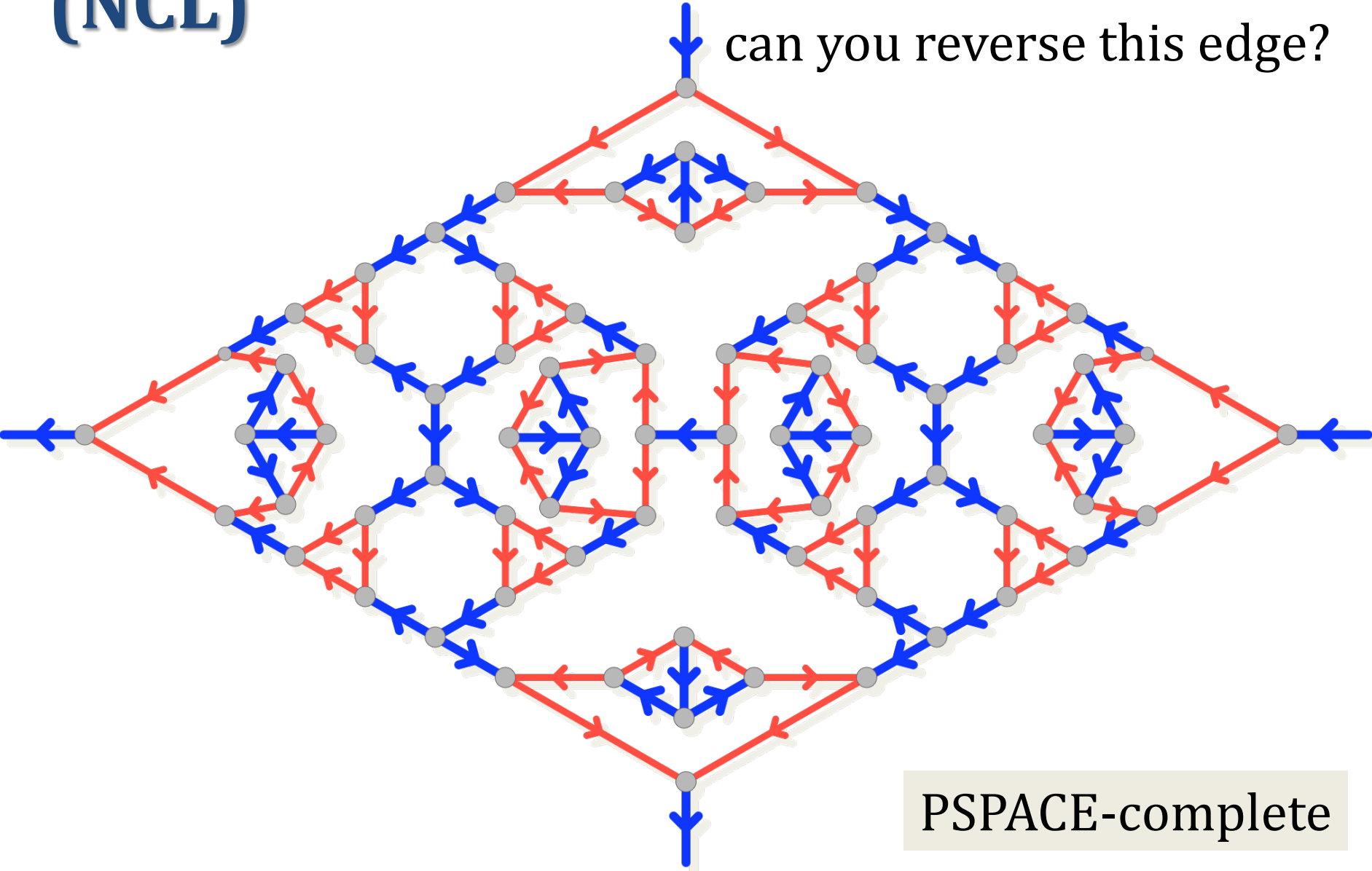
Constraint Graph Satisfaction is NP-complete





Nondeterministic Constraint Logic (NCL)

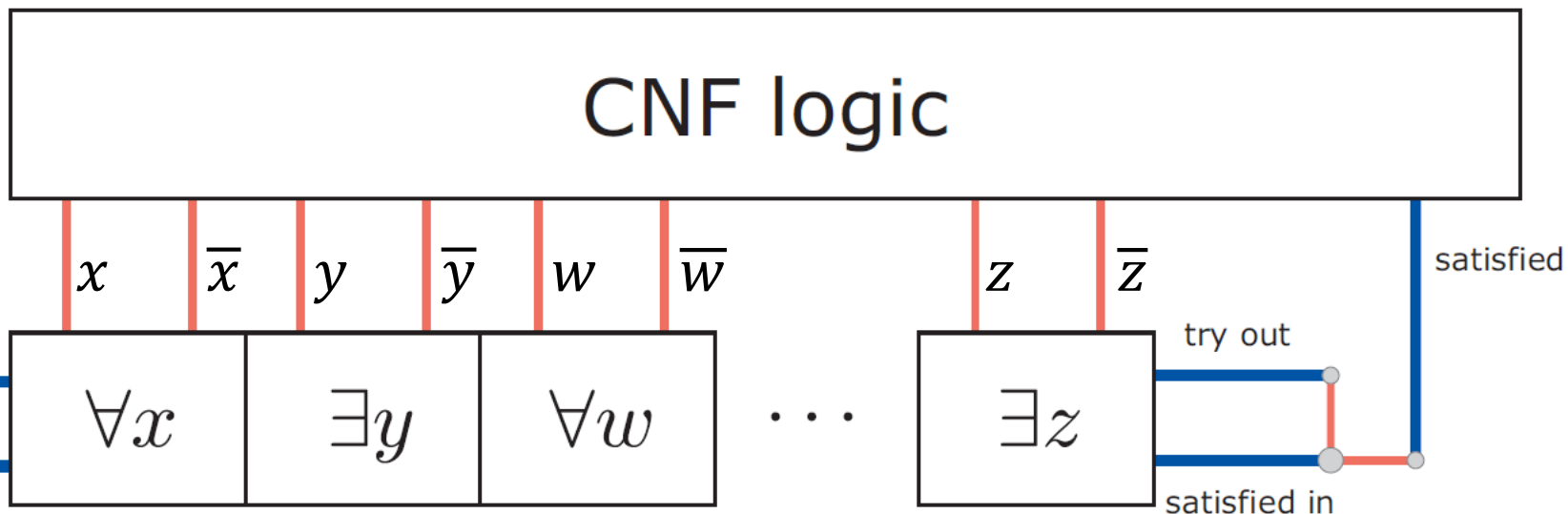
can you reverse this edge?



PSPACE-complete

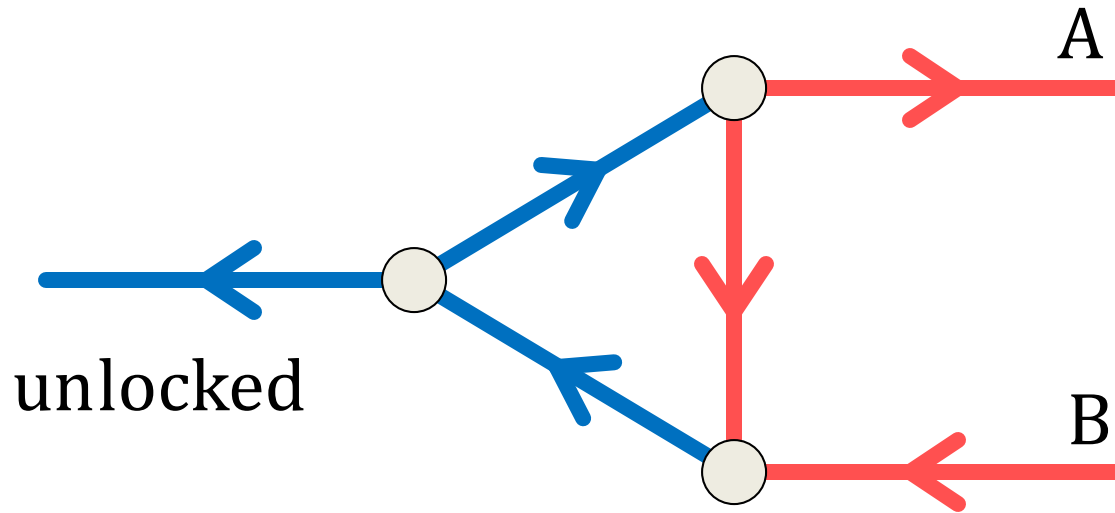
Quantified Boolean Formulas (QBF/QSAT)

$$\forall x \exists y \forall w \cdots \exists z [(x \vee y) \wedge \cdots \wedge (\bar{z} \vee x \vee \bar{w})]$$



