

MASSACHUSETTS INSTITUTE OF TECHNOLOGY
 Department of Electrical Engineering and Computer Science
 6.036—Introduction to Machine Learning
 Spring Semester 2016

Assignment 0: Preliminaries

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 Not For Submission

Linear Algebra

1. Points and Vectors

- (a) A list of d numbers is a point in a d -dimensional space and also a vector. For 2-dimensional points $[-3, 1]$ and $[4, -1]$, produce a diagram showing both interpretations. Use your diagram to show how the vector interpretation facilitates a geometric interpretation of the addition and subtraction of points.
- (b) Give formulae for computing the angle between two vectors, and a vector's length (magnitude). What is the angle between $[0.4, 0.3]$ and $[-0.15, 0.2]$, and what are their respective lengths? Normalize both vectors (so that they will both have length 1).
- (c) Given 3-dimensional vectors $x^{(1)} = [a_1, a_2, a_3]$ and $x^{(2)} = [a_1, -a_2, a_3]$, write down a formula for calculating the angle between them. When is $x^{(1)}$ orthogonal to $x^{(2)}$?
- (d) Explain what it means to project one vector on to another (use a diagram if necessary). What is the projection of $x^{(1)}$ onto $x^{(2)}$, for the $x^{(1)}$ and $x^{(2)}$ given above?

2. Planes

- (a) Consider a hyperplane, p_1 , in d -dimensions. The hyperplane includes all $x = [x_1, \dots, x_d]$ such that $\theta_0 + \theta_1 x_1 + \theta_2 x_2 + \dots + \theta_d x_d = 0$. We can say that the d -dimensional vector $\theta = [\theta_1, \dots, \theta_d]$ together with the offset θ_0 describe the hyperplane p_1 . Give another d -dimensional vector θ' and θ'_0 that describe the same hyperplane p_1 . How many alternative descriptions are there? Explain.
- (b) Give the equation for determining whether a vector is orthogonal to the hyperplane p_1 .
- (c) Explain how to compute the orthogonal projection of a point onto a plane such as p_1 .
- (d) Consider an arbitrary point x , and a hyperplane described by normal $[\theta_1, \dots, \theta_d]$ and offset θ_0 . The signed distance of x from the plane is the perpendicular distance between x and the hyperplane, multiplied by +1 if x lies on the same side of the plane as the vector θ points and by -1 if x lies on the opposite side. Derive the equation for the signed distance of x from the hyperplane.
- (e) Let p_2 be the plane (a line since it is 1-dimensional) consisting of the set of points $x = [x_1, x_2]$ for which $3x_1 + x_2 - 1 = 0$.
 - i. What is the signed perpendicular distance of point $a = [-1, -1]$ from p_2 ?
 - ii. What is the signed perpendicular distance of the origin from p_2 ?
 - iii. What is the orthogonal projection of point $a = [-1, -1]$ onto p_2 ?
- (f) Consider a hyperplane in a d -dimensional space. If we project a point onto the plane, can we recover the original point from this projection? If so, show the equation for performing the back-projection. If not, write down an expression for the set of points x that all project to a single point on the plane.

3. Matrices

(a) Consider the matrix:

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 1 & 2 & 1 \end{bmatrix}.$$

- i. Write down A^T .
 - ii. Calculate $\det(A)$ and $\det(A^T)$.
- (b) Evaluate A^{-1} using python (Numpy). Verify that $AA^{-1} = I$.
- (c) Assume C is a 3×2 matrix, and b is a 3×1 (column) vector. What are the dimensions of:
- i. CC^T
 - ii. C^TC
 - iii. C^Tb
 - iv. b^TC
- (d) If $g = [2, 1, 3]$ (row vector), calculate gA .
- (e) Write down expressions equivalent to $(AB)^{-1}$ and $(AB)^T$, using only inverses and transposes of A and/or B .
- (f) Given that $A^T(AB - C) = 0$, where 0 is an $m \times 1$ vector of zeros, derive an expression for B . Assume that all relevant matrices needed for this calculation are invertible.
- (g) What is the rank of:

$$B = \begin{bmatrix} 2 & 1 & 0 \\ 1 & 4 & 4 \\ 5 & 6 & 4 \end{bmatrix}.$$

Probability

4. Probability Density Functions

Given a random variable $x \in \mathbb{R}$ with probability density function $p(x)$. Which of the following statements are true for $p(x)$:

- (a) The value of $p(x)$ lies in the interval $[0,1]$,
- (b) When $a < b$, $\int_a^b p(x)dx \in [0, 1]$ and represents the probability that the value of random variable x falls within the interval $[a, b]$
- (c) $p(x)$ is always non-negative,
- (d) The integral of $p(x)$ from $-\infty$ to ∞ is finite but the specific value may vary.
- (e) $\int_{-\infty}^{\infty} p(x)dx = 1$ always

5. Univariate Gaussians

- (a) Let $x \sim \mathcal{N}(1, 2)$, i.e., it is a normally distributed random variable with mean 1 and variance 2. What is the probability that $x \in [0.5, 2]$.
- (b) Let $\mathcal{N}(x; \mu, \sigma^2)$ denote the probability density function for a normally distributed random variable x with mean μ and variance σ^2 . For what value of x is $\mathcal{N}(x; \mu, \sigma^2)$ maximized, for a fixed value of μ and σ ? And what is the value of $\mathcal{N}(x; \mu, \sigma^2)$ for that x .
- (c) Suppose a set of points $D = \{x_1, \dots, x_n\}$ are drawn independently from some given univariate Gaussian $\mathcal{N}(x; \mu, \sigma^2)$. Write down an expression for the multivariate (joint) probability density function for x_1, \dots, x_n .

6. Optimization, gradients

Gradient ascent/descent methods are typical tools for maximizing/minimizing functions. Let $L(x, \theta)$ be a function of two vector arguments, $x = [x_1, x_2]^T$ and $\theta = [\theta_1, \theta_2]^T$. We would like to find a value of θ , i.e., both θ_1 and θ_2 , for which $L(x, \theta)$ takes its maximum/minimum value where x is assumed to be given. There could be more than one such θ .

- (a) The gradient $\nabla_{\theta} L(x, \theta)$ is a vector with two components corresponding to partial derivatives

$$\frac{\partial}{\partial \theta_j} L(x, \theta), \quad j = 1, 2$$

Evaluate the gradient when $L(x, \theta) = \log(1 + \exp(-\theta \cdot x))$ where $\theta \cdot x$ is the “dot product” $\theta \cdot x = \theta^T x = \theta_1 x_1 + \theta_2 x_2$.

- (b) Into which direction does the gradient (viewed as a vector) point? Is the value of $L(x, \theta)$ larger or smaller if we evaluate it at $\theta' = \theta + \epsilon \nabla_{\theta} L(x, \theta)$ where ϵ is a small real number?