

(1)

6.006 Recitation 9

Agenda

- heaps review.

- ADT vs. implementation

Heaps

(idea) a semi organized data structure (typically tree-based)

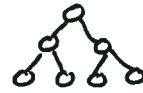
- organized enough to give decent runtimes
- unorganized enough to make maintenance easy.

ex: lazy laundry - separate underwear, pants, and shirts.

many types - binary, binomial, fibonacci.

→ Binary Heaps : use a binary tree structure

2 types : min-heap, max-heap



invariant: ① parent ≥ children.

- because this invariant is loose we can force another

② tree must be complete



how is this semi-organized?

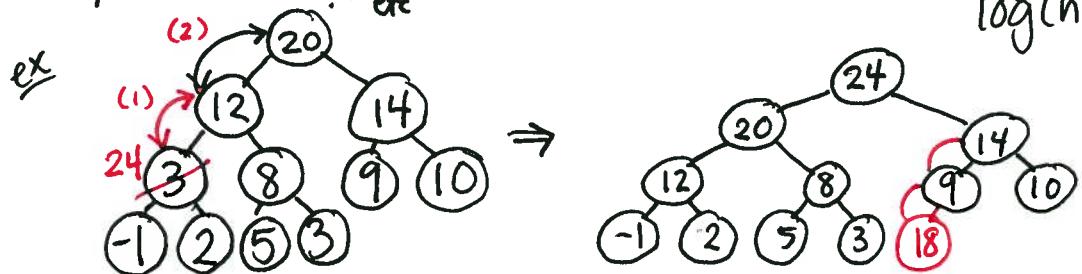
→ operations

2 many valid locations to insert.

• extract-max : return root
heapify(root) $\Rightarrow \Theta(1) + \text{heapify}$

• heapify : move the violation down the tree. $\Rightarrow O(\text{depth} = \log(n))$
b/c complete.

* • increase-key : move the violation UP the tree $\Rightarrow O(\text{depth} = \log(n))$



• insert : add to bottom of heap
increase-key (new element) $\Rightarrow \Theta(1) + \text{incr-key.}$

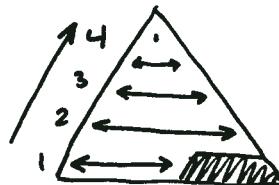
* assumes you know
the location of
the changing
node.

ex above: add 18.

* • decrease-key : change, then heapify node

* • delete : exchange w/ bottom of heap, then heapify

- build : call heapify on each node, starting at leaves + progressing to the root.



`build(node):`

```
if node is a leaf: return
build(left-child)
build(right-child)
heapify(node)
return.
```

runtime: every node is heapified
heapify takes $O(\lg n)$
so this is $O(n \lg n)$
lower bound? i dunno.

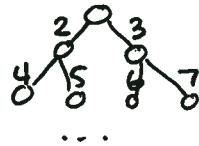
} ensure subtree @ node
has only 1 violation:
the root.

$$T(n) = 2T(n/2) + \lg(n)$$

try: $c n - d \rightarrow$ NO $d \geq \lg(n)$
 $c n - d \lg n \rightarrow$ OK if $d \geq 1$
not a lower bound.

Implementing a Binary Heap.

→ array indices



!! very space efficient
and time efficient: can find
children/parent fast.

since complete if $i \in \text{heap}$ then $j < i$ means $j \in \text{heap}$.

→ doubly linked tree

- just here to show that ADT ≠ implementation.

· array convenient for heapsort.

Priority Queue

ops: `insert(x)`, `max()`, `extract-max()`, `increase-key(x new)`

implementations:

- sorted list
- heaps
- unsorted list

	<code>ins()</code>	<code>max()</code>	<code>extr()</code>	<code>incr()</code>
- sorted list	$\lg(n)$	1	1	$n \lg n$
- heaps	$\lg(n)$	1	1	$\lg n$
- unsorted list	1	n	n	1

- to use it you need not know the implementation
only the interface.
- like the ADTs provided in python: list, dict, etc.

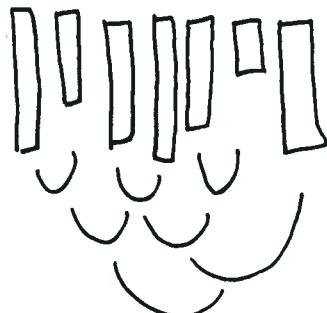
ADT : need to know to USE
implementation: need to DO .

(3)

Merging K-lists

- popular interview question

IDEA 1 : merge pairs of lists



- Problem: you have k sorted lists and you want 1 sorted list. The total # of elements is n
- a. merging 2 lists takes $\Theta(m)$
 $m = \# \text{elts in the lists}$.
 - b. you will need $\log(k)$ merges/stages
 - c. each stage touches (roughly) every element.

$$\mathcal{O}(n \log k)$$

!! : $\mathcal{O}(n)$ extra space needed.

IDEA 2: merge all k simultaneously using a min heap.

- take the top element from each list (along w/ keeping track of which list it came from)
- place the elements into a min heap
- remove-min + add to 'sorted' region [look a selection sort!]
- add the next element from the list ↑ came from.

time: building heap $\mathcal{O}(k \lg k)$

remove min $\mathcal{O}(\lg k)$

add element $\mathcal{O}(\lg k)$

- each element will be added and removed so: $n(\lg k)^2$

Space: $\mathcal{O}(k)$

- wait - huh?? well turns out w/ some smartness we can store our sorted list in the sublists free space .

- does having unbalanced lists affect the methods?
- other methods?
- what benefits do each have?
- why a heap rather than a sorted list?
Since really we're creating a priority Q...

this worked well.
accessible problem
students had lots
of good ideas.