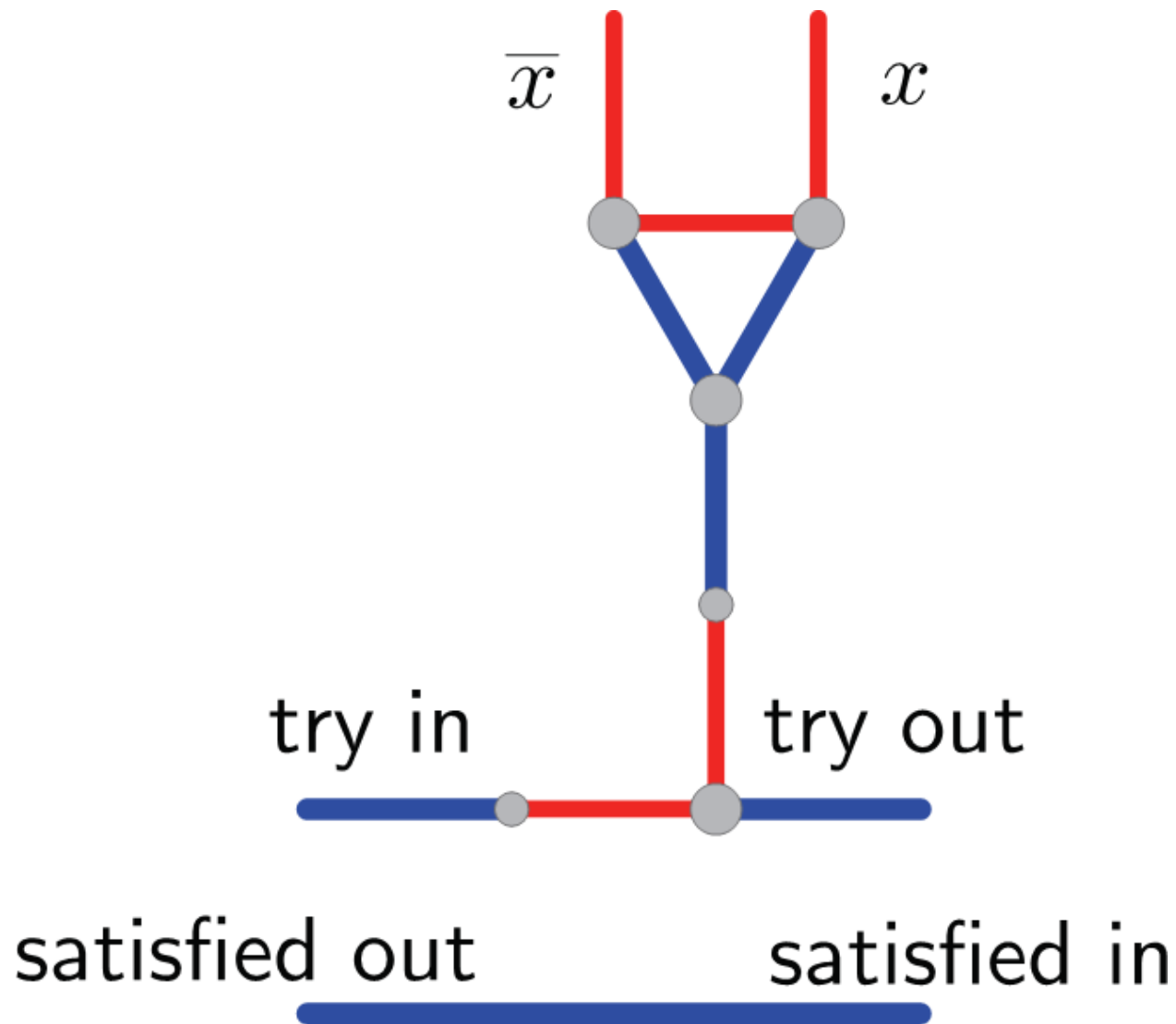


Latch



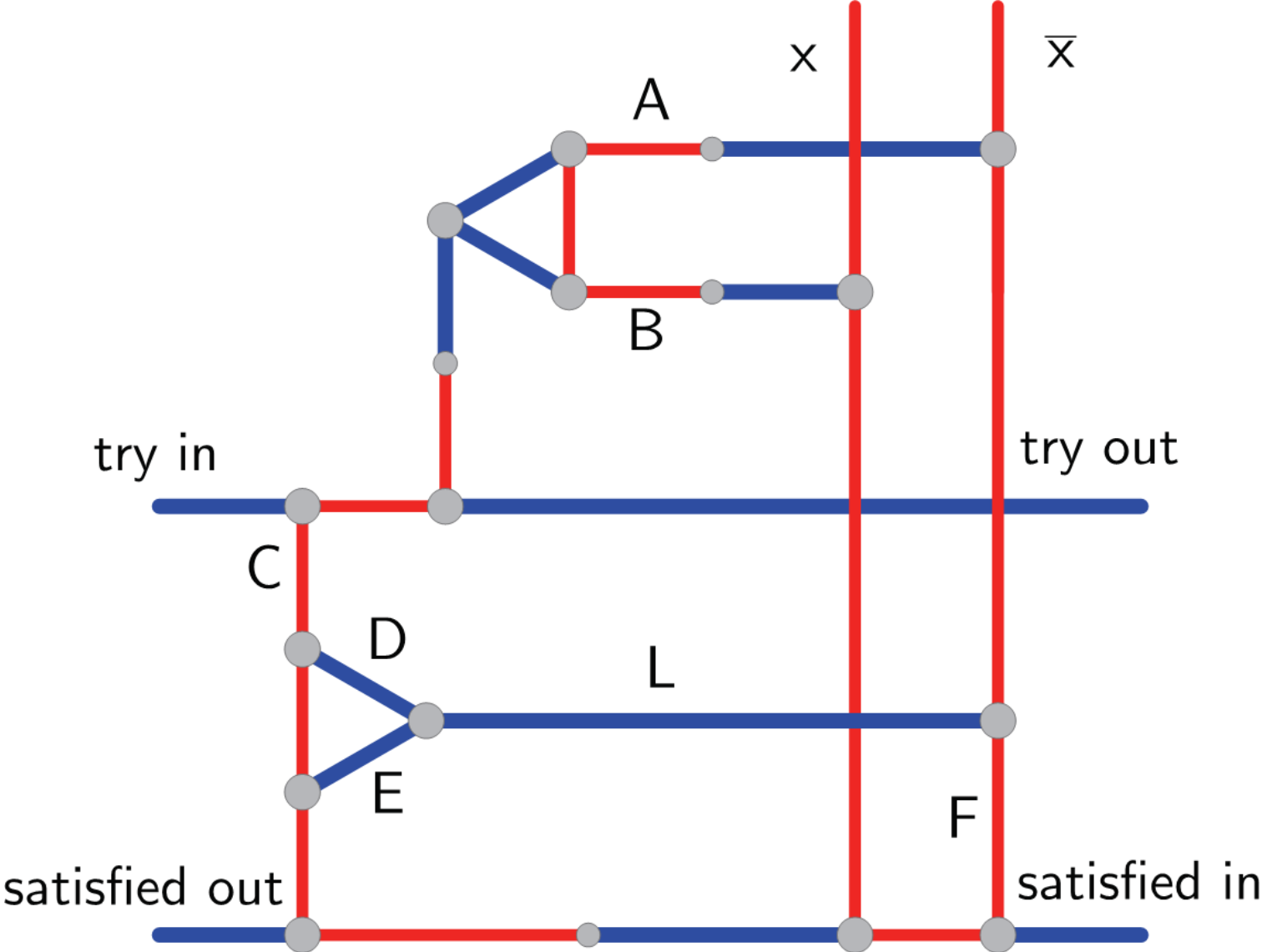


Existential Quantifier



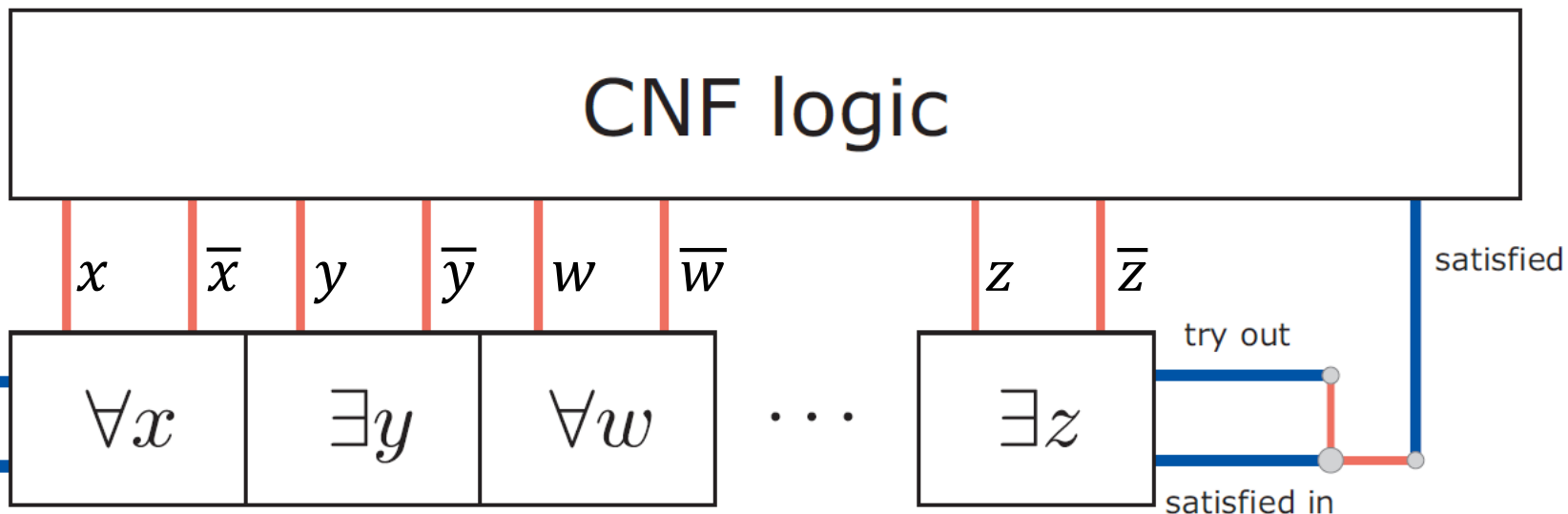


Universal Quantifier



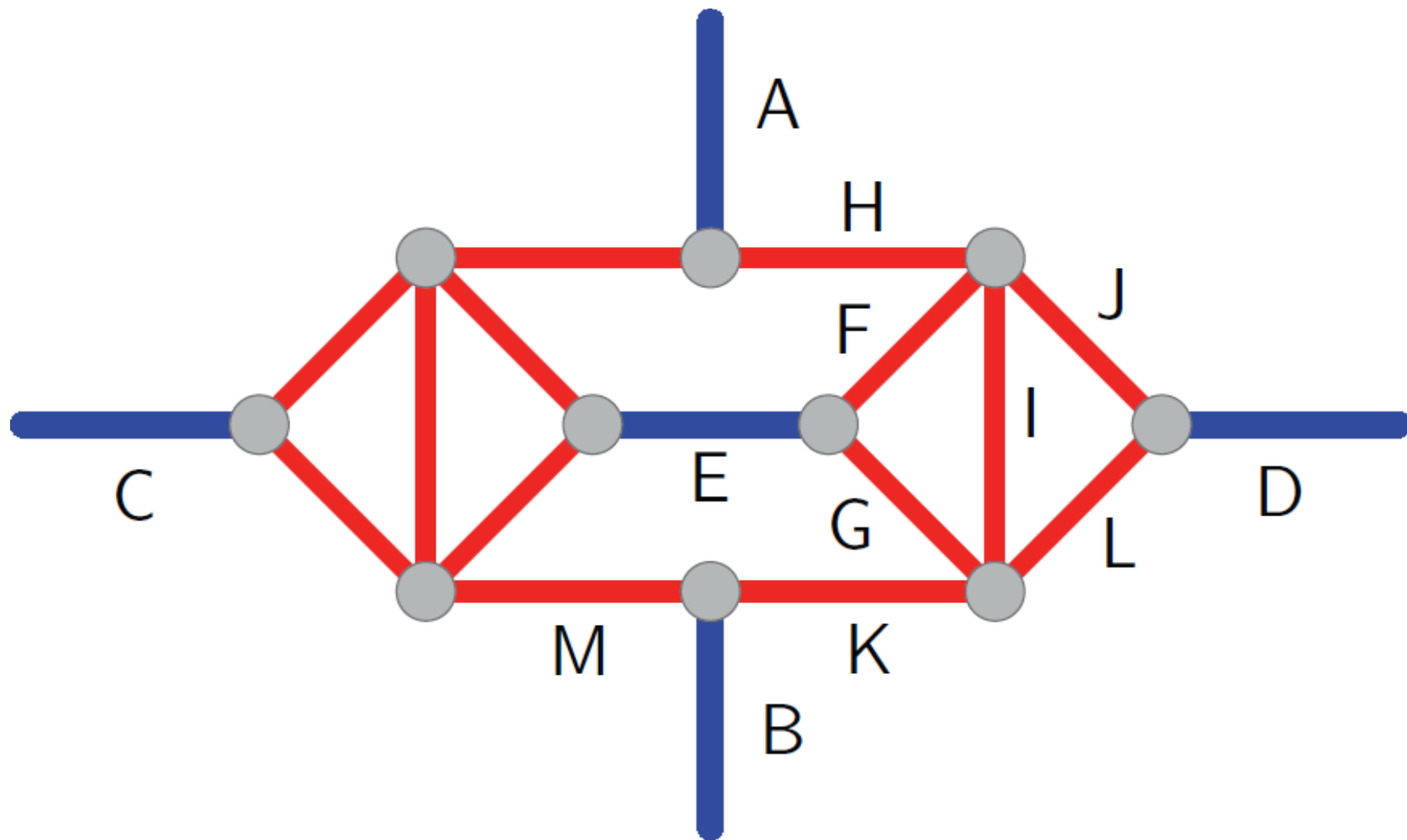
Quantified Boolean Formulas (QBF/QSAT)

$$\forall x \exists y \forall w \dots \exists z [(x \vee y) \wedge \dots \wedge (\bar{z} \vee x \vee \bar{w})]$$



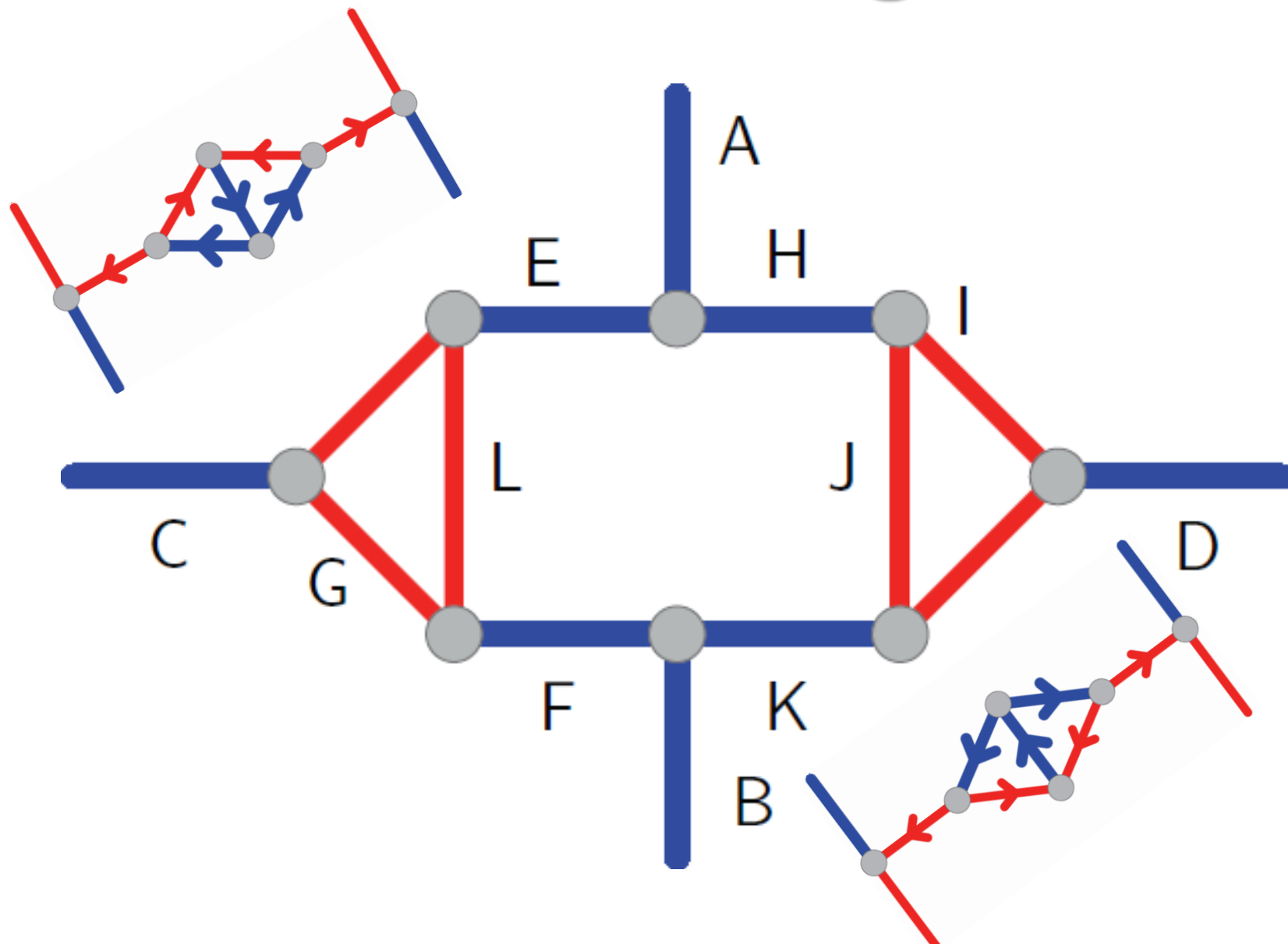


Crossover Gadget



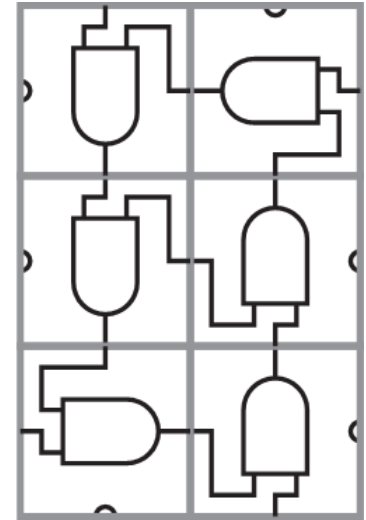
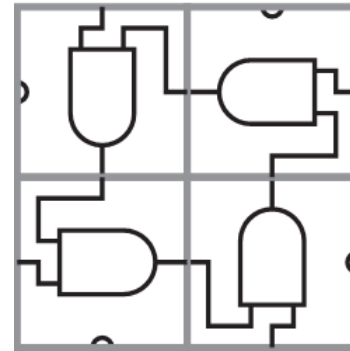


Vertex with 4 Red Edges



Grid Constraint Graphs: Straights & Turns

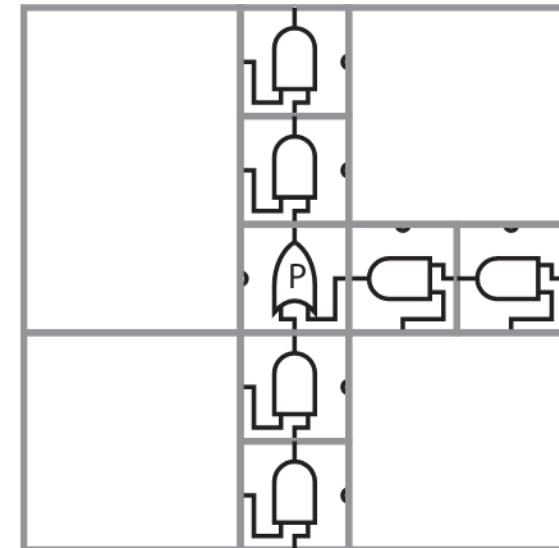
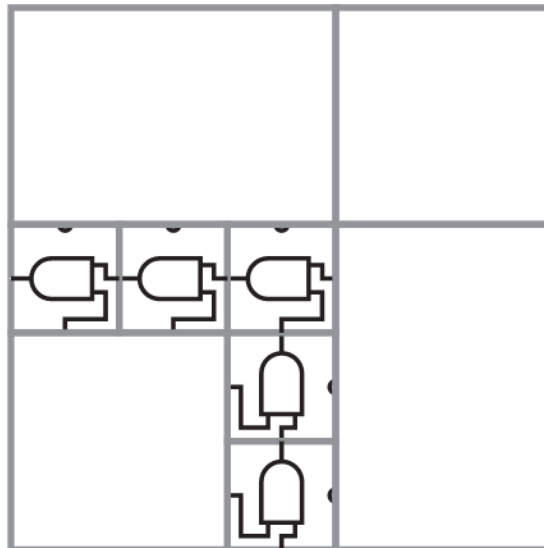
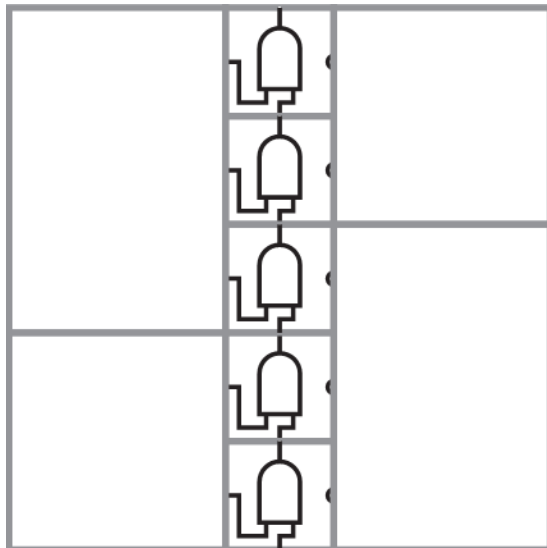
filler



