Modelling Nuclear Reactors with Julia

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December 2015

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Julia MOC

December 2015 1 / 12



To see how well Julia fits my use cases

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To see how well Julia fits my use cases

Benchmark problem: a nuclear reactor simulator (specifically method of charactersitics)

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What a nuclear reactor looks like

The heart of a typical nuclear powerplant is a pressure vessel where water is heated



Credit: US DOE

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What a nuclear reactor looks like

Inside that vessel are about 200 fuel assemblies—bundles of rods containing uranium



Credit: US DOE

What a nuclear reactor looks like

Reactors have a lot of axial symmetry which usually allows us to model them in 2D



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What my geometry looks like

For this project, I further simplified down the model to a single "pin cell" with reflective boundaries



The problem

Goal: neutron interaction rate Complication: strong anisotropy Diffusion can't solve this problem! Solution: integrate over characterstic paths

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Neutron characteristics

Select a set of azimuthal angles (32 in this case)



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Neutron characteristics

Repeat each azimuthal ray with a regular spacing (0.5 mm in this case)



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The algorithm

Algorithm 2 Transport Sweep Algorithm $\Phi_{i,g} \leftarrow 0 \quad \forall \, i,g \in \{I,G\}$ while $\Phi_{i,q} \forall i$ not converged do for all $m \in M$ do for all $k \in K(m)$ do for all $s \in S(k)$ do for all $q \in G$ do for all $p \in P$ do $i \leftarrow I(s)$ $\Delta \Psi_{k,i,g,p} \leftarrow \left(\Psi_{k,g,p} - \frac{Q_{i,g}}{\Sigma_{i}^{T}}\right) \left(1 - e^{-\tau_{k,i,g,p}}\right)$ $\Phi_{i,g} \leftarrow \Phi_{i,g} + \frac{4\pi}{A_i} \omega_m \omega_p \omega_k \sin \theta_p \Delta \Psi_{k,i,g,p}$ $\Psi_{k,a,p} \leftarrow \Psi_{k,a,p} - \Delta \Psi_{k,a,p}$ end for end for end for end for Credit: Will Boyd

- # Initialize FSR scalar fluxes to zero
- # Loop over azimuthal angles
- # Loop over tracks
- # Loop over segments
- # Loop over energy groups
- # Loop over polar angles
- # Get FSR for this segment
- # Compute angular flux change along segment
- # Increment FSR scalar flux
- # Update track outgoing flux

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The codes: a three-way face-off

C++

Python

Julia

Well developed parallel research code with many features

My own homework code, slow

Similar to the Python code, but fast

Image: A matrix of the second seco

	C++	Python	Julia
Baseline	2.8 s (1×)	117.0 s (41×)	14.4 s (5×)
Serial opt	-	-	-
2 Procs	-	-	_

Direct translation Python \rightarrow Julia gives 8× speed up. Awesome!

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	C++	Python	Julia
Baseline	2.8 s (1×)	117.0 s (41×)	14.4 s (5×)
Serial opt	-	-	9.4 s (3×)
2 Procs	-	-	_

Direct translation Python \rightarrow Julia gives 8× speed up. Awesome!

A little serial optimization gets us close the C++ reference

	C++	Python	Julia
Baseline	2.8 s (1×)	117.0 s (41×)	14.4 s (5×)
Serial opt	-	-	9.4 s (3×)
2 Procs	-	-	46.1 s (16×)

Direct translation Python \rightarrow Julia gives 8× speed up. Awesome!

A little serial optimization gets us close the C++ reference

Sadly my parallel efforts didn't turn out