

Lecture 16: Shortest Paths III - Dijkstra and Special Cases

Lecture Overview

- Shortest paths in DAGs
- Shortest paths in graphs without negative edges
- Dijkstra's Algorithm

Readings

CLRS, Sections 24.2-24.3

DAGs:

Can't have negative cycles because there are no cycles!

1. Topologically sort the DAG. Path from u to v implies that u is before v in the linear ordering
2. One pass over vertices in topologically sorted order relaxing each edge that leaves each vertex
 $\Theta(V + E)$ time

Example:

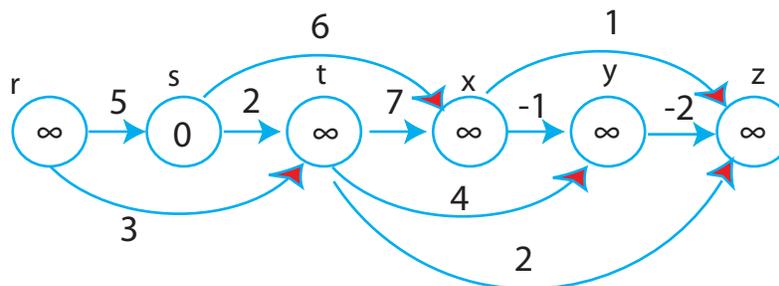


Figure 1: Shortest Path using Topological Sort.

Vertices sorted left to right in topological order

Process r : stays ∞ . All vertices to the left of s will be ∞ by definition

Process s : $t : \infty \rightarrow 2$ $x : \infty \rightarrow 6$ (see top of Figure 2)

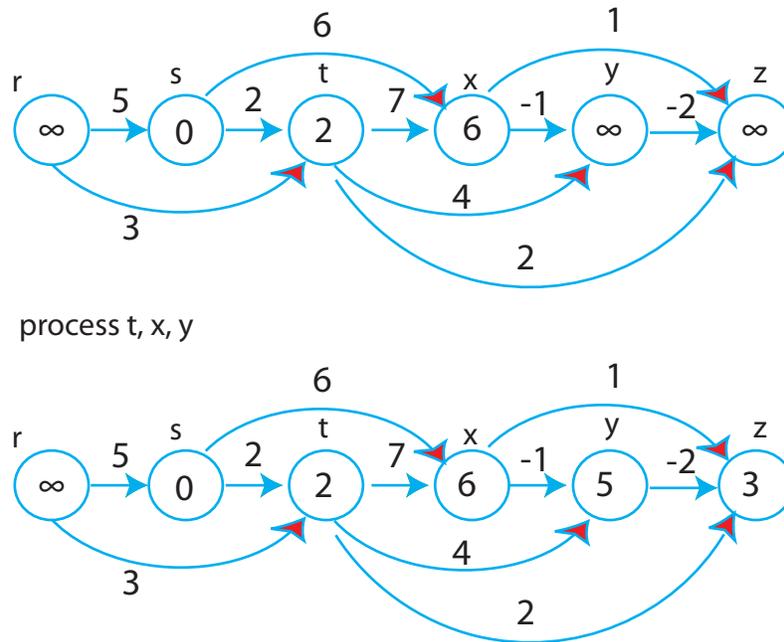


Figure 2: Preview of Dynamic Programming

DIJKSTRA Demo

Dijkstra's Algorithm

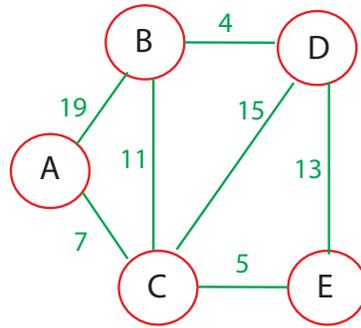
For each edge $(u, v) \in E$, assume $w(u, v) \geq 0$, maintain a set S of vertices whose final shortest path weights have been determined. Repeatedly select $u \in V - S$ with minimum shortest path estimate, add u to S , relax all edges out of u .

Pseudo-code

```

Dijkstra ( $G, W, s$ ) //uses priority queue Q
  Initialize ( $G, s$ )
   $S \leftarrow \phi$ 
   $Q \leftarrow V[G]$  //Insert into Q
  while  $Q \neq \phi$ 
    do  $u \leftarrow \text{EXTRACT-MIN}(Q)$  //deletes  $u$  from Q
     $S = S \cup \{u\}$ 
    for each vertex  $v \in \text{Adj}[u]$ 
      do RELAX ( $u, v, w$ ) ← this is an implicit DECREASE_KEY operation

```



A	C	E	B	D	D	B	E	C	A	E	C	A	D	B
7	12	18	22	4	13	15	22	5	12	13	16			

Figure 3: Dijkstra Demonstration with Balls and String.

Recall

```

RELAX( $u, v, w$ )
  if  $d[v] > d[u] + w(u, v)$ 
    then  $d[v] \leftarrow d[u] + w(u, v)$ 
         $\Pi[v] \leftarrow u$ 

```

Example

Strategy: Dijkstra is a greedy algorithm: choose closest vertex in $V - S$ to add to set S

Correctness: Each time a vertex u is added to set S , we have $d[u] = \delta(s, u)$

Complexity

$\theta(v)$ inserts into priority queue
 $\theta(v)$ EXTRACT_MIN operations
 $\theta(E)$ DECREASE_KEY operations

Array impl:

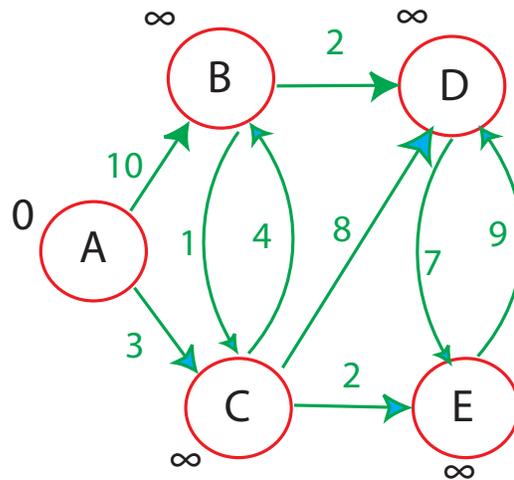
$\theta(v)$ time for extra min
 $\theta(1)$ for decrease key
Total: $\theta(V.V + E.1) = \theta(V^2 + E) = \theta(V^2)$

Binary min-heap:

$\theta(\lg V)$ for extract min
 $\theta(\lg V)$ for decrease key
Total: $\theta(V \lg V + E \lg V)$

Fibonacci heap (not covered in 6.006):

$\theta(\lg V)$ for extract min
 $\theta(1)$ for decrease key
amortized cost
Total: $\theta(V \lg V + E)$



$S = \{ \}$	{ A B C D E }	=	Q			
$S = \{ A \}$	0	∞	∞	∞	∞	
$S = \{ A, C \}$	0	10	3	∞	∞	← after relaxing edges from A
$S = \{ A, C \}$	0	7	3	11	5	← after relaxing edges from C
$S = \{ A, C, E \}$	0	7	3	11	5	
$S = \{ A, C, E, B \}$	0	7	3	9	5	← after relaxing edges from B

Figure 4: Dijkstra Execution