straight

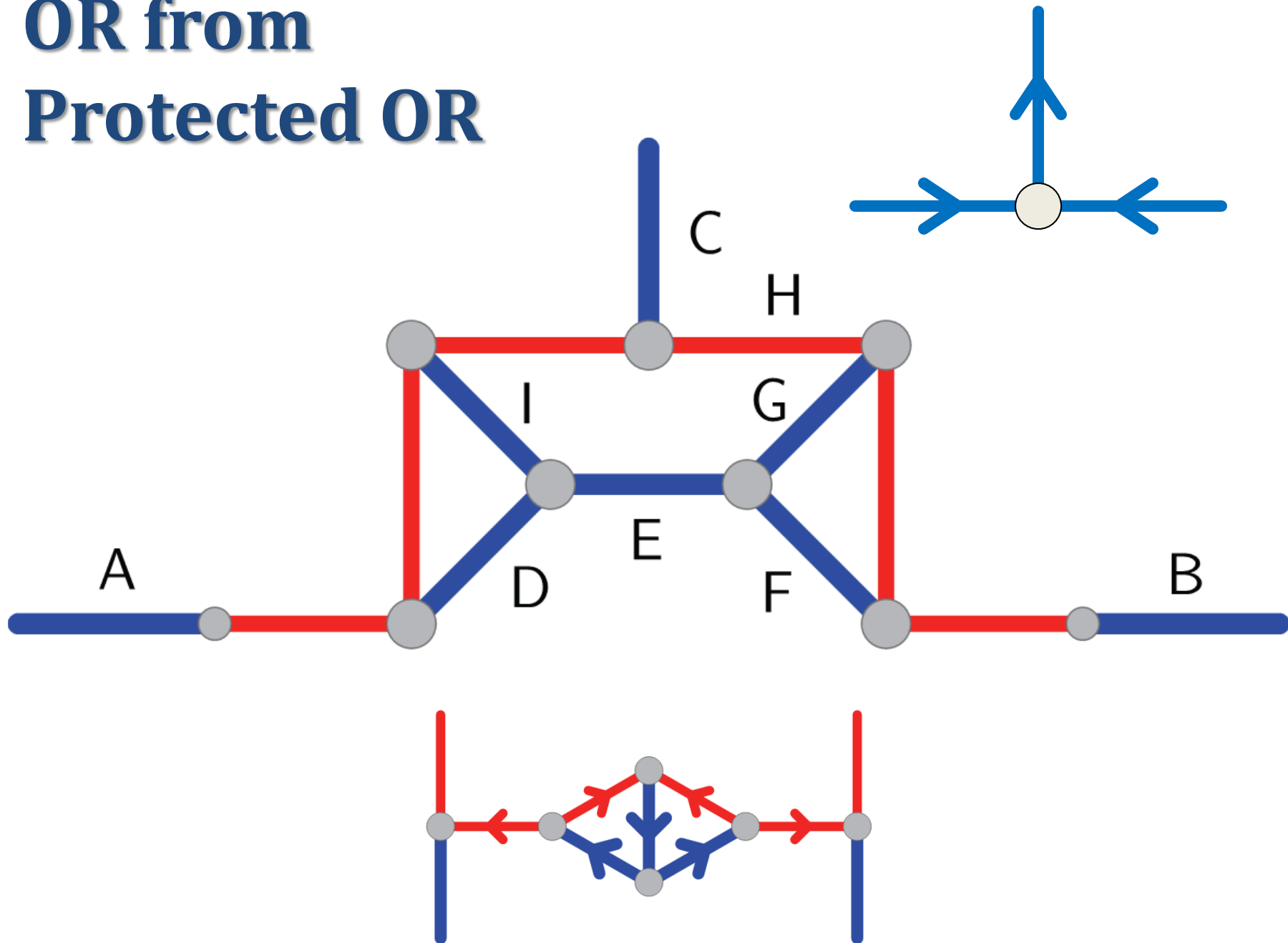
turn

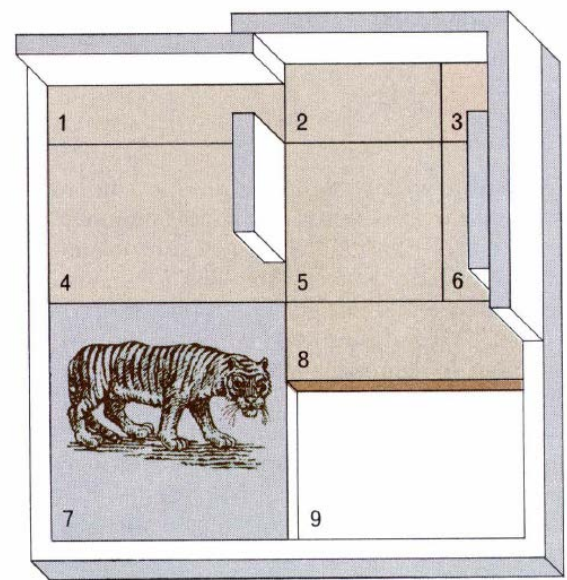
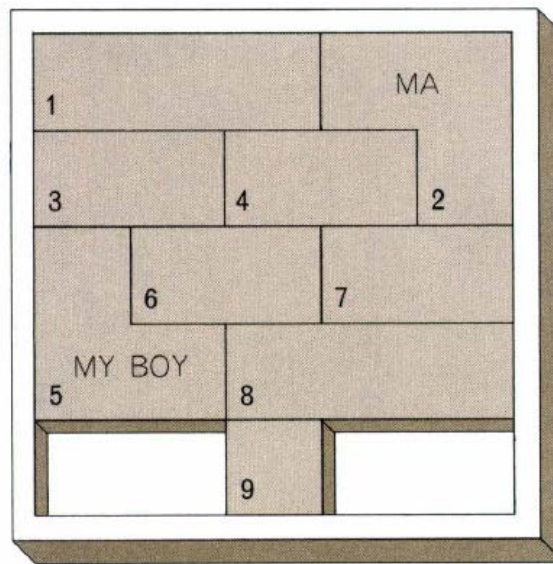
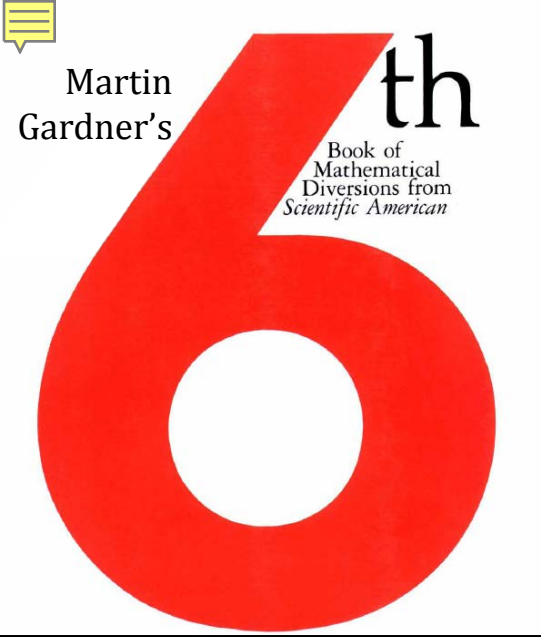
OR





OR from Protected OR



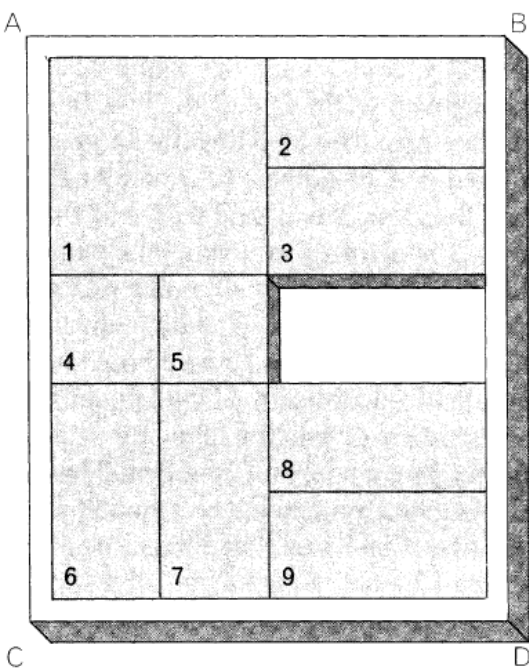
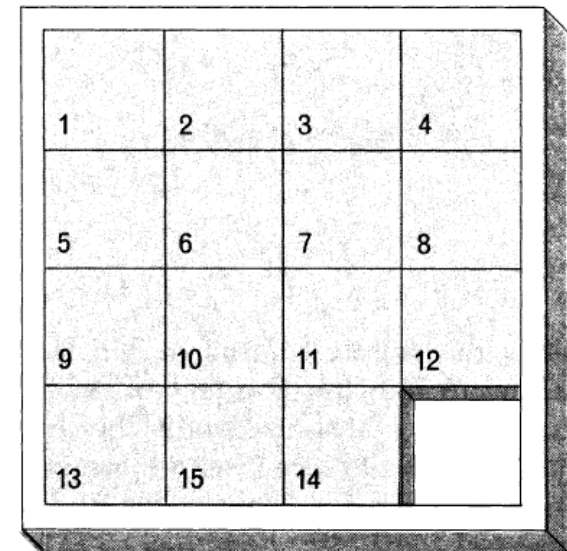
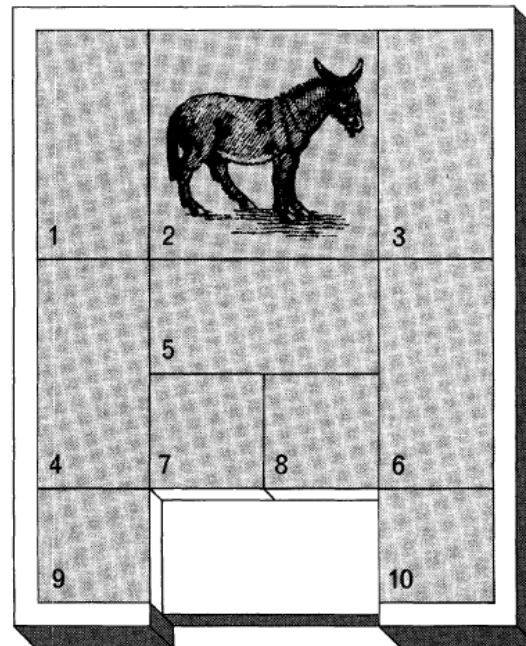


Ma's Puzzle

L'Ane Rouge

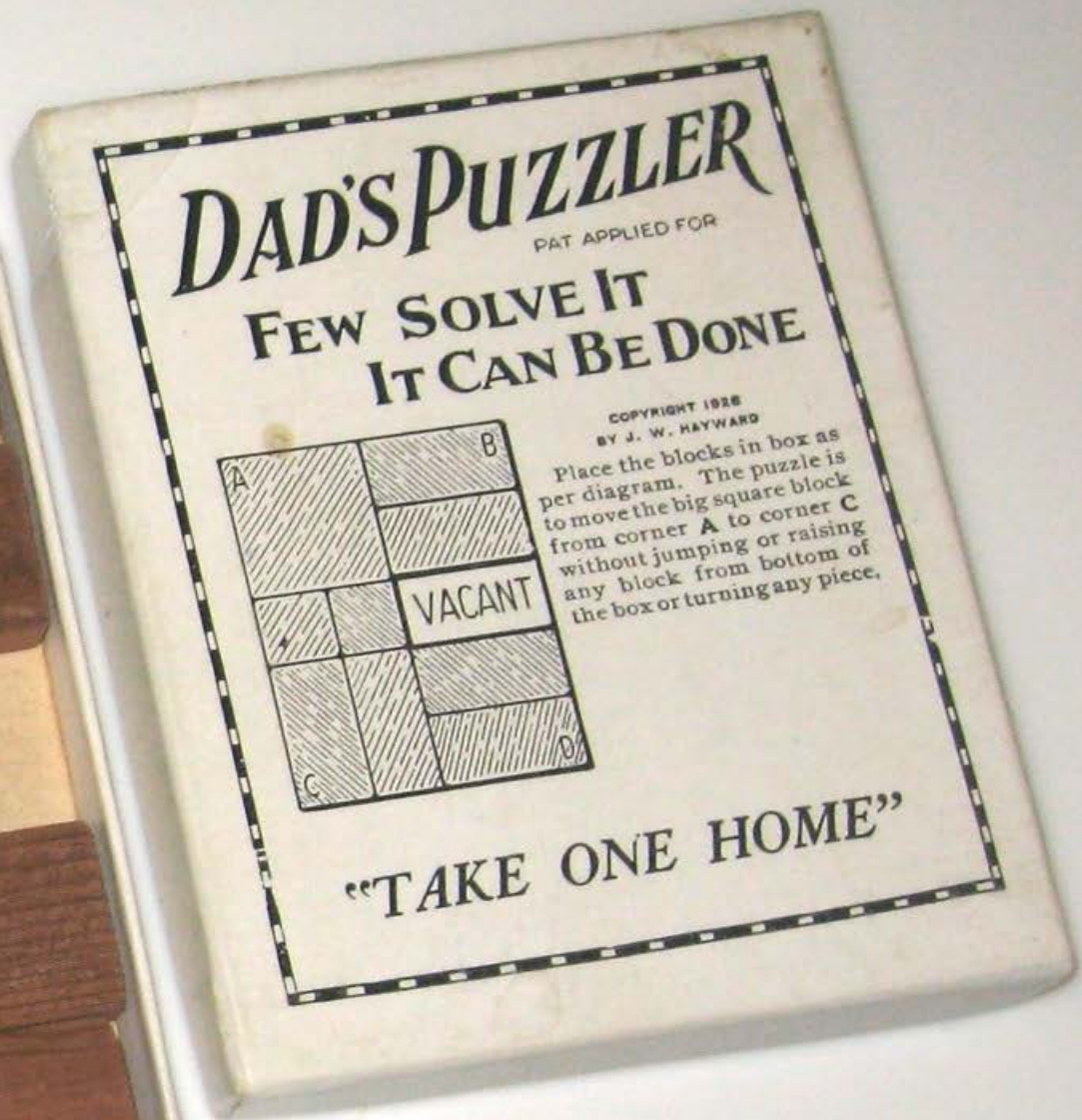
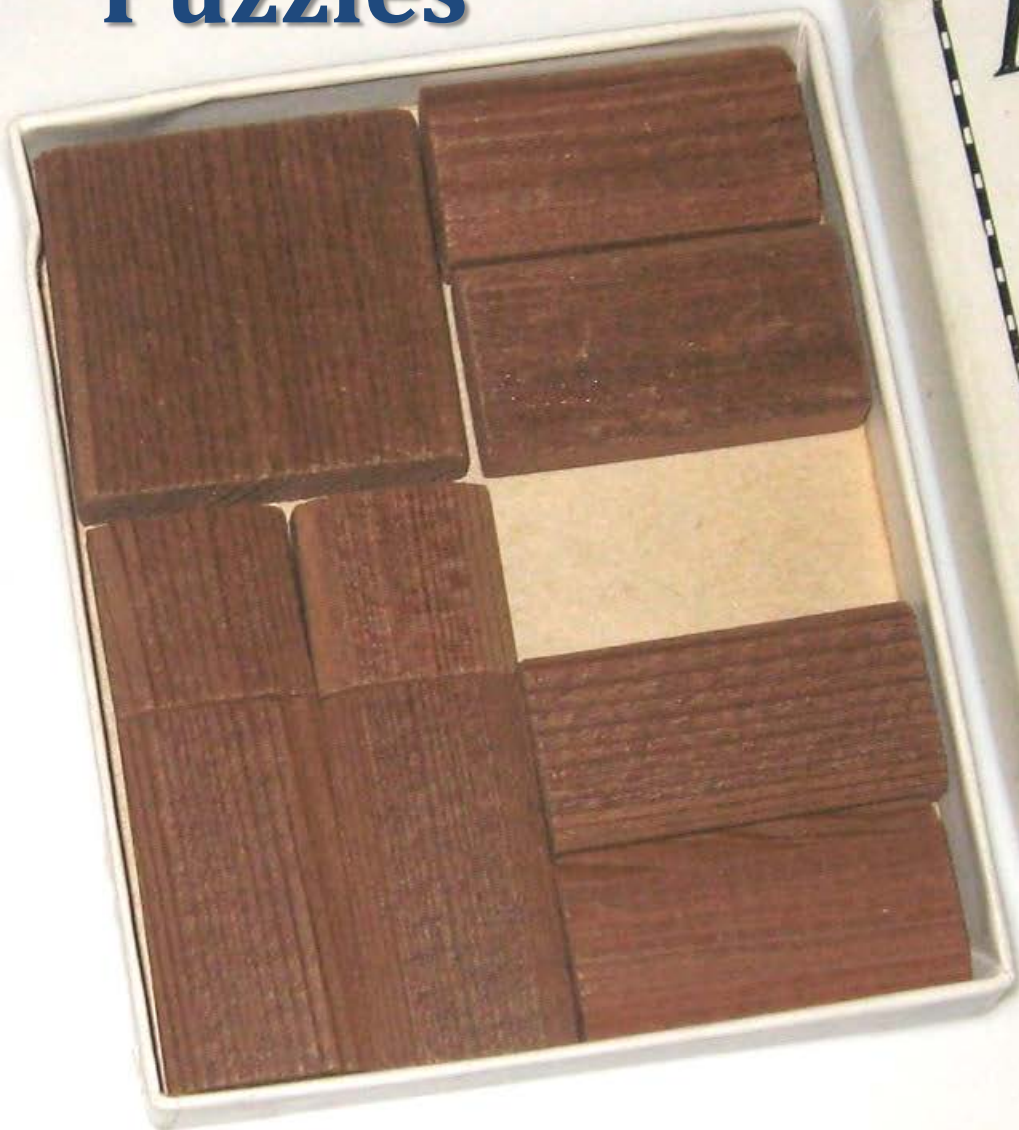
7. Sliding-Block Puzzles

Sam Loyd's 15 Puzzle



Dad's Puzzle (1926)

Sliding-Block Puzzles



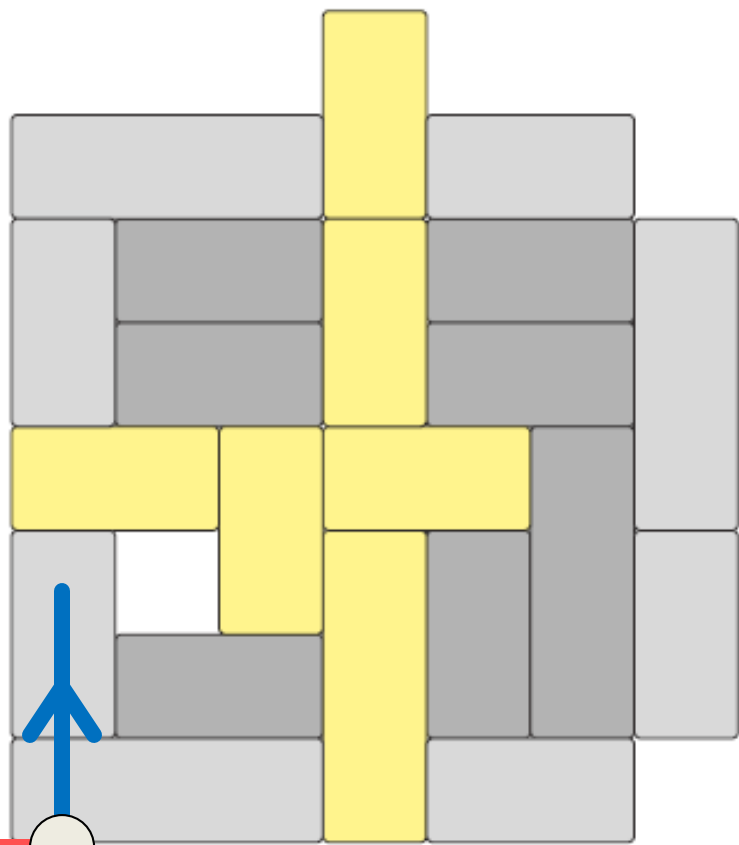
1926
83 moves



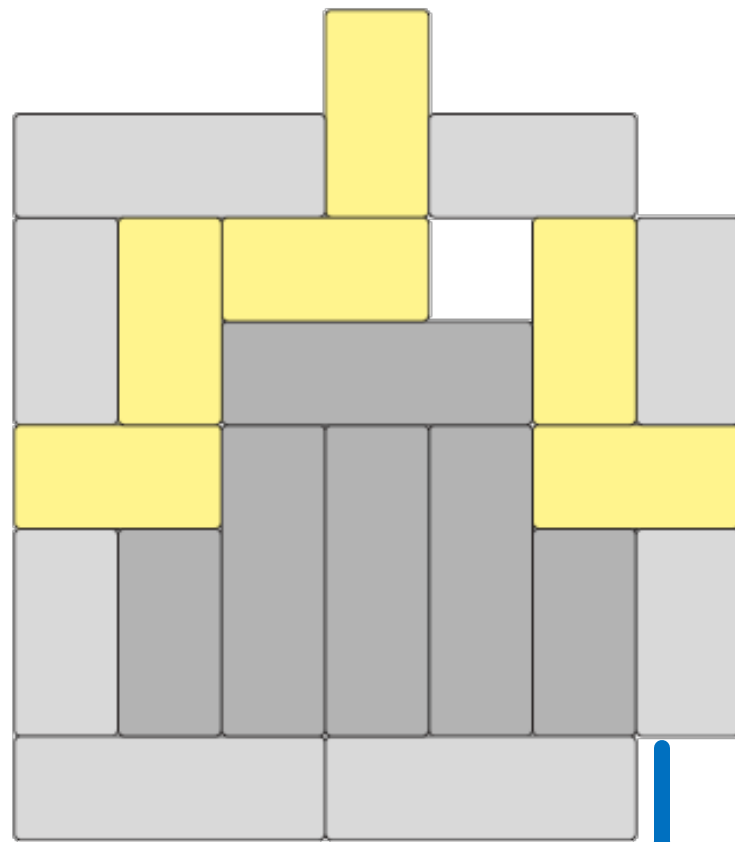
Sliding-Block Puzzles

[Hearn & Demaine 2002]

