

Outline: Dynamic Programming III (of 4)

- text justification
- parenthesization
- knapsack
- pseudopolynomial time
- Tetris training

Reading: CLRS 15

Review:

* DP is all about subproblems & guessing

* 5 easy steps:

- ① define subproblems; count # subprobs.
- ② guess (part of solution); count # choices
- ③ relate subprob. solutions; compute time/subprob.
- ④ recurse + memoize time = time/subprob.
 OR build DP table bottom-up; • # subprobs.

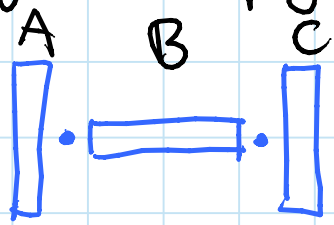
(check subproblems related acyclically)

[⑤ check original problem = a subproblem
 or solvable from DP table (\Rightarrow extra time)]

* for sequences, good subproblems are often prefixes OR suffixes OR substrings

Parenthesization:

optimal evaluation of associative expression
- e.g. multiplying rectangular matrices



$(AB)C$ costs $\Theta(n^2)$
 $A(BC)$ costs $\Theta(n)$

② guessing = outermost multiplication: $(\dots)(\dots)$
 \Rightarrow # choices = $O(n)$
 \uparrow \uparrow
 $k-1$ k

① subproblems = ~~prefixes & suffixes?~~ NO
= cost of substring $A[i:j]$
 \Rightarrow # subproblems = $\Theta(n^2)$

③ relation:

$$- DP[i, j] = \min(DP[i, k] + DP[k, j] + \text{cost of } (A[i] \dots A[k-1]) \cdot (A[k] \dots A[j-1]))$$

for k in range($i+1, j$)

$$- DP[i, i+1] = \emptyset$$

\Rightarrow cost per subproblem = $O(n)$

④ total time = $O(n^3)$

⑤ solution = $DP[0, n]$

(& use parent pointers to recover parens.)

Knapsack of size S you want to pack

- item i has integer size s_i & real value v_i
- goal: choose subset of items of max. total value subject to total size $\leq S$

First attempt:

- ① ~~subproblem = value for suffix i : WRONG~~
- ② guessing = whether to include item i
 \Rightarrow #choices = 2
- ③ relation:
 - $DP[i] = \max(DP[i+1], v_i + DP[i+1])$ if $s_i \leq S$?!)
 - not enough information to know whether item i fits - how much space is left?
GUESS!

① subproblem = value for suffix i :
given knapsack of size X
 \Rightarrow #subproblems = $O(n \cdot S)$ (!)

- ③ relation:
 - $DP[i, X] = \max(DP[i+1, X], v_i + DP[i+1, X - s_i])$ if $s_i \leq X$
 - $DP[n, X] = \emptyset$
 - \Rightarrow time per subproblem = $O(1)$

④ total time = $O(n \cdot S)$

⑤ solution = $DP[0, S]$

(& use parent pointers to recover subset)

AMAZING: effectively trying all possible subsets!

Knapsack is in fact NP-complete!

⇒ suspect no polynomial-time algorithm

↳ polynomial in length of input

What gives?

- here input = $\langle S_1, s_0, \dots, s_{n-1}, v_0, \dots, v_{n-1} \rangle$
- length in binary: $O(\lg S + \lg s_0 + \dots) \approx O(n \lg \dots)$
- so $O(nS)$ is not "polynomial time"
not S
- $O(nS)$ still pretty good if S is small
- "pseudopolynomial time": polynomial in length of input & integers in the input

Remember:

polynomial - GOOD

exponential - BAD

pseudopoly. - SO SO

Tetris training:

- given sequence of n Tetris pieces & a board of small width w
- must choose orientation & x coordinate for each
- then must drop piece till it hits something
- full rows do not clear

without these artificialities WE DON'T KNOW!
(but: if w also large then NP-complete)

- goal: survive i.e. stay within height h
[material below covered in recitation]

First attempt:

① ~~subproblem = survive in suffix i : ?~~ **WRONG**

② guessing = how to drop piece i
 \Rightarrow # choices = $O(w)$

③ ~~relation: $DP[i] = DP[i+1]$?!~~ **not enough information!**

\rightarrow What do we need to know about prefix i ? 

① subproblem = survive? in suffix i :

given initial column occupancies h_0, h_1, \dots, h_{w-1}
 \Rightarrow # subproblems = $O(n \cdot h^w)$

③ relation: $DP[i, \vec{h}] = \max(DP[i, \vec{m}])$ for valid moves \vec{m} of piece i in \vec{h}

\Rightarrow time per subproblem = $O(w)$

④ total time = $O(n w h^w)$

⑤ solution = $DP[\emptyset, \vec{\emptyset}]$

(& use parent pointers to recover moves)