PSPACE-complete



(a) AND

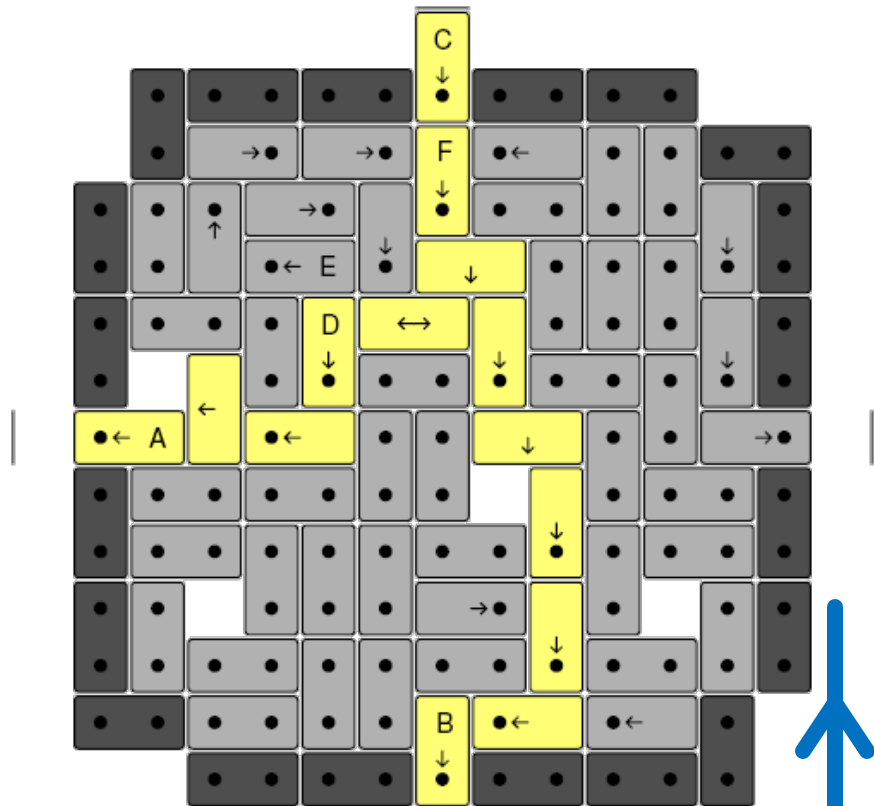


(b) OR

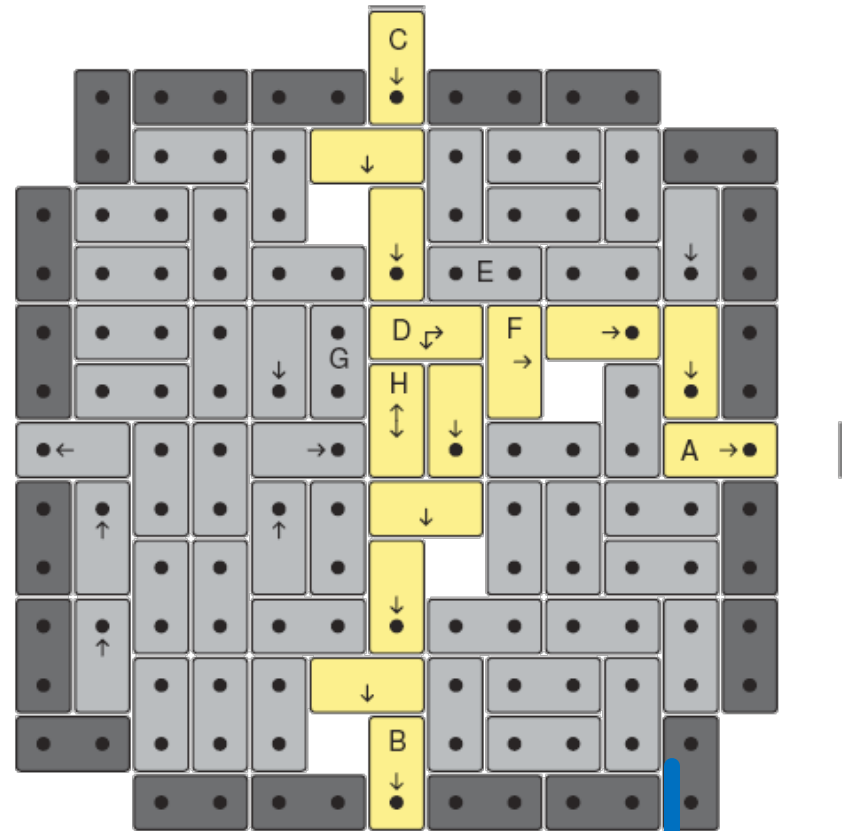
Sliding-Block Puzzles

[Hearn & Demaine 2002]

PSPACE-complete



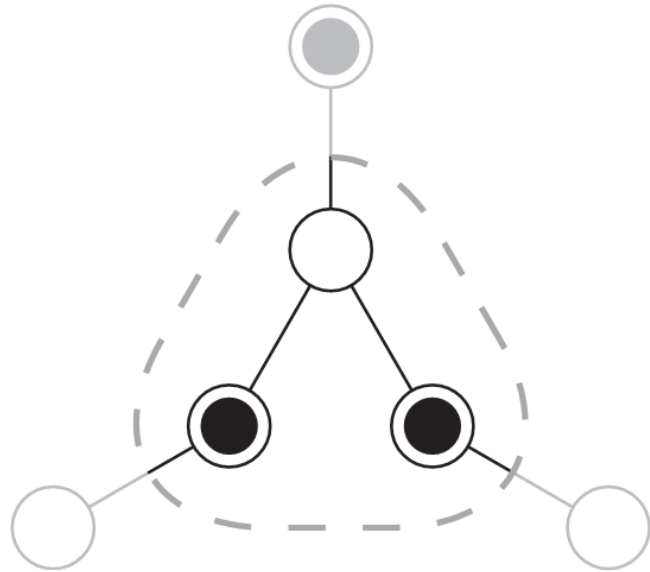
(a) AND



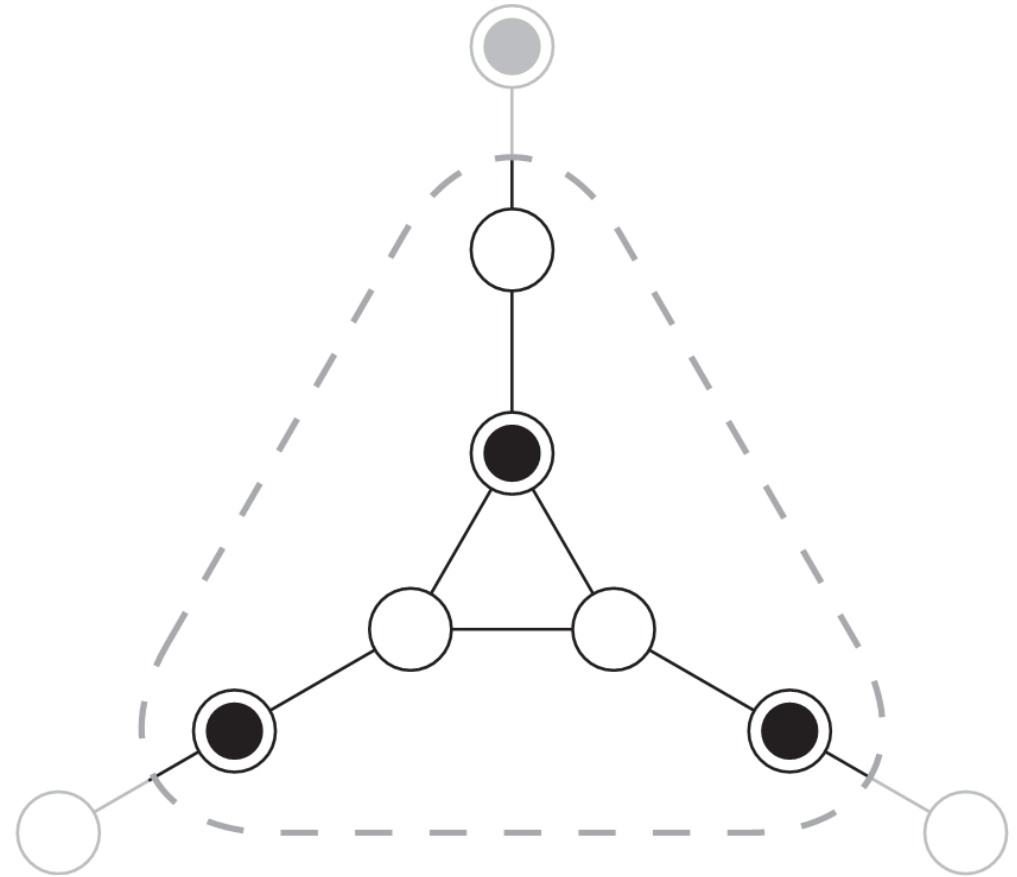
(b) Protected OR



Sliding Tokens (Reconfiguration Independent Set)



(a) AND

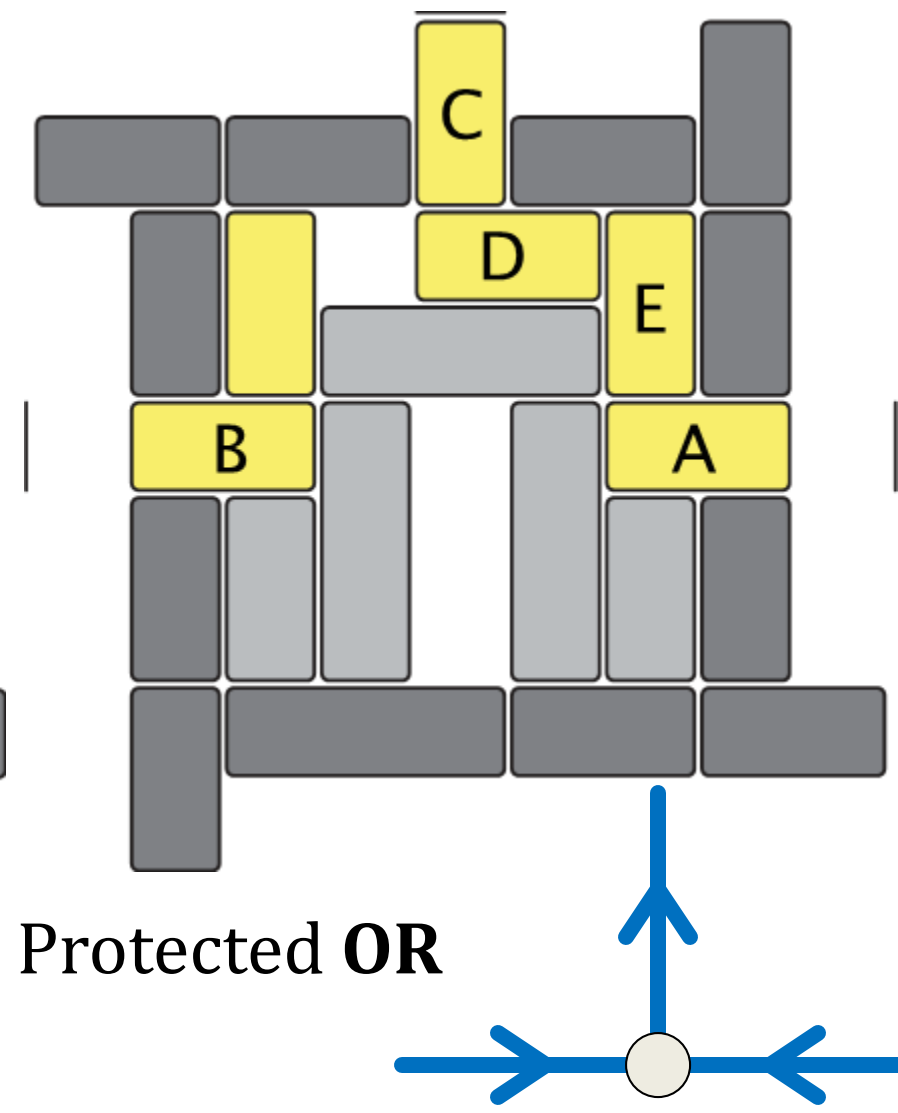
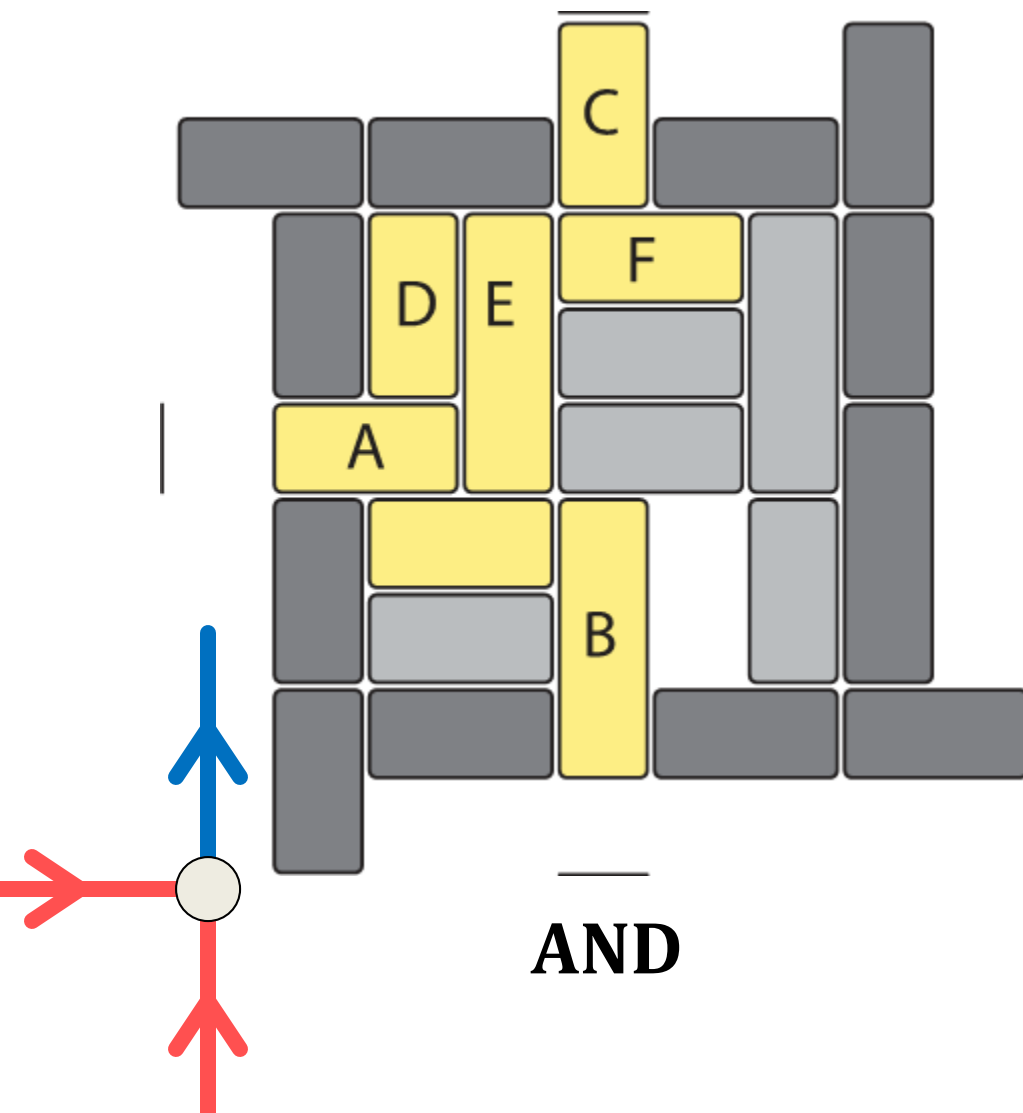


(b) OR



Rush Hour is PSPACE-complete

[Flake & Baum 2002; Hearn & Demaine 2002]



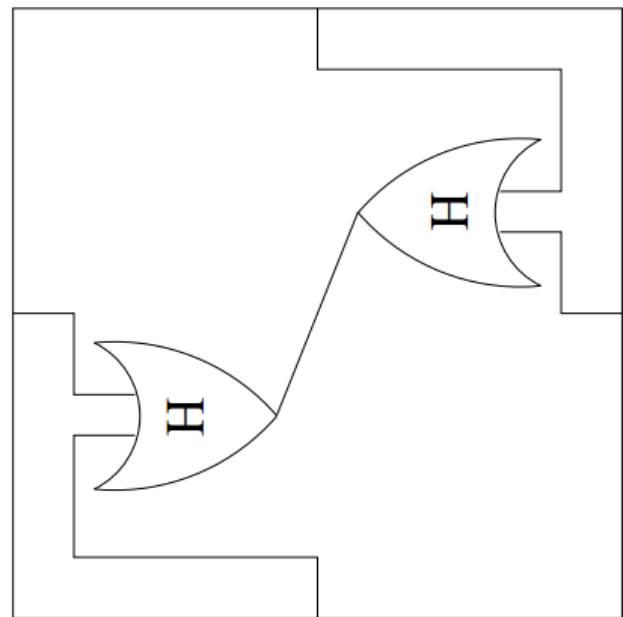
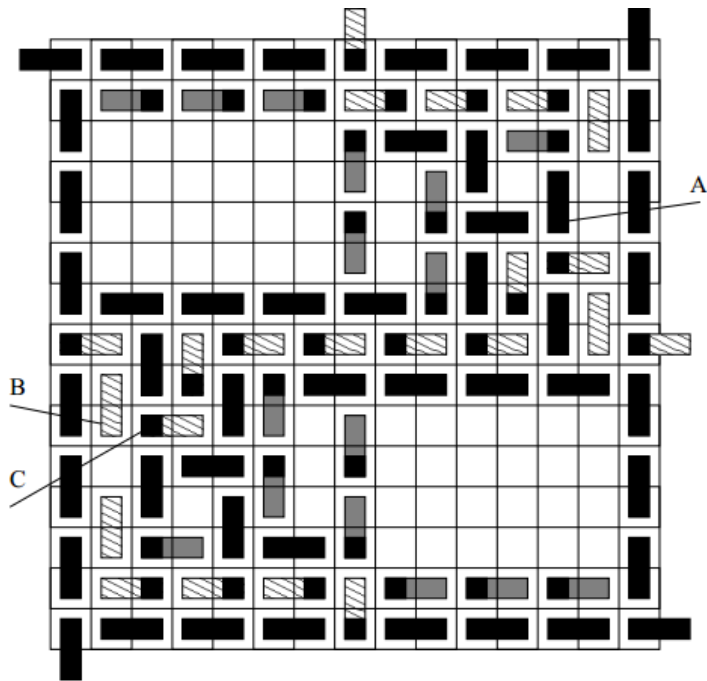
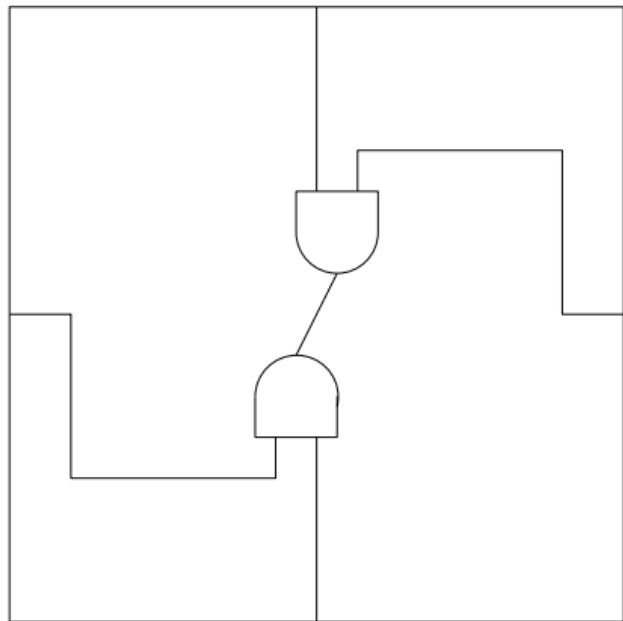
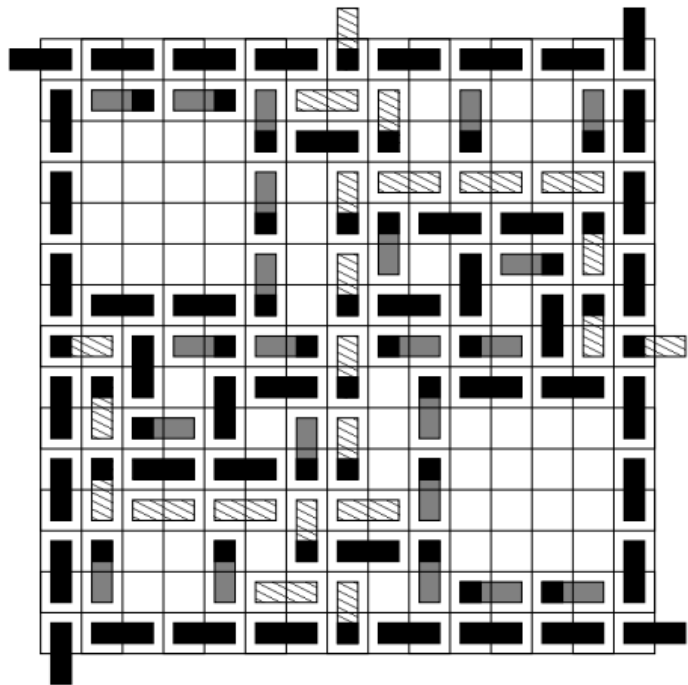


Rush Hour

[Tromp & Cilibrasi 2008]

2 ANDs

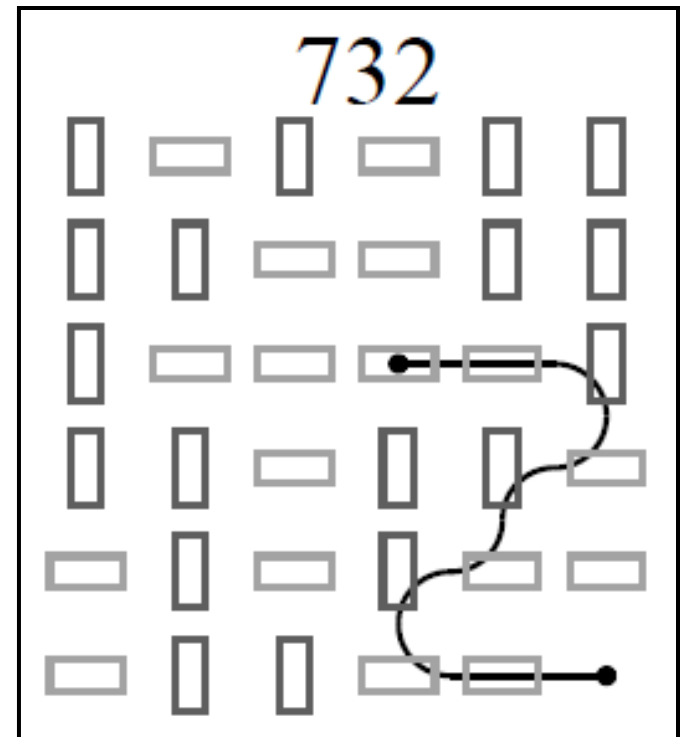
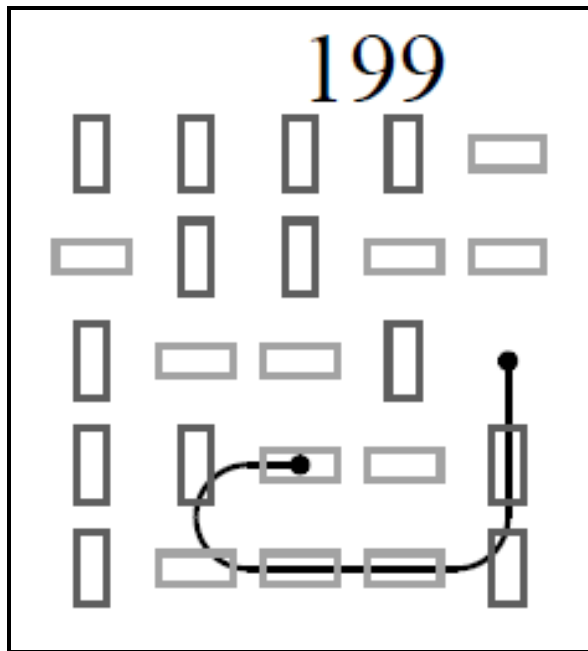
2 protected ORs

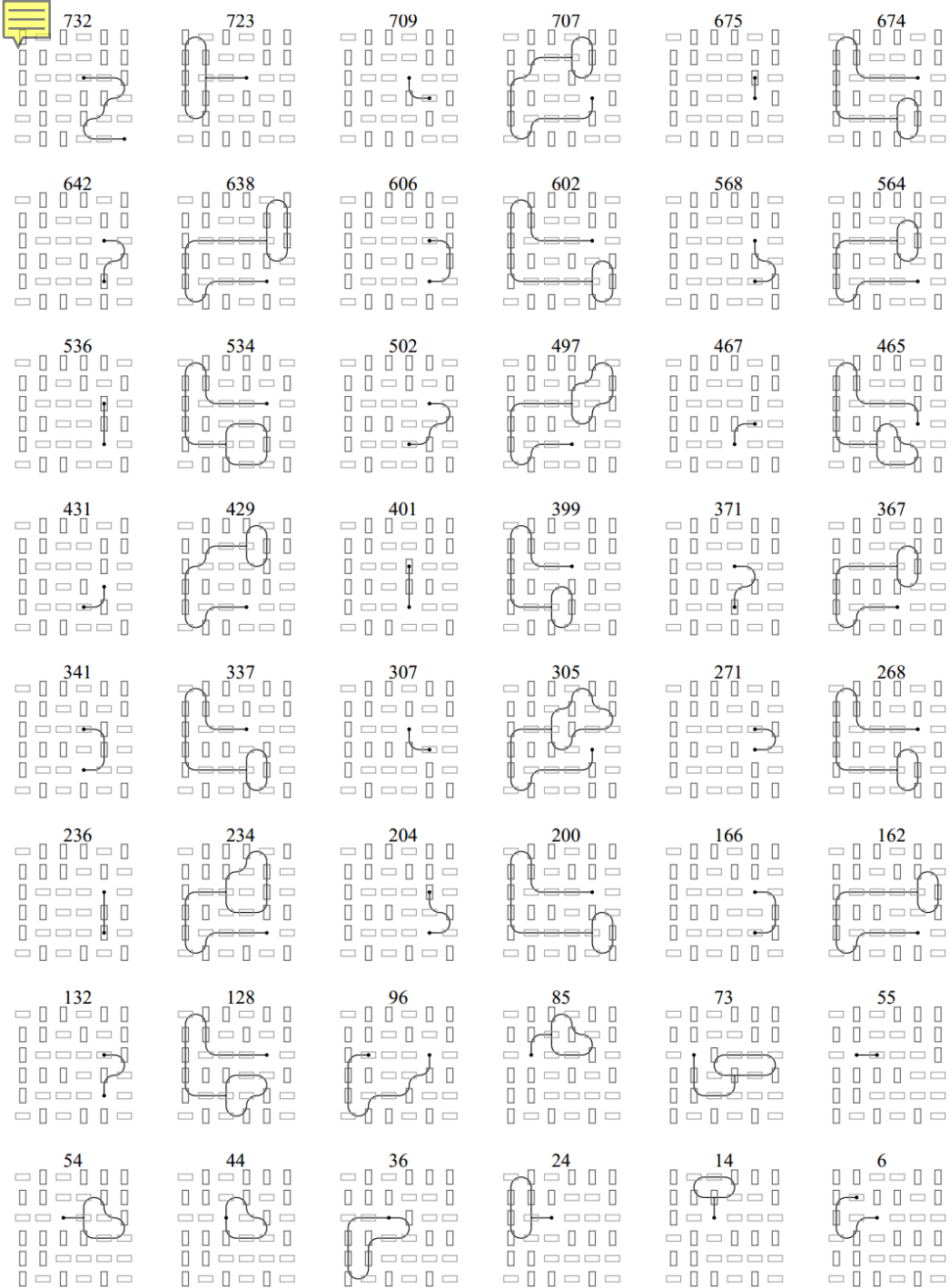


Open: 1×1 Rush Hour

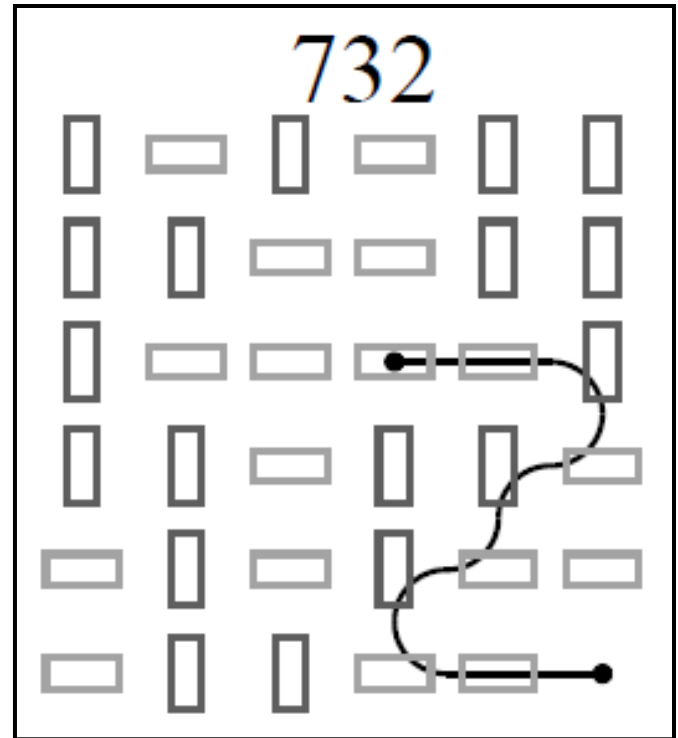
[Tromp & Cilibrasi 2008]

- P or PSPACE-complete or ...?





[Tromp & Cilibrasi 2008]

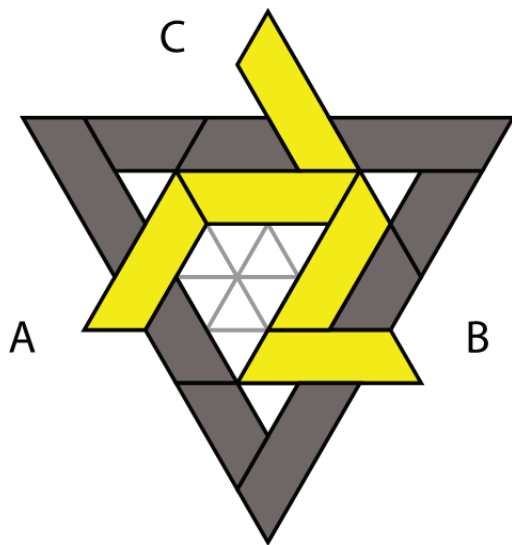
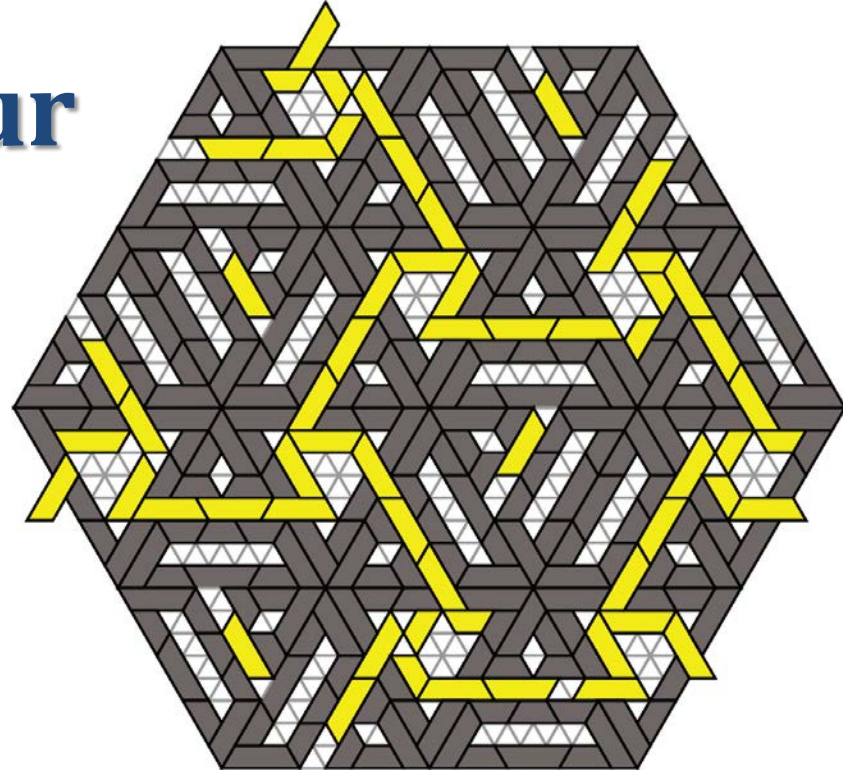




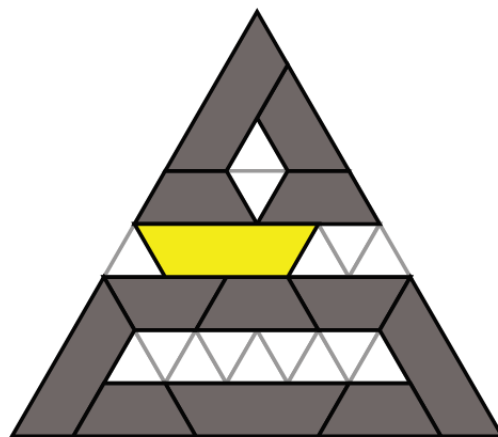
Triangular Rush Hour

[Hearn & Demaine 2009]

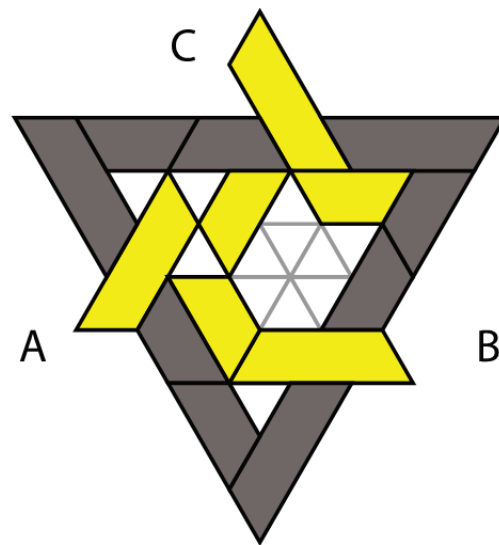
PSPACE-complete



(a) AND vertex



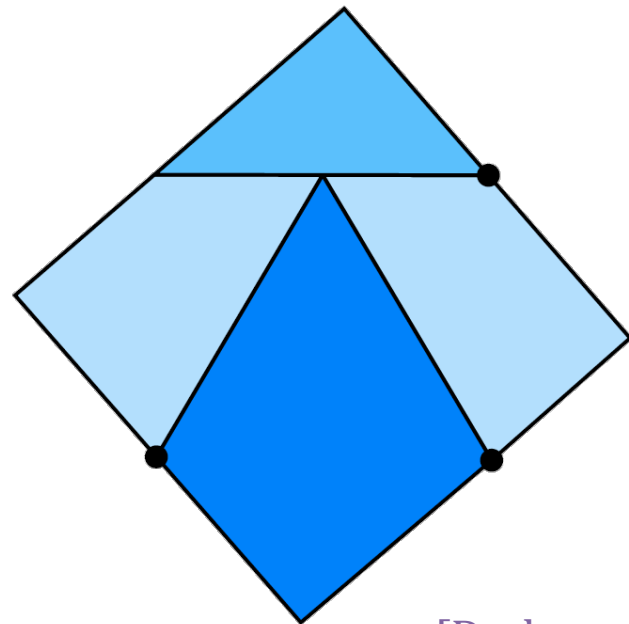
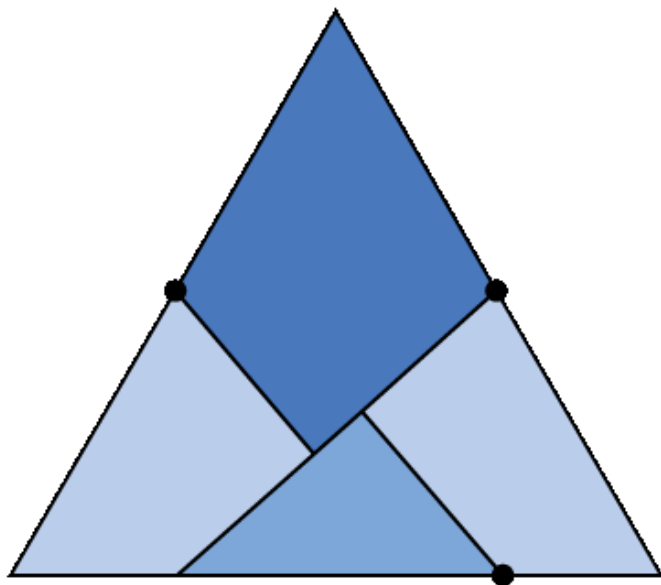
(b) Connector



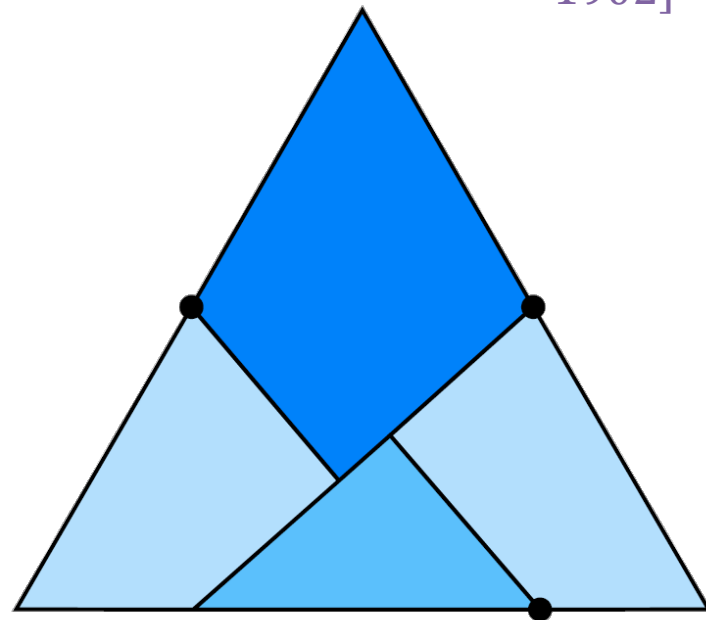
(c) OR vertex



Hinged Dissection



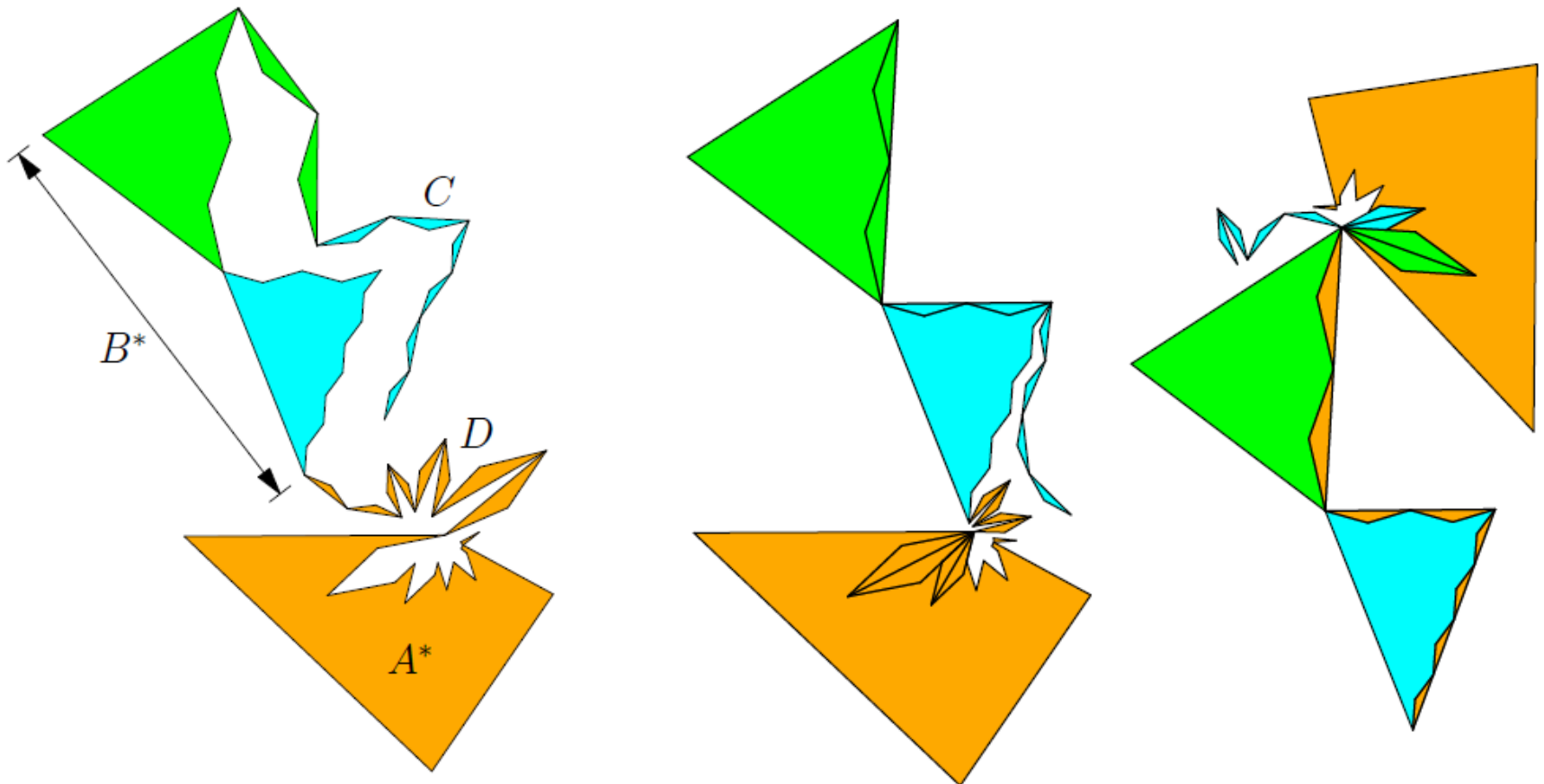
[Dudeney
1902]

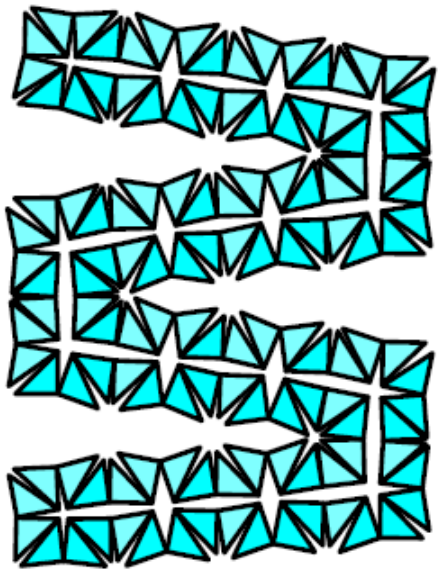
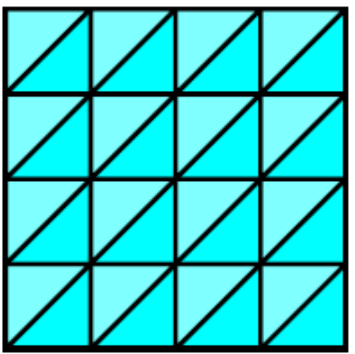
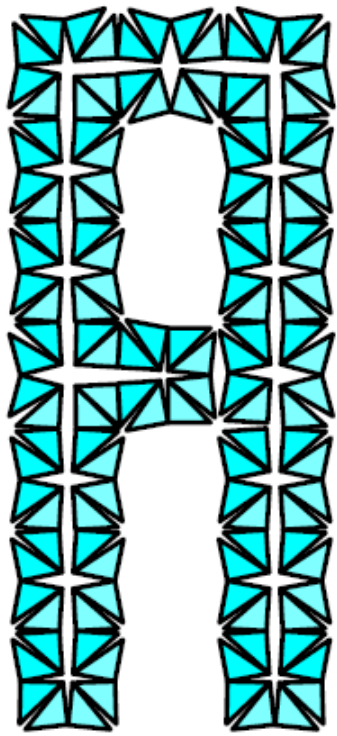
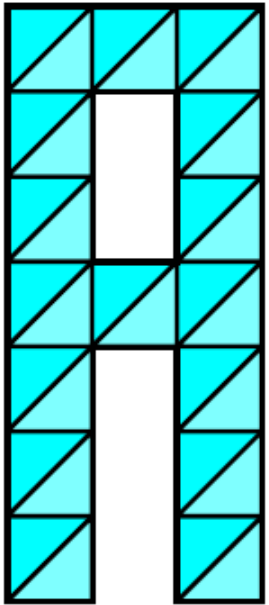


Hinged Dissection Universality

[Abbott, Abel, Charlton, Demaine, Demaine, Kominers 2008]

Polygons of equal area have a hinged dissection that folds *continuously without self-intersection*

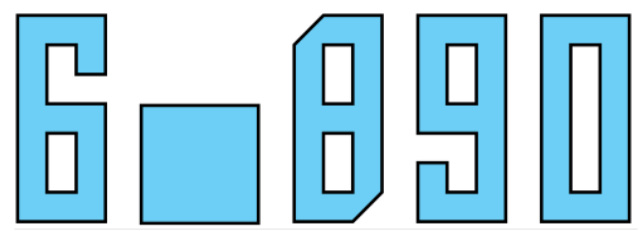
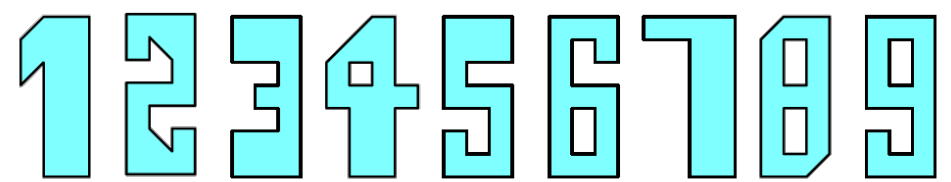
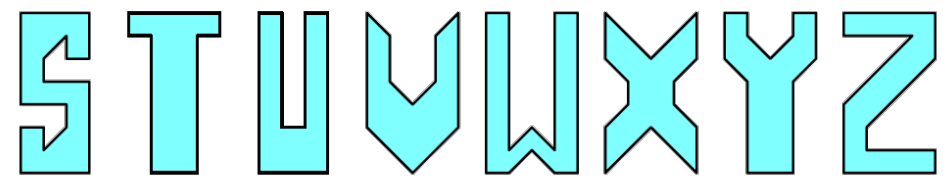
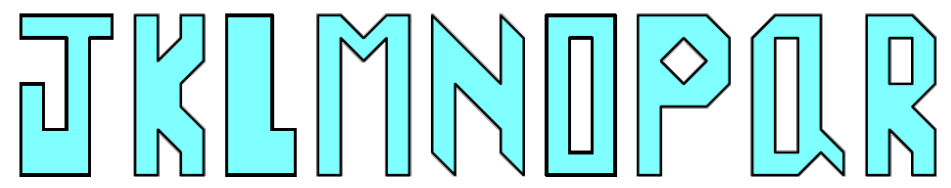
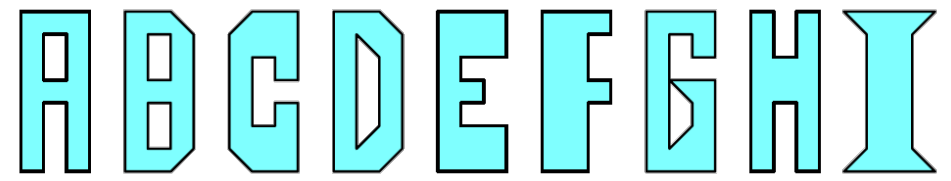




"Hinged alphabet"

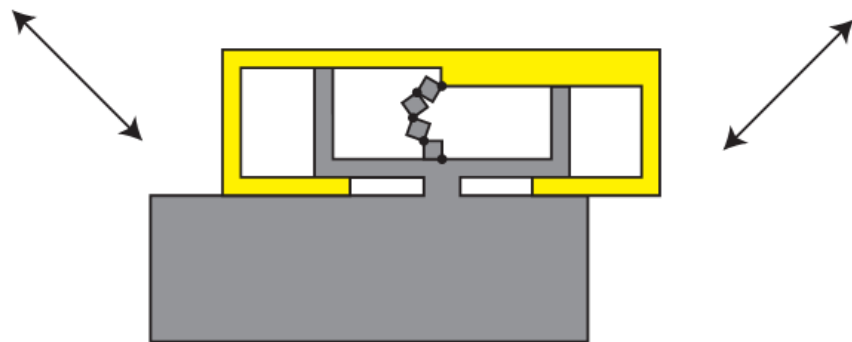
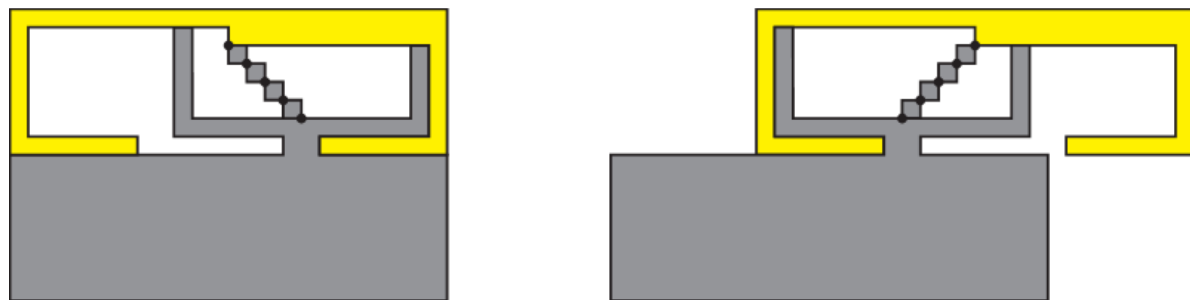
Erik & Martin Demaine

2003



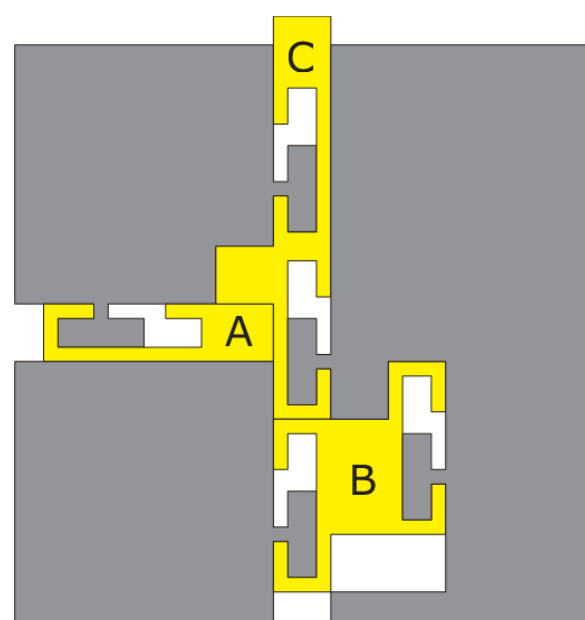
Hinged Dissection Motion

[Hearn & Demaine 2009]

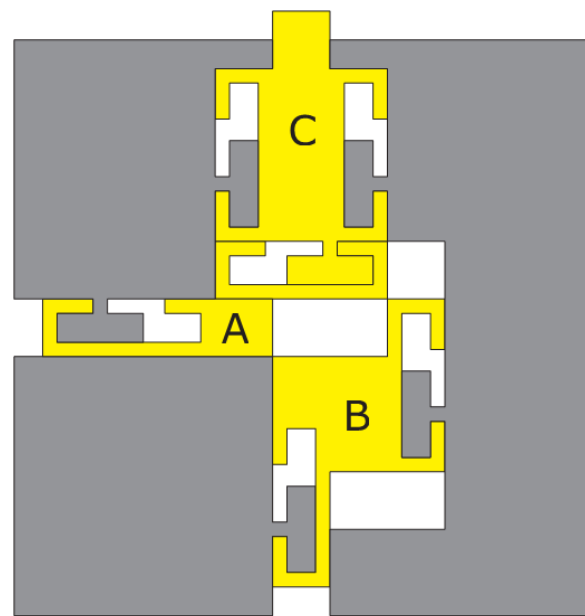


(c) Hinged slider

PSPACE-complete



(a) AND



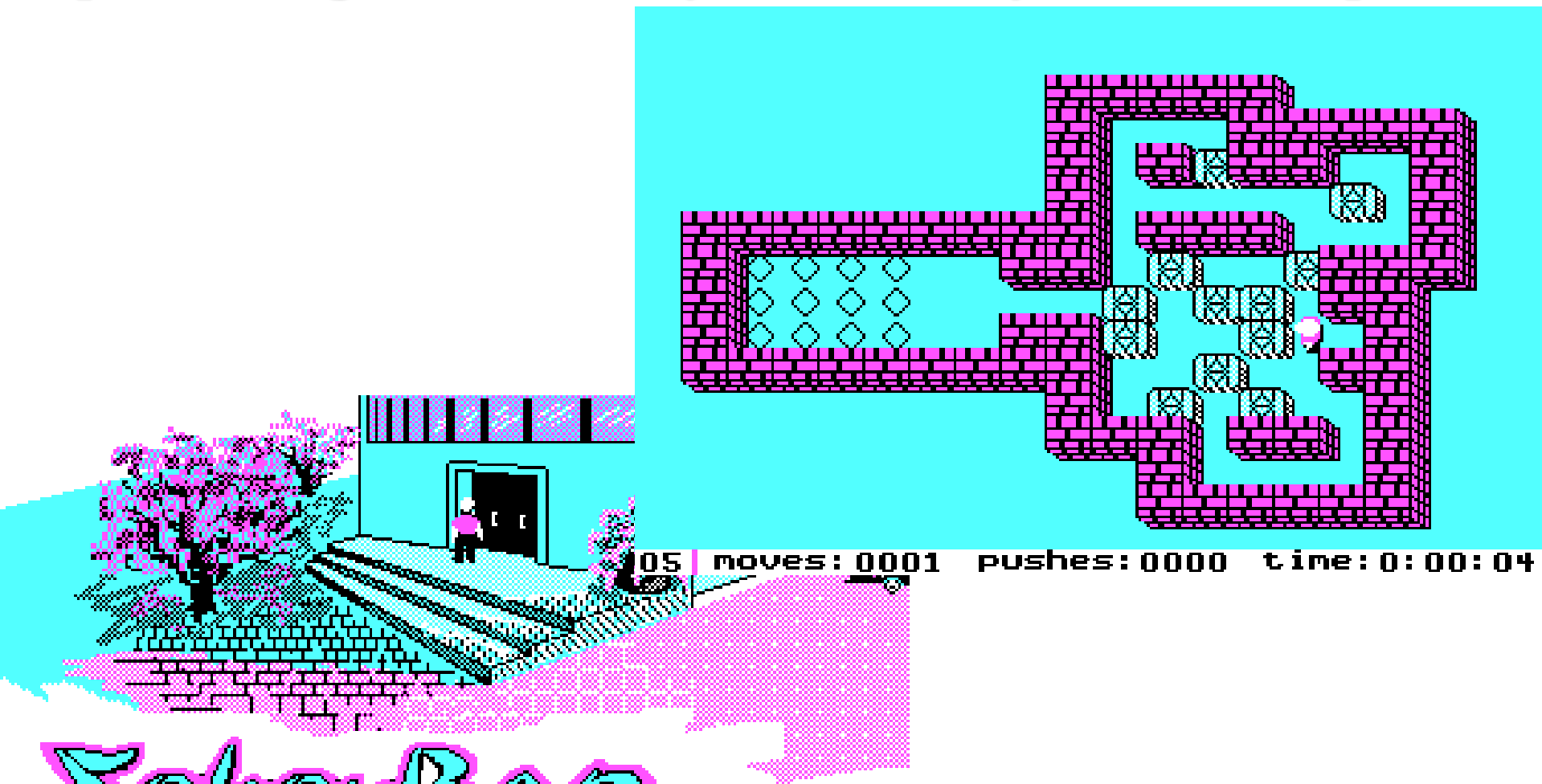
(b) OR

Pushing 1×1 Blocks Complexity

Name	Push	Fixed	Slide	Goal	Complexity	Reference
Push- k	$k \geq 1$	no	min	path	NP-hard	D, D, O'Rourke 2000
Push-*	∞	no	min	path	NP-hard	Hoffmann 2000
PushPush- k	$k \geq 1$	no	max	path	PSPACE-complete	D, Hoffmann, Holzer 2004
PushPush-*	∞	no	max	path	NP-hard	Hoffmann 2000
Push-1F	1	yes	min	path	NP-hard	DDO 2000
Push- k F	$k \geq 2$	yes	min	path	PSPACE-complete	D, Hearn, Hoffmann 2002
Push- $*$ F	∞	yes	min	path	PSPACE-complete	Bremner, O'Rourke, Shermer 1994
Push- k X	$k \geq 1$	no	min	simple path	NP-complete	D, Hoffmann 2001
Push- $*$ X	∞	no	min	simple path	NP-complete	Hoffmann 2000
Sokoban	1	yes	min	storage	PSPACE-complete	Culberson 1998

Sokoban

[Thinking Rabbit, Hiroyuki Imabayashi, 1982]



Soko-Ban

by *Spectrum HoLoByte*™ a division of Sphere Inc.

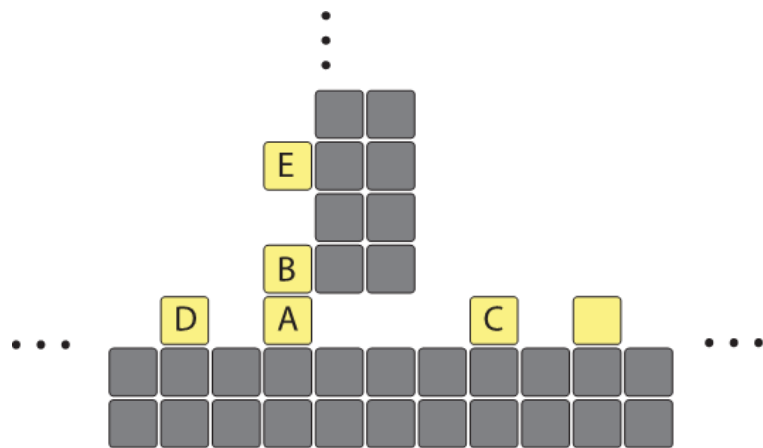
Designed by Khaled Bentebal
Programmed by Farah Soebrata
Graphics by Jody Sather

© Copyright 1984 ASCII Corp.

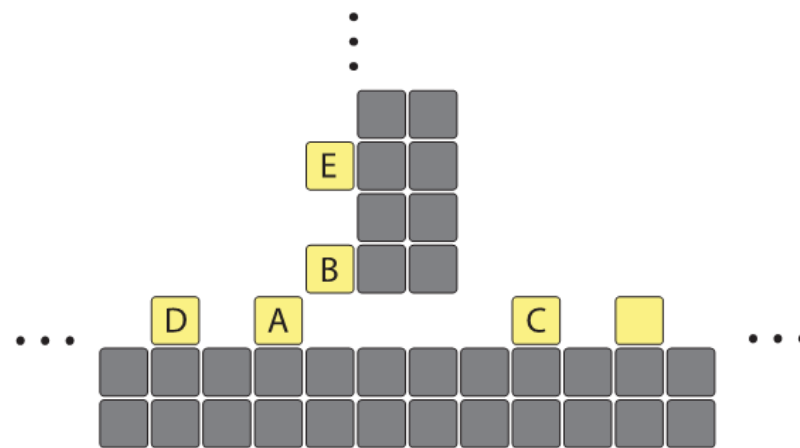


Sokoban is PSPACE-complete

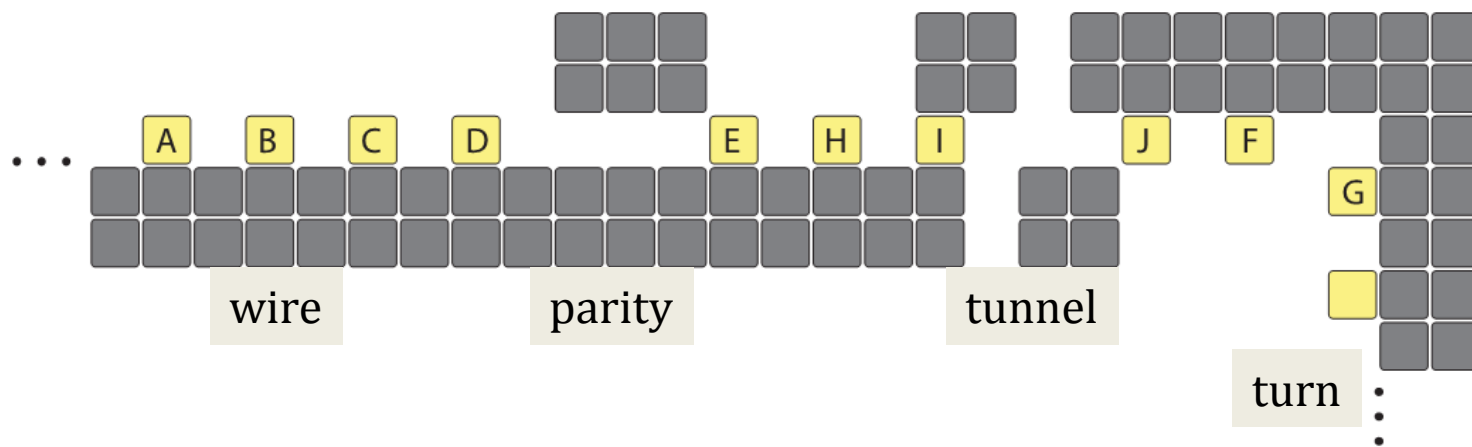
[Culberson 1998; Hearn & Demaine 2002]



(a) AND



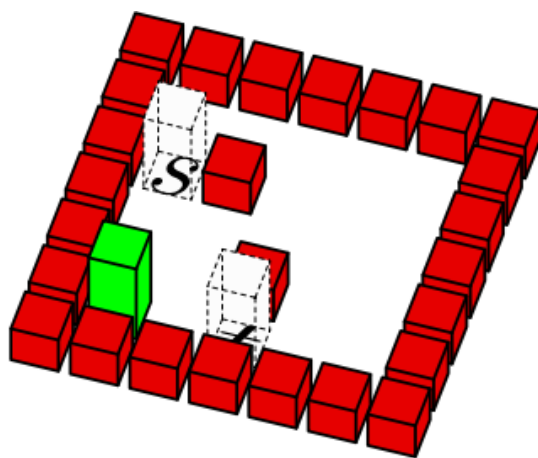
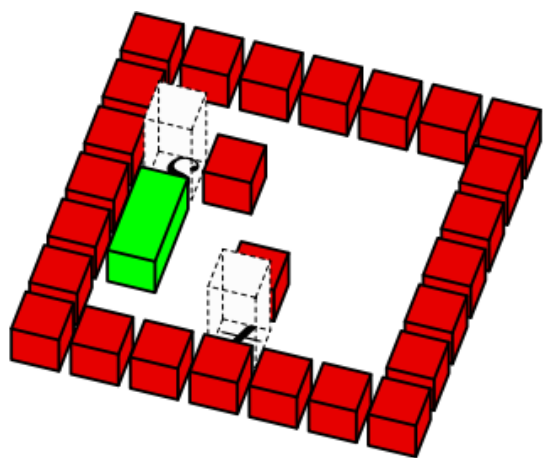
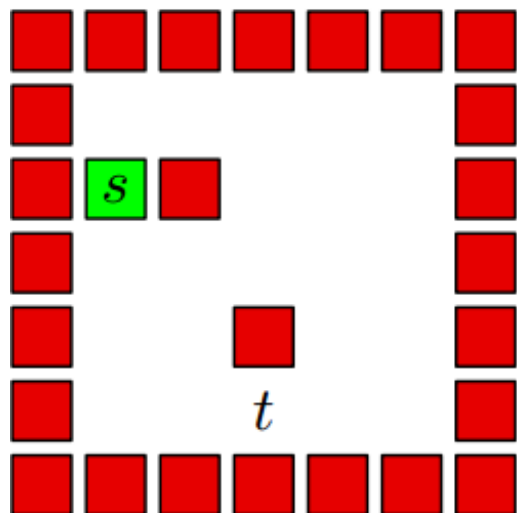
(b) OR



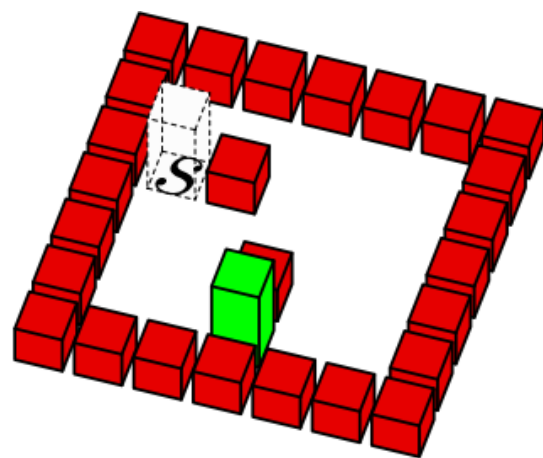
(c) Utility gadgets



Rolling Block Mazes



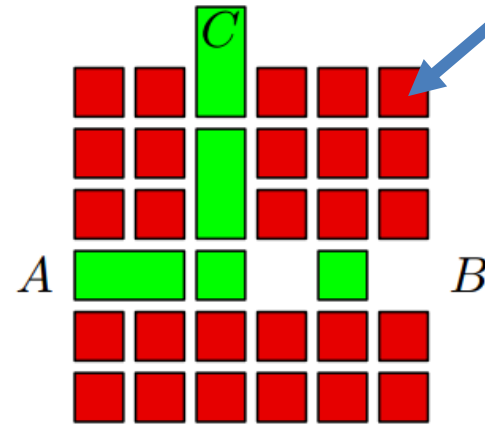
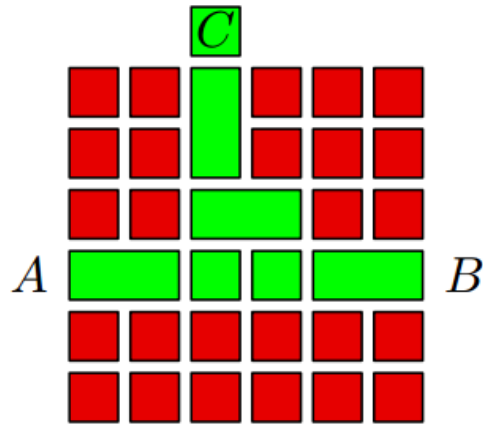
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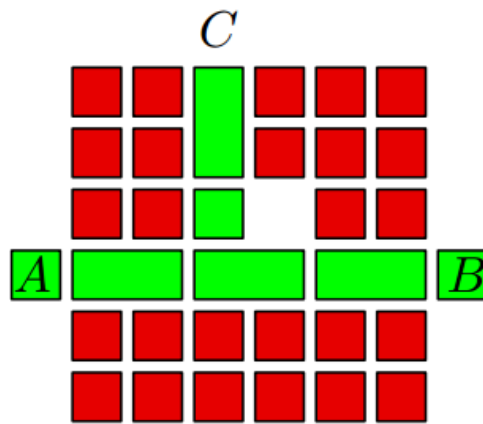


Rolling Block Mazes PSPACE-complete

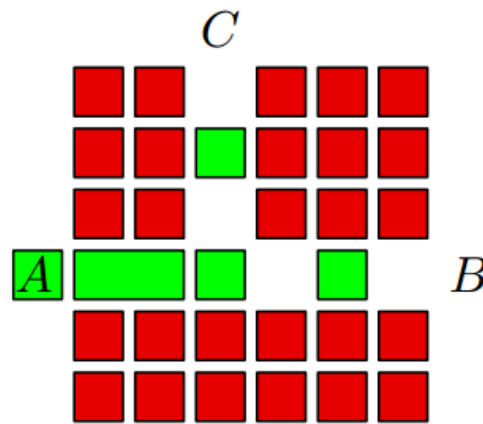
[Holzer & Jakobi 2012]



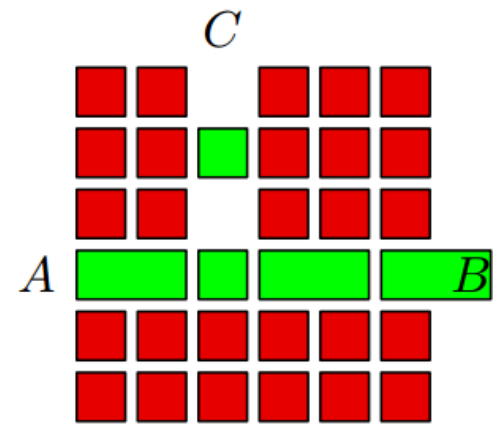
effectively
immovable
 $1 \times 1 \times 2$
blocks



AND



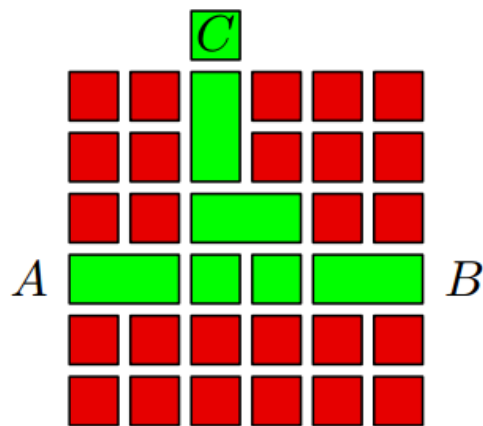
OR





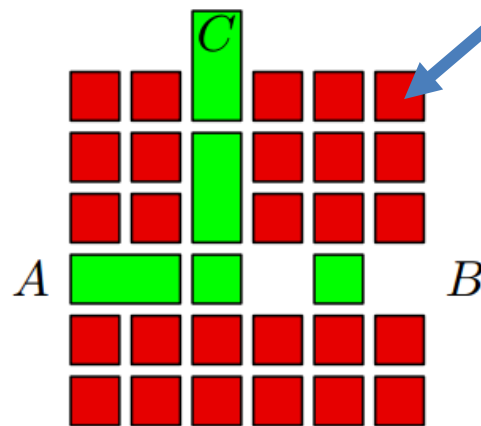
Rolling Block Mazes PSPACE-complete

[Holzer & Jakobi 2012]

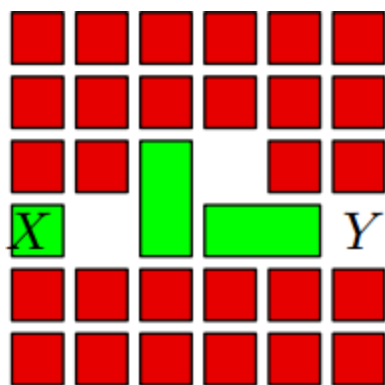


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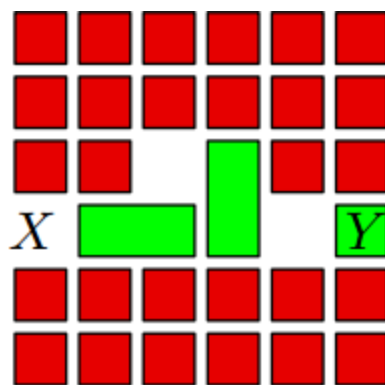
OR



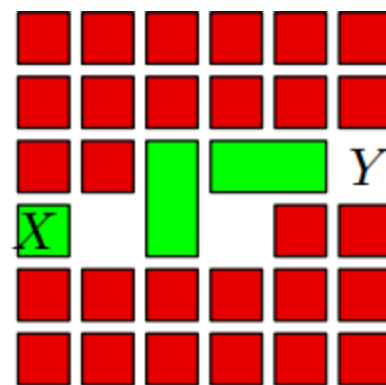
effectively
immovable
 $1 \times 1 \times 2$
blocks



rightward edge



leftward edge



shift

Plank Puzzles

[Andrea Gilbert; ThinkFun]

HOW TO PLAY:

1



Hiker STARTS TO CROSS.

2



Hiker MOVES the medium plank TO A NEW POSITION.

3



Hiker MOVES the small plank TO A NEW POSITION.

4



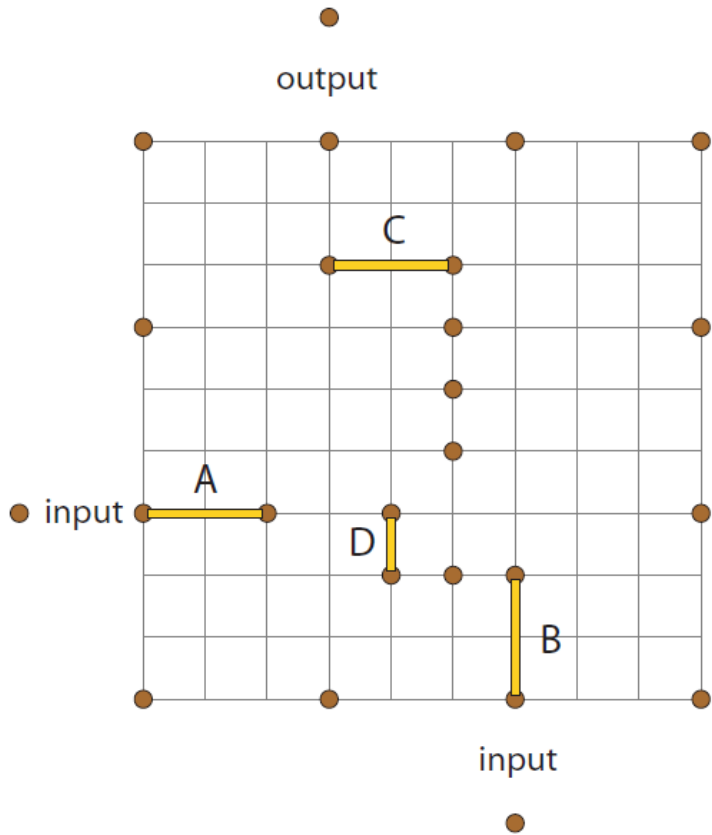
Hiker MOVES the medium plank and makes it across!



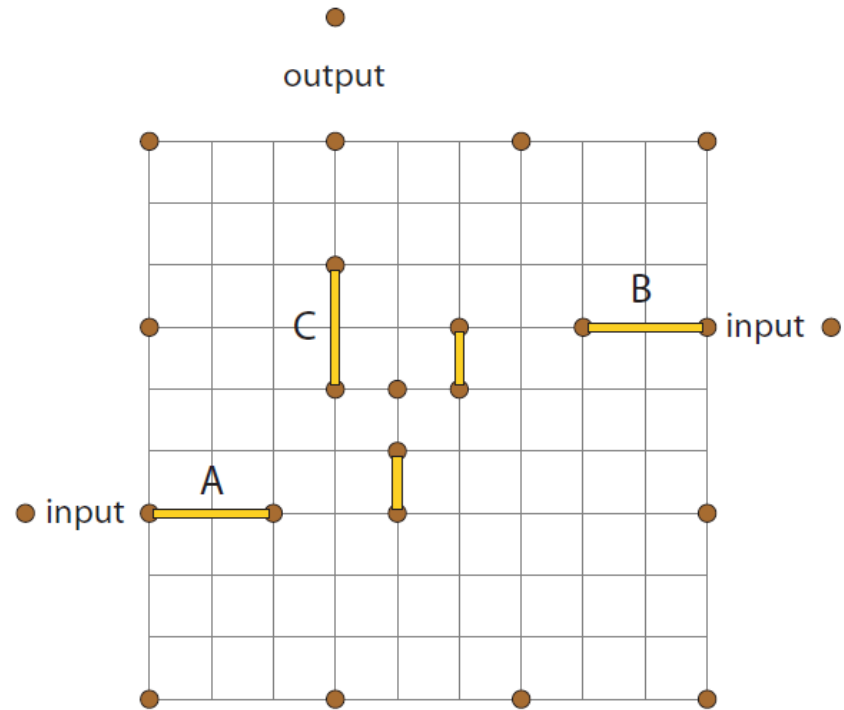


Plank Puzzles

[Hearn 2004]



(a) AND



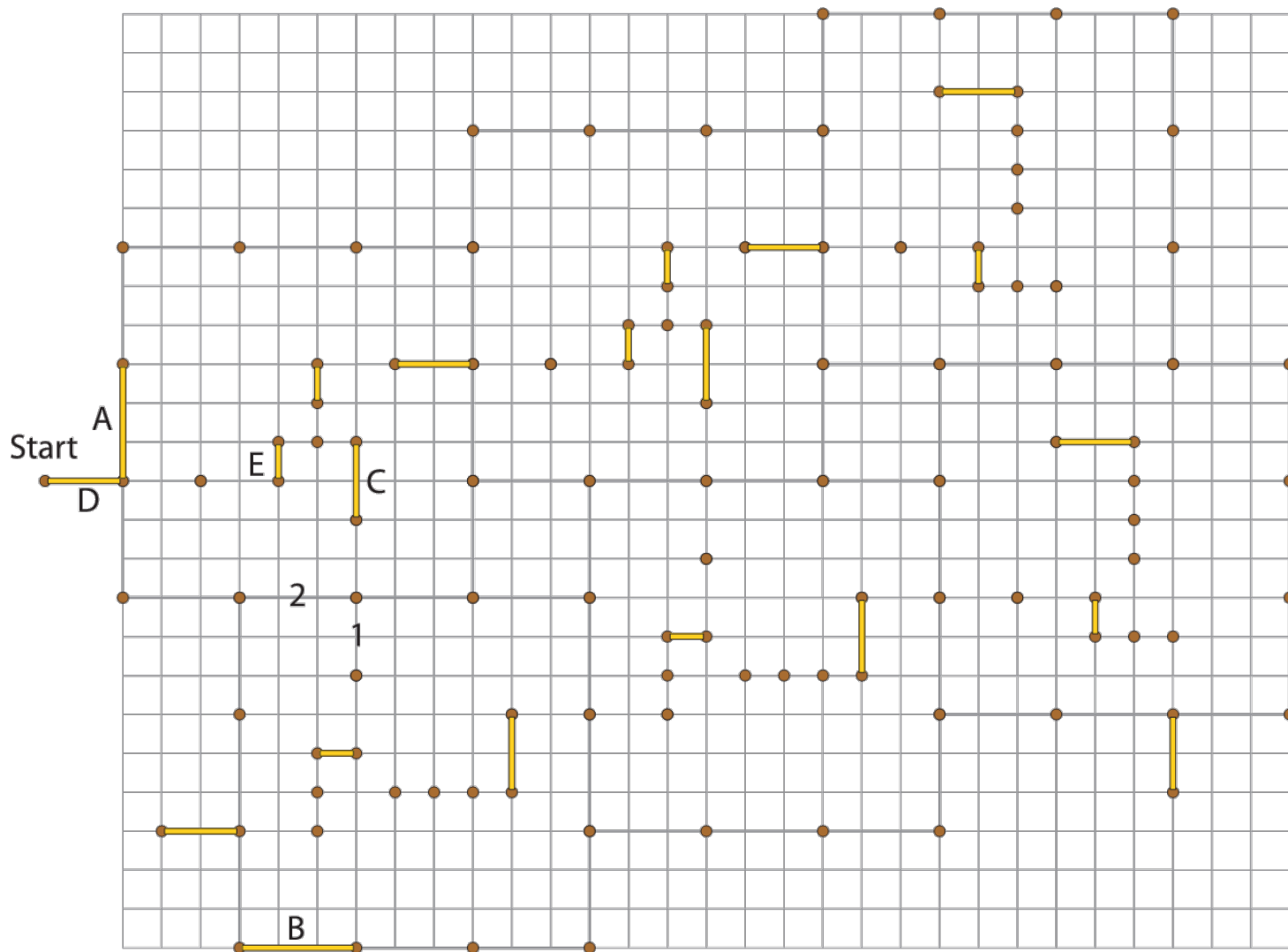
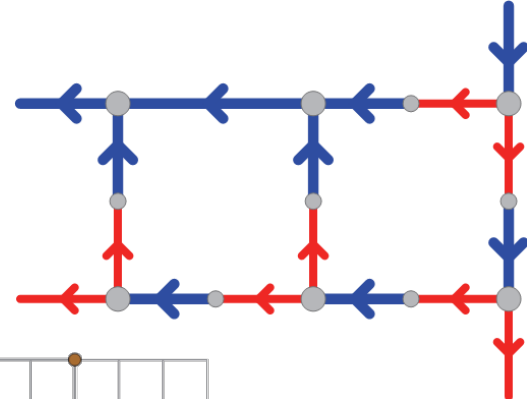
(b) OR



Plank Puzzles

[Hearn 2004]

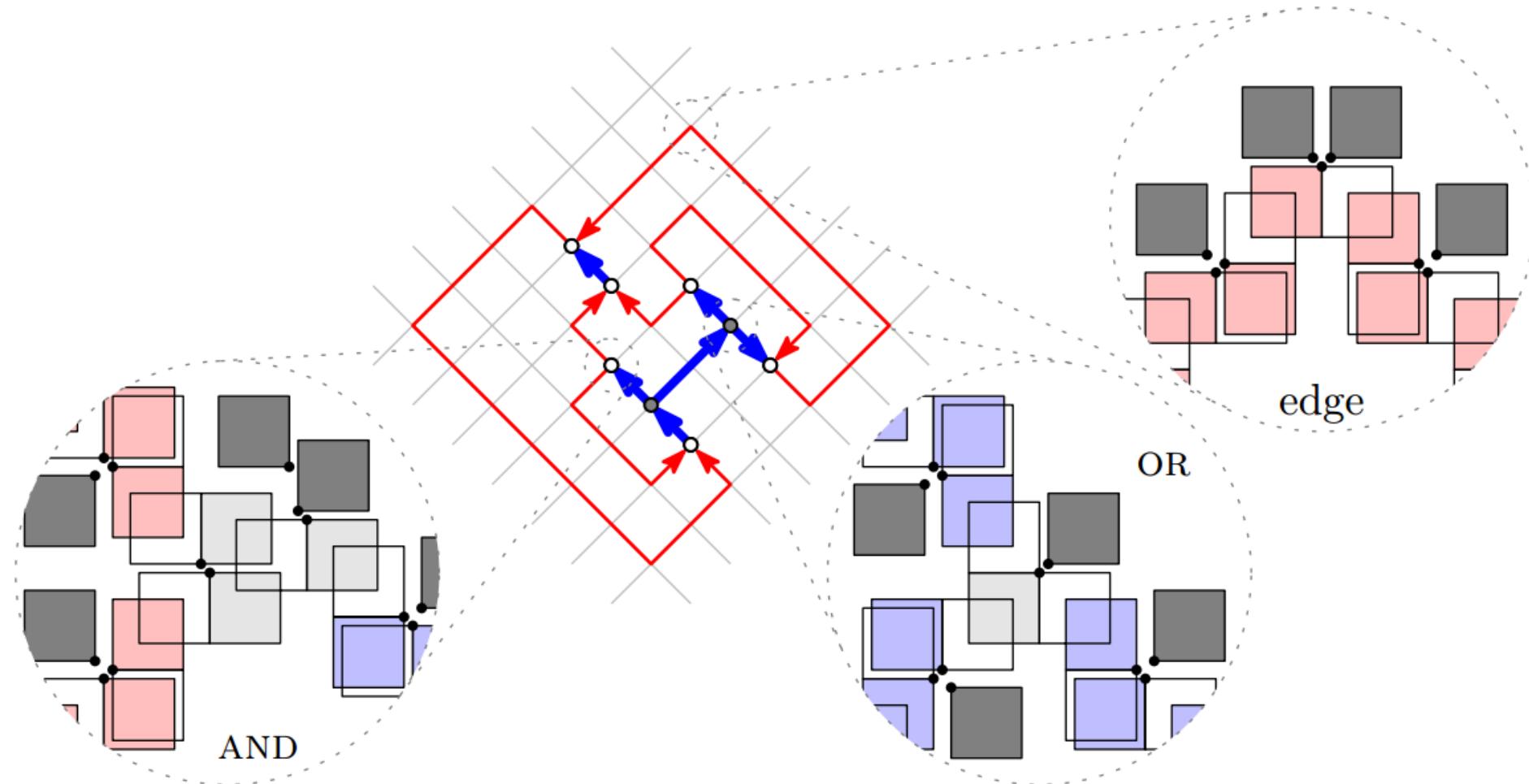
• End





Dynamic Map Labeling

[Buchin & Gerrits 2013]



Partial Searchlight Scheduling

[Viglietta 2013]

